

8.3.2. Rječun derivacije oblika za stacionarni Navier-Stokes, Podsjetnik slaba formulacija za N-S glasi

$$(5) \left\{ \begin{array}{l} \text{Pronađi } (u, p) \in u_0 + V \text{ takva da} \\ \forall (v, q) \in V, \quad \int_{\Omega} \sigma(u, p) : \varepsilon(v) + Du \cdot v - q \operatorname{div} v = \int_{\Gamma_{\text{out}}} h \cdot v \\ \text{gdje su } V = \left\{ (u, p) \in H^1(\Omega; \mathbb{R}^3) \times L^2(\Omega) : u|_{\Gamma_{\text{in}} \cup \Gamma} = 0 \right\} \\ u_0 + V = \left\{ (u, p) \in H^1(\Omega; \mathbb{R}^3) \times L^2(\Omega) : u|_{\Gamma_{\text{in}}} = u_0, u|_{\Gamma} = 0 \right\}. \end{array} \right.$$

Zadica na domeni $\phi_{\theta}(\Omega)$ (koja je vraćena na Ω) uz notaciju

$$a(\theta; u, p; v, q) = \int_{\Omega} 2\mu S(D(u) D\phi_{\theta}^{-1}) : S(D(v) D\phi_{\theta}^{-1}) J_{\theta} \\ - \int_{\Omega} p \operatorname{tr}(D(v) D\phi_{\theta}^{-1}) J_{\theta} \\ + \int_{\Omega} D(u) D\phi_{\theta}^{-1} u \cdot v J_{\theta} \\ - \int_{\Omega} q \operatorname{tr}(Du D\phi_{\theta}^{-1}) J_{\theta}$$

$$b(\theta; v, q) = \int_{\Gamma_{\text{out}}} h_0 \cdot v$$

glasi

$$\left. \begin{array}{l} \text{Pronađi } (u, p) \in u_0 + V \text{ t.d.} \\ \forall (v, q) \in V \quad a(\theta; u, p; v, q) = b(\theta; v, q). \end{array} \right\}$$

Dano rješenje je očito $(u_{\theta} \circ \phi_{\theta}, p_{\theta} \circ \phi_{\theta})$ gdje su (u_{θ}, p_{θ}) rješenja od (5) na domeni $\phi_{\theta}(\Omega)$.

Definiraj

$$F(\theta; u, p; v, q) = a(\theta; u, p; v, q) - b(\theta; v, q)$$

možemo pokazati da je

$$F_0: K(\vartheta, \vartheta) \subseteq W^{1, \infty}(\mathbb{R}^3; \mathbb{R}^3) \times H_0^1(\Omega; \mathbb{R}^3) \times L_0^2(\Omega) \\ \rightarrow H^{-1}(\Omega; \mathbb{R}^3) \times L_0^2(\Omega)$$

gdje

$$F_0(\theta; u, p; v, q) = F(\theta; u \# \tilde{u}_0, p; v, q)$$

\tilde{u}_0 je Poissonova funkcija na cilindru.

osigurava da radimo u prostoru gdje su nam prijeneti teoremi u implicitnoj funkciji. Za detaljnije pogledajte referencu od zadnjeg puta:

J. A. Bello, E. Fernández-Cara, J. Lemaire, J. Simón:

"The differentiability of the drag with respect to the variations of a Lipschitz domain in a Navier-Stokes Flow"

Tine je $(u_\theta \circ \phi_\theta - \tilde{u}_\theta, p_\theta \circ \phi_\theta)$ Fréchet diferencijabilno i opravdao s tim sljedeći formula račun.

$$(MD) \begin{cases} (u_\theta, p_\theta) \in V \\ D_{(u,p)} F(\theta, u, p; v, q)[u_\theta, p_\theta] = -D_\theta F(\theta, u, p; v, q)[\theta], \forall (v, q) \in V \end{cases}$$

↑
uočite F umjesto F_0 ,
rigorozni postupak predavanja.

$$D_{(u,p)} F(\theta, u, p; v, q)[\tilde{u}, \tilde{p}] = \int_{\Omega} \sigma(\tilde{u}, \tilde{p}) : \varepsilon(v) + D\tilde{u} u \cdot v + D u \tilde{u} \cdot v \\ - \int_{\Omega} q \operatorname{div} \tilde{u}$$

$$D_\theta F(\theta, u, p; v, q)[\theta] = \int_{\Omega} -2\mu S(D_u D\theta) : S(Dv) - 2\mu S(Du) : S(Dv D\theta) \\ + \int_{\Omega} \operatorname{div} \theta \cdot 2\mu \varepsilon(u) : \varepsilon(v) + p \operatorname{tr}(Dv D\theta) - p \operatorname{div} v \operatorname{div} \theta$$

$$+ \int_{\Omega} D u u \cdot v \operatorname{div} \theta - D u D \theta u \cdot v$$

$$+ \int_{\Omega} g \operatorname{tr}(D u D \theta) - g \operatorname{div} u \operatorname{div} \theta$$

Istaknimo da eventualni doprinos od desne strane b zbog $\theta|_{\Gamma_{\text{out}}} = 0$

nestaje pa (MD) postaje

$$(\dot{u}_\theta, \dot{p}_\theta) \in V$$

$$\int_{\Omega} \sigma(\dot{u}_\theta, \dot{p}_\theta) : \varepsilon(v) + D \dot{u}_\theta u \cdot v + D u \dot{u}_\theta \cdot v - g \operatorname{div} \dot{u}_\theta =$$

$$\int_{\Omega} \underbrace{2\mu S(D u D \theta) : S(D v)} + \underbrace{2\mu S(D u) : S(D v D \theta)} + \sigma(u, p) : S(D v D \theta)$$

$$+ \int_{\Omega} \underbrace{p \operatorname{div} v \operatorname{div} \theta - 2\mu \varepsilon(u) : \varepsilon(v) \operatorname{div} \theta} - \underbrace{p \operatorname{tr}(D v D \theta)} - \sigma(u, p) : \varepsilon(v) \operatorname{div} \theta$$

$$+ \int_{\Omega} D u D \theta u \cdot v - D u u \cdot v \operatorname{div} \theta$$

$$+ \int_{\Omega} g \operatorname{div} u \operatorname{div} \theta - \underbrace{g \operatorname{tr}(D u D \theta)} + \sigma(v, g) : S(D u D \theta)$$

Što možemo zapisati kao

$$\left. \begin{aligned} & \int_{\Omega} \sigma(\dot{u}_\theta, \dot{p}_\theta) : \varepsilon(v) + D \dot{u}_\theta u \cdot v + D u \dot{u}_\theta \cdot v - g \operatorname{div} \dot{u}_\theta = \\ & \int_{\Omega} \sigma(u, p) : (D v D \theta) + \sigma(v, g) : (D u D \theta) + D u D \theta u \cdot v \\ & + \int_{\Omega} (g \operatorname{div} u \cdot v - D u u \cdot v - \sigma(u, p) : \varepsilon(v)) \operatorname{div} \theta \end{aligned} \right\} \text{(SMD)}$$

Preostaje izračunati derivacijski oblik

$$\begin{aligned}
 J(\phi_\theta(\Omega)) &= \int_{\phi_\theta(\Omega)} 2\mu \varepsilon(u_\theta) : \varepsilon(u_\theta) \\
 &= \int_{\Omega} 2\mu \varepsilon(u_\theta) \circ \phi_\theta : \varepsilon(u_\theta) \circ \phi_\theta J_\theta \\
 &= \int_{\Omega} 2\mu S(D(u \circ \phi_\theta) D\phi_\theta^{-1}) : S(D(u \circ \phi_\theta) D\phi_\theta^{-1}) J_\theta \\
 &= \int_{\Omega} 2\mu \varepsilon(u) : \varepsilon(u) - \int_{\Omega} 4\mu S(Du D\theta) : \varepsilon(u) \\
 &\quad + \int_{\Omega} 2\mu \varepsilon(u) : \varepsilon(u) \operatorname{div} \theta + \int_{\Omega} 4\mu \varepsilon(\dot{u}_\theta) : \varepsilon(u) + \sigma(\theta)
 \end{aligned}$$

$$\begin{aligned}
 J'(\Omega; \theta) &= - \int_{\Omega} 4\mu S(Du D\theta) : \varepsilon(u) + \int_{\Omega} 2\mu \varepsilon(u) : \varepsilon(u) \operatorname{div} \theta \\
 &\quad + \int_{\Omega} 4\mu \varepsilon(u) : \varepsilon(\dot{u}_\theta)
 \end{aligned}$$

Prisjetimo se ad'ingine slabije formulacije:

$$\text{(ASF)} \left\{ \begin{array}{l} \forall (\varphi, \psi) \in V \\ \int_{\Omega} \sigma(\nu, \varrho) : \varepsilon(\varphi) + D\varphi \cdot u \cdot \nu + Du \cdot \varphi \cdot \nu - \varphi \operatorname{div} \nu = - \int_{\Omega} 4\mu \varepsilon(u) : \varepsilon(\varphi) \end{array} \right.$$

Stavimo $(\varphi, \psi) = (\dot{u}_\theta, \dot{p}_\theta)$ i ubacimo u $J'(\Omega; \theta)$

$$\begin{aligned}
J'(\Omega; \Theta) &= \int_{\Omega} 2\mu \varepsilon(u) : \varepsilon(u) \operatorname{div} \Theta - 4\mu \varepsilon(u) : S(Du D\Theta) \\
&\quad - \int_{\Omega} 2\mu \varepsilon(v) : \varepsilon(\dot{u}_{\Theta}) = g \operatorname{div}(\dot{u}_{\Theta}) + D\dot{u}_{\Theta} u \cdot v + Du \dot{u}_{\Theta} \cdot v - \dot{p}_{\Theta} \operatorname{div} v \\
&= \int_{\Omega} 2\mu \varepsilon(u) : \varepsilon(u) \operatorname{div} \Theta - 4\mu \varepsilon(u) : S(Du D\Theta) \\
&\quad - \int_{\Omega} \sigma(\dot{u}_{\Theta}, \dot{p}_{\Theta}) : \varepsilon(v) + D\dot{u}_{\Theta} u \cdot v + Du \dot{u}_{\Theta} \cdot v - g \operatorname{div}(\dot{u}_{\Theta})
\end{aligned}$$

$$\begin{aligned}
&\stackrel{\text{(SMD)}}{=} \int_{\Omega} 2\mu \varepsilon(u) : \varepsilon(u) \operatorname{div} \Theta - 4\mu \varepsilon(u) : S(Du D\Theta) \\
&\quad - \int_{\Omega} \sigma(u, p) : (Dv D\Theta) + \sigma(v, q) : (Du D\Theta) + Du D\Theta \cdot v \\
&\quad - \int_{\Omega} (g \operatorname{div} u - Du u \cdot v - \sigma(u, p) : \varepsilon(v)) \operatorname{div} \Theta \\
&= \int_{\Omega} (\sigma(u, q) : \varepsilon(u) + \sigma(u, p) : \varepsilon(v) + Du u \cdot v) \operatorname{div} \Theta \\
&\quad - \int_{\Omega} 4\mu \varepsilon(u) : S(Du D\Theta) - \sigma(u, p) : (Dv D\Theta) - \sigma(v, q) : (Du D\Theta) + Du D\Theta \cdot v
\end{aligned}$$

▣

8.3.3. Newtonov metod za tretiranju nelinearnosti kod N-S

Ideja: Neka je $f: X \rightarrow X'$, X Hilbertov prostor, Rješenje $f(x) = 0$ traži se kroz Newtonov metod (modificiran, klasično je za $f: X \rightarrow X$) tako da iteracije gradimo kroz

$$x_{k+1} = x_k + \delta x_k$$

$$\parallel x_{k+1} = x_k - (f'(x_k))^{-1} f(x_k) \text{ za } f: X \rightarrow X.$$

gdje je δx_k rješenje od

$$f'(x_k) \delta x_k = -f(x_k) \text{ (jednadba vriji u dualnom prostoru } X')$$

U našem slučaju $X = H^1(\Omega; \mathbb{R}^d) \times L^2(\Omega)$, $X' = (H^1(\Omega; \mathbb{R}^d))' \times L^2(\Omega)$,

$$f \equiv a(0; u, p; \nu, g): X \rightarrow X', \text{ tj.}$$

$$a(0; u, p; \nu, g) = \int_{\Omega} \sigma(u, p): \varepsilon(\nu) + D u u \cdot \nu - g \operatorname{div} u$$

Loganin računom dolazimo da f' (u oznaci $D_{(u,p)} a(0; u, p; \nu, g)$)

$$D_{(u,p)} a(u, p; \nu, g) [\delta u, \delta p] = \int_{\Omega} \sigma(\delta u, \delta p): \varepsilon(\nu) + D \delta u u \cdot \nu + \int_{\Omega} D u \delta u \cdot \nu - g \operatorname{div}(\delta u)$$

Iterativna metoda glasi:

1) (u^0, p^0) je rješenje Stokesove zadatice:

$$\left\{ \begin{array}{ll} -\operatorname{div}(\sigma(u^0, p^0)) = 0 & \text{u } \Omega \\ \operatorname{div} u^0 = 0 & \text{u } \Omega \\ u^0 = u_0 & \text{na } \Gamma_{in} \\ u^0 = 0 & \text{na } \Gamma \\ \sigma(u^0, p^0) n = h_0 & \text{na } \Gamma_{out} \end{array} \right.$$

2) Ponavlja se za $k \in \mathbb{N}$ dok se ne postigne konvergencija

(u^{k+1}, p^{k+1}) dobivamo preko

$$(u^{k+1}, p^{k+1}) = (u^k, p^k) + (\delta u^k, \delta p^k)$$

gdje je $(\delta u^k, \delta p^k)$ nejednako linearni Navier-Stokes

$$-\operatorname{div}(\sigma(\delta u^k, \delta p^k)) + D\delta u^k u^k + Du^k \delta u^k = \operatorname{div}(\sigma(u^k, p^k)) - Du^k u^k$$

$$\operatorname{div}(\delta u^k) = 0 \quad \text{u } \Omega$$

$$\delta u^k = 0 \quad \text{na } \Gamma_{in} \cup \Gamma$$

$$\sigma(\delta u^k, \delta p^k) \cdot n = 0 \quad \text{na } \Gamma_{out}$$