# PRINCIPLES OF MATHEMATICAL MODELLING

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Lectures:

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Tuesday: 9–11 (A201)
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Exercises:

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Tuesday: 11–13 (A201)
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Consultations:

Monday: 14–16

## Contents.

#### **Mathematical models**

- Exponential model
- Logistic model
- Tunor growth models (von Bertalanffy, Gompertz,...)
- Growth with limitation
- Model of bioreactor ('chemostat' model)
- Lotka-Volterra model (predator-prey model)
- Compartmental models
- Epidemiological models (SIS, SIR, ...)

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## **Mathematical contents**

- Prerequisite: derivation, integration
- Differential equations
- Solving differential equations
- Numerical solutions of differential equations
- Least squares method (determination of model parameters)
- Equilibria
- Stability of equilibria
- Partial derivative
- Eigenvalues of linear operator

#### Programming: 'Mathematica'

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## Grading

- 1. exam 50%
- 2. exam 50%
- Homework
- Repeated exam (maximal grade is 2)

## **GROWTH MODELS**

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# 1.1. EXPONENTIAL MODEL 1.1.1. Exponential function

Exponential function:

$$exp: \mathbb{R} \to \mathbb{R},$$

(General) exponential function:

$$\exp_a : \mathbb{R} \to \mathbb{R},$$

*a* - base of exponential function, a > 0 and  $a \neq 1$ .

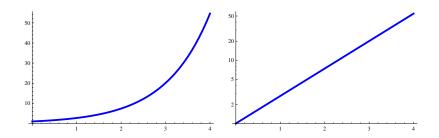
Notation:

$$\exp_a(x) = a^x$$

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## Graph of exponential function.



## Definition of exponential function.

$$\exp(x) = e^x$$

NO!

Power series:

$$\exp x = \sum_{k=0}^{\infty} \frac{x^k}{k!}$$

or differential equation

$$f'(x) = f(x), \quad f(0) = 1,$$

or

$$\exp x = \lim_{n \to \infty} \left( 1 + \frac{x}{n} \right)^n$$

Property:

## Motivation for exponential function.

For  $n \in \mathbb{N}$ :

$$a^n = a \cdot a \cdot \ldots \cdot a$$

To extend property 
$$f(x + y) = f(x)f(y)$$
 on  $\mathbb{N}_0$ :  
 $a^n = a^{n+0} = a^n a^0 \Rightarrow a^0 = 1$ .

The same property we extend on  $\mathbb{Z}$ :

$$1 = a^0 = a^{n-n} = a^n a^{-n} \quad \Rightarrow \quad a^{-n} = \frac{1}{a^n},$$

and on  $\mathbb{Q}$ :

$$a = a^{1} = a^{n\frac{1}{n}} = a^{\frac{1}{n} + \frac{1}{n} + \dots + \frac{1}{n}} = \left(a^{\frac{1}{n}}\right)^{n} \quad \Rightarrow \quad a^{\frac{1}{n}} = \sqrt[n]{a}.$$

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Property

$$f(x+y)=f(x)f(y)$$

uniquely define exponential function on  $\mathbb{Q}$ . Can we this property extend on  $\mathbb{R}$ ?

#### Theorem (1)

For given  $a \in \mathbb{R}$ , a > 0, there exists unique continuous function  $f : \mathbb{R} \to \mathbb{R}$  satisfying f(x + y) = f(x)f(y) for all  $x, y \in \mathbb{R}$  and f(1) = a.

#### Theorem (2)

For given  $a \in \mathbb{R}$ , a > 0, there exists unique monotone function  $f : \mathbb{R} \to \mathbb{R}$  satisfying f(x + y) = f(x)f(y) for all  $x, y \in \mathbb{R}$  and f(1) = a.

#### Definition

Function from Theorem 1 (2) for a = f(1) > 0 and  $a \neq 1$  we call exponential function. Number *a* we call a base of exponential function.

## **1.Homework**

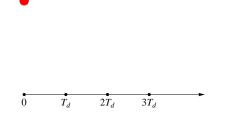
Prove Theorems 1. and 2.

For those who want more: Show that a continuity is necessary condition for uniqueness, i.e., show that there exists a function satisfying f(x + y) = f(x)f(y) for all  $x, y \in \mathbb{R}$  and it is not continuosus.

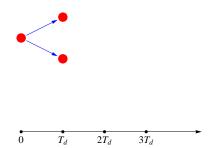
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## 1.1.2. Discrete exponential model

We observe cell where each cell divides after time  $T_d$  (exactly). We start with one cell

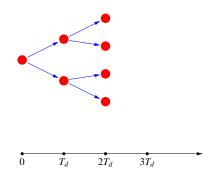


After time  $T_d$  it will divide and we will have two cells

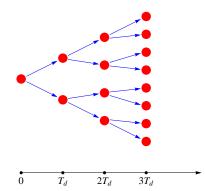


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After time  $2T_d$  each cell will divide and we will have 4 cells

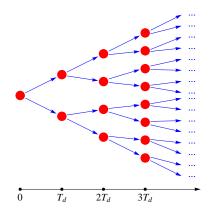


After time  $3T_d$  we will have 8 cells



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etc.



Number of cells at time  $t_i = i \cdot T_d$  is: 1, 2, 4, 8, 16, ....

(Geometrical growth.)

N - population size,

$$N_i := N(t_i) = 2^i.$$

Exponential function. Exponential growth.

Different notation:

 $N_i$  - population size at time  $t_i$ After period of  $T_d$  population will double:

$$N_{i+1} = 2N_i$$
.

Diference equation.

Solution of diference equation:

$$N_i = 2N_{i-1} = 2^2N_{i-2} = \ldots = N_02^i.$$

Solution is not unique.

With given initial value  $N_0$  at time  $t_0$  the solution will be unique.

#### **Thomas Robert Malthus** (1766-1834)

- English economist and demographist
- He was the first who used exponential function for the description of a population growth.
- Malthusian growth
- "An Essay on the Principle of Population" (1798)



## 1.1.3. Derivation of exponential model

- Assumption that all cells divide at the same time is unrealistic.
- More realistic: cells are mixed and divide at different moments.
- Time between two divisions  $(T_d)$  is not the same for all cells.
- **Doubling time** is the average time it takes for a population to double in number.

#### Assumption

All cells divide exactly after the same time  $T_d$ .

- Doubling time (average time for division) should not be constant with the respect on time.

- For example, it depends on availability of substrate (food).

Define gain function

$$G(N(t),h) = N(t+h) - N(t).$$

G does not depend on t explicitly.

If we start to observe population gain of size N at different time points t, after the time interval h the gain is the same.

- We consider a system that is not influenced by external factors.

Simpler notation: N = N(t).

First consider dependence of gain function G on population size. For fixed *h* define function

$$g_h(N)=G(N,h).$$

Divide population on two subpopulations of sizes M i N. Each of them continues to grow under the same conditions:

$$G(N(t), h) = N(t + h) - N(t)$$
 i  $G(M(t), h) = M(t + h) - M(t)$ .

On the other side, two populations can be considered as one population:

$$G(N(t) + M(t), h) = N(t + h) + M(t + h) - N(t) - M(t)) = = G(N(t), h) + G(M(t), h),$$

i.e.,

$$g_h(N+M)=g_h(N)+g_h(M).$$

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Cauchy's functional equation

$$f(x+y)=f(x)+f(y).$$

 $\Rightarrow$  *f* is linear function on  $\mathbb{Q}$ : *f*(*x*) = *ax*.

What about  $\mathbb{R}$ ?

If *f* is monotonic (or continuous)  $\Rightarrow$  *f* is linear function on  $\mathbb{R}$ .

Note: function G is monotonic (increasing) with the respect to N and h.

Larger population  $\rightarrow$  larger gain

 $\Rightarrow$  *G* is monotonic by variable *N* and *g*<sub>h</sub> is monotonic (increasing) function.

 $g_h$  is linear function  $\rightarrow$  *G* is linear in variable *N*:

$$g_h(N) = aN = a(h)N.$$

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Gain function:

 $\Rightarrow$ 

$$N(t+h)-N(t)=G(N(t),h)=a(h)N(t).$$

$$N(t + h) = a(h)N(t) + N(t) = (1 + a(h))N(t) = b(h)N(t).$$

Population increase after time  $h_1 + h_2$ :

$$N(t + h_1 + h_2) = b(h_1 + h_2)N(t).$$

On the other side,

$$N(t + h_1 + h_2) = b(h_2)N(t + h_1) = b(h_1)b(h_2)N(t).$$

Equalize right sides:

$$b(h_1 + h_2) = b(h_1)b(h_2).$$

*G* is monotonic function in variable  $h \Rightarrow b$  is monotonic function.

b is exponential function:

$$b(h) = e^{\alpha h}$$

and

$$N(t+h)=\mathrm{e}^{\alpha h}\,N(t).$$

Especially, for t = 0 and h = t, we obtain expression for *N*:

 $N(t)=N(0)\,\mathrm{e}^{\alpha t}\,.$ 

- exponential model
- model function
- N(0) and  $\alpha$  are model parameters

Instead of: cells divide after time  $T_d$ , exactly

We may consider: all cells have the same probability of splitting and this probability is time independent.  $\Rightarrow$  In population of relatively large number of cells, average doubling time will be constant.

Derivation of exponential model from this assumption is the same as previous derivation. (Note: if population is divided in two parts, for both parts, assumption about the same probability of splitting holds.)

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## **Cauchy's functional equation**

$$f(x + y) = f(x) + f(y), \quad \forall x \in \mathbb{R}.$$

and f is monotonic (continuous). Then f is a linear function.

**Proof.** First, we show that f(x + y) = f(x) + f(y) is a linear function on  $\mathbb{Q}$ .

For  $m \in \mathbb{N}$ :

$$f(mx)=mf(x).$$

Now, for  $n \in \mathbb{N}$ :

$$f(x) = f\left(n\frac{1}{n}x\right) = nf\left(\frac{1}{n}x\right).$$
  

$$\Rightarrow \quad f\left(\frac{1}{n}x\right) = \frac{1}{n}f(x).$$

Hence, for all  $r \in \mathbb{Q}$ ,  $r = \frac{m}{n}$ , we have f(rx) = rf(x).

*f* is linear function, but only on  $\mathbb{Q}$ .

Let  $a \in \mathbb{R}$  is given.

 $\mathbb{Q}$  is dense in the set  $\mathbb{R} \Rightarrow$ for arbitrary  $\delta > 0$  there exists  $r_1, r_2 \in \mathbb{Q}$  such that  $r_1 < a < r_2$ ,  $|a - r_1| < \delta$  and  $|a - r_2| < \delta$ .

f is monotonic (increasing)  $\Rightarrow$ 

$$f(ay) - af(y) \le f(r_2y) - af(y) = r_2f(y) - af(y) = (r_2 - a)f(y).$$

Similarly,

$$f(ay) - af(y) \ge f(r_1y) - af(y) = r_1f(y) - af(y) = (r_1 - a)f(y).$$

Therefore,

$$\begin{aligned} |f(ay) - af(y)| &\leq \max\{|r_1 - a|, |r_2 - a|\}|f(y)| \leq \\ &\leq \delta|f(y)| \end{aligned}$$

for all  $\delta > 0$ .

$$\Rightarrow f(ay) - af(y) = 0,$$

i.e.

$$\Rightarrow f(ay) = af(y)$$

for arbitrary  $a \in \mathbb{R}$ .

$$\Rightarrow f(x) = f(x \cdot 1) = x f(1)$$

f is a linear function.

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## 1.1.4. Taylor expansion of the gain function

Taylorov mean value theorem:

$$f(x+h) = f(x) + f'(x)h + \frac{1}{2}f''(x)h^2 + \ldots + \frac{1}{k!}f^{(k)}(x)h^k + \frac{1}{(k+1)!}f^{(k+1)}(\zeta)h^{k+1}.$$

For k = 2:

$$f(x+h) = f(x) + f'(x)h + \frac{1}{2}f''(x)h^2 + \mathcal{O}(h^3).$$

Function *f* is approximates by polinomial:

$$f(x+h) = a + bh + ch^2 + \mathcal{O}(h^3) = P_2(h) + \mathcal{O}(h^3).$$

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Gain function

$$G(N(t),h) = N(t+h) - N(t)$$

depends on two variables: N i h.

$$G(N,h)=P_2(N,h)+\mathcal{O}.$$

(remainder  $\mathcal{O}$  consists of third powers and higher)

'Neglect' O:

$$G(N,h) = a + bh + cN + dh^2 + ehN + fN^2.$$

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1. For N = 0 (no population) a gain is 0 G(0, h) = 0,  $\forall h \Rightarrow$ 

$$0 = G(0, h) = a + bh + dh^2, \quad \forall h$$

 $\Rightarrow a = b = d = 0$ 

Now,

$$G(N,h)=cN+ehN+fN^2.$$

2. For h = 0 (no time laps) a gain is  $0 \quad G(N, 0) = 0, \forall N \Rightarrow$ 

$$0 = G(N, 0) = cN + fN^2, \quad \forall N$$

 $\Rightarrow c = f = 0$ 

Now,

$$G(N,h) = ehN =: \alpha hN.$$

$$G(N, h) = \alpha h N.$$
  
 $N(t + h) - N(t) = \alpha h N(t).$ 

$$\frac{N(t+h) - N(t)}{h} = \alpha N(t). \quad /\lim_{h \to 0}$$

$$N'(t) = \alpha N(t).$$

**Differential equation** 

Function  $N_0 e^{\alpha t}$  is a solution.

Is it unique?

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## 1.1.5. Application of exponential model

Implicit assumption: unlimited access to food

Applicable in initial phase of growth.

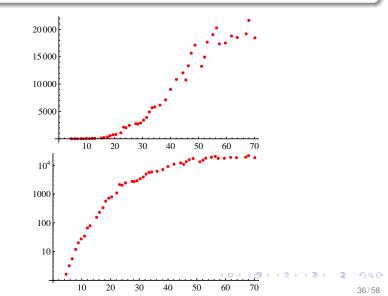
Exponential function is unbounded!

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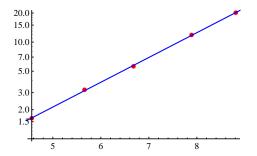
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#### Example

#### Growth of tunor cells (volume is shown).



Choose first 5 data points:



Data coincide with an exponential curve!

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# **Doubling time**

Funkcija:

$$N(t)=N_0\,\mathrm{e}^{\alpha t}$$

 $T_d$  - doubling time

$$N(t + T_d) = 2N(t)$$

$$N_0 e^{\alpha(t+T_d)} = 2N_0 e^{\alpha t}$$

$$e^{\alpha t} e^{\alpha T_d} = 2 e^{\alpha t}$$

$$e^{\alpha T_d} = 2$$

$$\alpha = \frac{\ln 2}{T_d}$$

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# 1.2. Differential equations1.2.1. Definition and example

Exponential model:

$$y(t) = N_0 e^{\alpha t}$$

or

$$y'(t) = \alpha y(t), \quad N(0) = N_0, \quad \forall t$$

Model is described by differential equation!

Interpretation of derivative:

- tangent (Leibniz)
- velocity (Newton)

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#### Definition

Let  $f : [a, b] \times \mathbb{R} \to \mathbb{R}$  be a given function. Then an equation of the form

 $y'(t) = f(t, y(t)) \quad \forall t \in [a, b]$ 

is named ordinary differential equation (ODE). Function  $y : [a, b] \to \mathbb{R}$  satisfying this equation is named a solution of (ordinary) differential equation.

- We will use shorter form: differential equation
- It is common to omit argument t in the notation of a function y
- $\forall t \in [a, b]$  is also omitted (maximal domain is assumed):

$$y'=f(t,y)$$

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## Examples.

## Example 1.

$$y'(t) = \alpha y(t)$$
  
 $\Rightarrow f(t, y(t)) = \alpha y(t) \Rightarrow f(t, y) = \alpha y$ 

Shorter:

$$\mathbf{y}' = \alpha \mathbf{y}$$

**Example 2.** Check if  $y(x) = e^x$  is a solution of the equation

$$y' = y?$$
  
 $y(x) = e^x \Rightarrow y'(x) = e^x$   
 $y' = y \Leftrightarrow e^x = e^x$ 

It holds for  $\forall x \in \mathbb{R}$ .

Function  $y(x) = e^x$  is a solution of the given differential equation.

Function  $y(x) = 2e^x$  is also a solution of the differential equation y' = y:

$$y(x) = 2e^x \Rightarrow y'(x) = 2e^x$$
  
 $y' = y \Leftrightarrow 2e^x = 2e^x$ .

Solution is not unique!

Moreover,  $y(x) = c e^x$  is also solution for all  $c \in \mathbb{R}$ !

$$y(x) = c e^x \Rightarrow y'(x) = c e^x$$
  
 $y' = y \Leftrightarrow c e^x = c e^x$ .

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**Primjer 3.** Check if function  $y(x) = e^{2x}$  is a solution of the equation

$$y' = y$$
?

$$y(x) = e^{2x} \Rightarrow y'(x) = 2e^{2x}$$
  
 $y' = y \Leftrightarrow e^{2x} = 2e^{2x}$ 

Does not hold  $\forall x \in \mathbb{R}$ ).

Function  $y(x) = e^{2x}$  is not solution of the given differential equation.

## Differential equation y' = f(t, y)

- may have no solution
- if there is a solution, it should not have to be unique
- Additional condition (equation) may be implied of the form

-  $y(a) = y_0$  - initial condition  $\rightarrow$  initial value (Cauchy) problem for ODE.

- condition including behaviour in end points of some interval, for example  $y(a) + \alpha y(b) = \beta \rightarrow$  boundary condition  $\rightarrow$  boundary problem for ODE.

We may define differential equations of higher order (using higher order derivatives):

$$\mathbf{y}^{(k)} = f\left(t, \mathbf{y}, \mathbf{y}', \dots, \mathbf{y}^{(k-1)}\right)$$

**Example 4.** Find solution of initial value problem for ODE

$$y'=y, \quad y(1)=1.$$

One solution of the equation is of the form

$$y(x) = c e^x$$
.

Constant c is is determined from the initial condition

$$y(1) = 1.$$
  

$$\Rightarrow \quad 1 = y(1) = c e^{1} = c e^{1}$$
  

$$\Rightarrow \quad c = e^{-1}$$
  

$$\Rightarrow \quad y(x) = e^{-1} e^{x} = e^{x-1}$$

# 1.2.2. Solving differential equations

Consider differential equation

$$y'=f(t,y).$$

When function f may be written as a product

•

$$f(t,y)=g(t)h(y)$$

equation is

$$y' = g(t)h(y)$$

or

$$\frac{y'}{h(y)}=g(t).$$

Functions are equal  $\Rightarrow$  indefinite integrals (set of all antiderivatives) are equal:

$$\int \frac{y'}{h(y)} dt = \int g(t) dt.$$

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$$\int \frac{y'}{h(y)} dt = \int g(t) dt.$$

integration by substitution: y'dt = dy

$$\int \frac{dy}{h(y)} = \int g(t)dt.$$

Let H and G are antiderivatives:

$$H'(y) = \frac{1}{h(y)}$$
 i  $G'(t) = g(t)$ .

Now,

$$H(y)=G(t)+C$$

C - generic constant.

If H is an bijection, then

$$y = H^{-1} (G(t) + C)$$
.

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Solving differential equation  $\Leftrightarrow$  calculating indefinite integral

- Method of separation of variables

Problem

Check that

$$y(t) = H^{-1}(G(t) + C).$$

is a solution of differential equation

$$y'=f(x,y).$$

## Rješenje.

Derivative of inverse function:

$$(f^{-1}(y))' = \frac{1}{f'(f^{-1}(y))}$$

The composite function rule:

$$(f(g(x)))' = f'(g(x))g'(x).$$

$$y'(t) = \left(H^{-1}(G(t) + C)\right)' = \frac{G'(t)}{H'(H^{-1}(G(t) + C))} =$$
$$= \frac{G'(t)}{H'(y(t))} = \frac{g(t)}{\frac{1}{h(y(t))}} = g(t)h(y(t)) = f(t, y(t)).$$

**Example 6.** Solve differential equation

$$\mathbf{y}' = \alpha \mathbf{y}.$$

#### Solution.

Separation of variables:

$$y' = \alpha y = g(t)h(y) \implies g(t) = \alpha, \quad h(y) = y$$
$$\frac{y'}{y} = \alpha \implies \int \frac{y'}{y} dt = \int \alpha dt \implies \int \frac{dy}{y} = \alpha t + C$$
$$\implies \ln |y| = \alpha t + C \implies |y| = e^{\alpha t + C} = C_1 e^{\alpha t}, \quad C_1 > 0$$
$$\implies y = C_2 e^{\alpha t}, \quad C_2 \in \mathbb{R}$$

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In growth models differential equation does not depend explicitly on time *t*.

The very same argument as for gain function holds:

- If we start experiment in different times starting wit populations of the same size, growth should be the same.

Growth models:

$$y'=f(y)$$

- Autonomous differential equation

# Numerical solution of differential equatioi

- Even if differential equation has a solution, it often can not be expressed explicitly.
- Method of separation of variables is just one among many methods.
- It is often the case that antiderivative can not be expressed using 'simple' functions.
- Even if we determine inverse function in the method of separation of variables, it does not mean that we will find its inverse.

New approach: calculate numerical (approximate) solution of ODE instead of exact solution.

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Consider initial value problem

$$y' = f(t, y), \quad y(0) = y_0.$$

Main idea - Taylor polynomial:

$$y(t+h) = y(t) + y'(t)h + \frac{y''(\zeta)}{2}h^2.$$

Neglect quadratic term:

$$y(t+h) \approx y(t) + y'(t)h.$$

If y is a solution of differential equation y' = f(t, y), then

$$y(t+h) \approx y(t) + h \cdot f(t, y(t)).$$

Initial value problem:

$$y' = f(t, y), \quad y(0) = y_0.$$

We are looking for the solution on the interval [0, a].

*n* - given

Divide interval [0, a] on n equal parts:

$$h = \frac{a}{n}, \quad t_i = i \cdot h, \ i = 0, 1, 2, \dots, n.$$

 $t_0$  and  $y_0$  are known (initial conditions). Calculate an approximation to the solution at  $x_1$ :

$$y_1=y_0+h\cdot f(t_0,y_0)$$

Next step:

$$y_2 = y_1 + h \cdot f(t_1, y_1)$$

etc.

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Method:

$$y_{i+1} = y_i + h \cdot f(t_i, y_i), \quad i = 0, 1, \dots$$

- Euler's method

#### Example

Using Euler's method approximate solution of the initial value problem

$$y'=y, \quad y(0)=1,$$

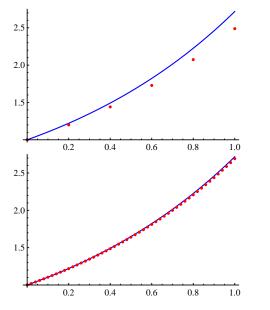
at point x = 1 using subdivision on 5 subintervals.

#### Solution.

Interval [0, 1].

 $n = 5 \Rightarrow h = 0.2$ 

i	ti	Уi	$f(t_i, y_i)$	<b>y</b> <sub>i+1</sub>
0	0.0	1.000	1.000	1.200
1	0.2	1.200	1.200	1.440
2	0.4	1.440	1.440	1.728
3	0.6	1.728	1.728	2.074
4	0.8	2.074	2.074	2.488
5	1.0	2.488		



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- y(t + h) is approximated by a linear term from Taylor expansion
- The simplest of all methods
- Better approximation  $\rightarrow$  better method
- Well known:
  - Runge-Kutta methods
  - linear multistep methods