

### 8.3. Optimizacija oblika za inkompresibilni Navier-Stokesov fluid u ograničenoj domeni

#### 8.3.1. Iskaz problema

Neka je  $D \subseteq \mathbb{R}^3$  cilindar oblika

$$D = \left\{ (x_1, x_2, x_3) : x_1^2 + x_2^2 \leq R_0^2, 0 \leq x_3 \leq L \right\}, \quad R_0, L > 0.$$

Područje fluida označavamo s  $\Omega$ , a rub  $\partial\Omega$ , te je  $\Omega \subset D$ .

Ulazni tok fluida definiran je na granici

$$\Gamma_{in} = \partial\Omega \cap \left\{ (x_1, x_2, x_3) \in D : x_3 = 0 \right\}$$

Izlazni tok fluida definiran je na granici

$$\Gamma_{out} = \partial\Omega \cap \left\{ (x_1, x_2, x_3) \in D : x_3 = L \right\}$$



Radi jednostavnosti pretpostavljamo da je  $\Gamma_{in} = \{(x_1, x_2, 0) : x_1^2 + x_2^2 \leq R^2\}$   
 $\Gamma_{out} = \{(x_1, x_2, L) : x_1^2 + x_2^2 \leq R^2\}$

Tine je  $\partial\Omega = \Gamma \cup \Gamma_{in} \cup \Gamma_{out}$  disjunktan unija, gdje je  $\Gamma$  nepoznat dio ruba koji želimo optimizirati.

Konkretno, N-S sustav PDI možemo zapisati kao

$$(NS) \left\{ \begin{array}{l} -\operatorname{div}(\sigma(u, p)) + (u \cdot \nabla)u = 0 / \nu \\ \operatorname{div} u = 0 / \rho \\ u = u_0 = (0, 0, c(x_1^2 + x_2^2 - R^2)) \quad \text{na } \Gamma_{in} \\ u = 0 \quad \text{na } \Gamma \\ \sigma(u, p)n = h_0 = (2\mu c x_1, 2\mu c x_2, -p_1) \quad \text{na } \Gamma_{out} \end{array} \right. \quad \begin{array}{l} \text{D}_u u \\ u \text{ u } \Omega \\ \nu |_{\Gamma_{in} \cap \Gamma} = 0 \\ \sigma(u, p) = -pI + 2\mu \varepsilon(u) \\ \varepsilon(u) = \frac{1}{2} (D_u + D_u^T) \end{array}$$

$\mu$  označava viskoznost,  $c > 0$ ,  $p_1 \in \mathbb{R}$ .

Interpretacija - ako je  $\Gamma$  cilindar tj.  $\Gamma = \{(x_1, x_2, x_3) : x_1^2 + x_2^2 = R^2\}$

dobivamo Poiseuilleov tok te je  $\epsilon = \frac{p_1 - p_0}{4\mu L}$ ,  $p_0$  tlak na  $\Gamma_{in}$   
 $p_1$  tlak na  $\Gamma_{out}$

Za traženi  $\Gamma$  znamo i eksplicitne rješenja

$$u(x_1, x_2, x_3) = (0, 0, c(x_1^2 + x_2^2 - R^2))$$

$$p(x_1, x_2, x_3) = 4\mu c(x_3 - L) + p_1.$$

Neka je  $V = \left\{ (u, p) \in H^1(\Omega; \mathbb{R}^2) \times L^2(\Omega) : u|_{\Gamma_{in} \cup \Gamma} = 0 \right\}$

$u_0 + V = \left\{ (u, p) \in H^1(\Omega; \mathbb{R}^2) \times L^2(\Omega) : u|_{\Gamma_{in}} = u_0, u|_{\Gamma} = 0 \right\}$

Slaba formulacija (NS) glasi:

Pronađi  $(u, p) \in u_0 + V$  t.d.

$$\forall (v, q) \in V, \left. \int_{\Omega} \sigma(u, p) : \epsilon(v) + Du \cdot v - q \operatorname{div} u = \int_{\Gamma_{out}} h_0 v \, dS \right\} (S)$$

Ako je  $\Omega$  regularna domena (različit od cilindra) rješenje postoji, recimo vidi 9. poglavlje od

G. P. Galdi: "An Introduction to the Mathematical Theory of the Navier-Stokes Equations"

ili

R. Temam: "Navier-Stokes Equations" 2. poglavlje.

**Teorem 8.3.1**

Neka  $u_0 \in H^{\frac{3}{2}}(E; \mathbb{R}^3)$ ;  $h \in H^{\frac{1}{2}}(S; \mathbb{R}^3)$ . Ako je  $\mu$  dovoljno veliko tada problem (NS) ima jedinstveno rješenje

$$(u, p) \in H^1(\Omega; \mathbb{R}^3) \times L^2(\Omega).$$

Ideja je minimizirati energiju fluida ili otpor fluida (eng. drag)

$$J(\Omega) = 2\mu \int_{\Omega} |\varepsilon(u)|^2 dx,$$

Zapišimo Lagrangeov funkcional na standardni način kao dosada

$$L(\Omega, u, p; v, q) = 2\mu \int_{\Omega} \varepsilon(u) : \varepsilon(u) dx + \int_{\Omega} \sigma(u, p) : \varepsilon(v) + Du \cdot v - q \operatorname{div} u - \int_{\Gamma_N} h_0 \cdot v dS$$

To nam daje ideju kako zapisati adjungiranu zadaću.

Uočimo da  $\frac{\partial L}{\partial(v, q)} = 0$  vraćajući na (5).

$$\frac{\partial L}{\partial(u, p)}(\Omega, u, p; v, q) [\varphi, \bar{\varphi}] = \int_{\Omega} 4\mu \varepsilon(u) : \varepsilon(\varphi)$$

$$+ \int_{\Omega} 2\mu \varepsilon(\varphi) : \varepsilon(v) - \varphi \operatorname{div} v + D\varphi \cdot v + Du \varphi \cdot v - q \operatorname{div} \varphi = 0$$

$$(Asf) \left\{ \begin{array}{l} \forall (\varphi, \bar{\varphi}) \in V \\ \int_{\Omega} \sigma(v, q) : \varepsilon(\varphi) + D\varphi \cdot v + Du \varphi \cdot v - \varphi \operatorname{div} v = - \int_{\Omega} 4\mu \varepsilon(u) : \varepsilon(\varphi) \end{array} \right.$$

$$\Rightarrow \int_{\Omega} \operatorname{div}(\sigma(v, q) \varphi) - \operatorname{div} \sigma(v, q) \cdot \varphi + u \cdot D\varphi^T v + Du^T v \cdot \varphi - \varphi \operatorname{div} v = - \int_{\Omega} 4\mu \varepsilon(u) : \varepsilon(\varphi)$$

$$u \cdot D\varphi^T v = u \cdot (\operatorname{grad}(v \cdot \varphi) - Dv^T \varphi) = -Dv u \cdot \varphi + u \cdot \operatorname{grad}(v \cdot \varphi)$$

$$= -\operatorname{Div} u \varphi + \operatorname{div}((v \cdot \varphi) u) - (v \cdot \varphi) \underbrace{\operatorname{div} u}_{=0}$$

$$\int_{\Omega} u \cdot D \varphi^T v = - \int_{\Omega} \operatorname{Div} u \cdot \varphi + \int_{\partial \Omega} (v \cdot \varphi) u \cdot n \quad \leftarrow \varphi|_{\Gamma_{\text{out}}} = 0$$

$$= - \int_{\Omega} \operatorname{Div} u \cdot \varphi + \int_{\Gamma_N} (u \cdot n) v \cdot \varphi$$

$$\Rightarrow \int_{\Omega} (-\operatorname{div} \sigma(v, g) - \operatorname{Div} u + D u^T v) \cdot \varphi + \int_{\Gamma_N} (\sigma(v, g) n + (u \cdot n) v) \cdot \varphi$$

$$- \varphi \operatorname{div} v = \int_{\Omega} 2\mu \Delta u - \int_{\Gamma_N} 4\mu \varepsilon(u) n \cdot \varphi, \quad \forall (\varphi, \psi) \in V$$

Dakle adjungirana zadatak glasi

$$\left\{ \begin{array}{ll} -\operatorname{div} \sigma(v, g) + D u^T v - \operatorname{Div} v = 2\mu \Delta u & u \text{ na } \Omega \\ \operatorname{div} v = 0 & u \text{ na } \Omega \\ v = 0 & u \text{ na } \Gamma_{\text{in}} \cup \Gamma \\ \sigma(v, g) n + (u \cdot n) v = 0 & u \text{ na } \Gamma_{\text{out}} \end{array} \right.$$

Zapišimo slabu formulaciju od  $S$  na perturbiranoj domeni

$$\phi_{\theta}(\Omega) = (Id + \theta)(\Omega), \quad V_{\theta} = \left\{ (u, p) \in H^1(\Omega; \mathbb{R}^3) \times L^2(\Omega) : u|_{\phi(\Gamma) \cup \Gamma_{\text{out}}} = 0 \right\}$$

Pronađi  $(u_{\theta}, p_{\theta}) \in u_{\theta} + V_{\theta}$

$$\int_{\phi_{\theta}(\Omega)} \sigma(u_{\theta}, p_{\theta}) : \varepsilon(v) + D u u \cdot v - g \operatorname{div} u_{\theta} = \int h \cdot v, \quad \forall (v, q) \in V_{\theta}$$

$$\phi_{\theta}(\Gamma_{\text{out}}) = \Gamma_{\text{out}}$$

Nap. Događor je  $\theta = 0$  na okolini od  $\Gamma_{\text{in}}$  i  $\Gamma_{\text{out}}$

kao i kod elastičnosti

Zapišimo sve u referentnoj domeni

Konitivno

$$e(u) \circ \phi_\theta = S(D(u \circ \phi_\theta) D\phi_\theta^{-1})$$

$$D u \circ \phi_\theta = D(u \circ \phi_\theta) D\phi_\theta^{-1}$$

$$\int_{\Omega} (2\mu \varepsilon(u_\theta) \circ \phi_\theta : \varepsilon(v) \circ \phi_\theta - \rho_\theta \circ \phi_\theta \operatorname{div}(v) \circ \phi_\theta) J_\theta + \int_{\Omega} (D u_\theta \circ \phi_\theta u_\theta \circ \phi_\theta \cdot v \circ \phi_\theta - g_\theta \circ \phi_\theta \operatorname{div}(u_\theta) \circ \phi_\theta) J_\theta = \int_{\Gamma_N} h \cdot v$$

$$\Rightarrow \int_{\Omega} 2\mu S(D(u_\theta \circ \phi_\theta) D\phi_\theta^{-1}) : S(D(v \circ \phi_\theta) D\phi_\theta^{-1}) J_\theta + \int_{\Omega} -\rho_\theta \circ \phi_\theta \operatorname{tr}(D(v \circ \phi_\theta) D\phi_\theta^{-1}) J_\theta + \int_{\Omega} D(u_\theta \circ \phi_\theta) D\phi_\theta^{-1} u_\theta \circ \phi_\theta \cdot v \circ \phi_\theta J_\theta - \int_{\Omega} g_\theta \circ \phi_\theta \operatorname{tr}(D(u_\theta \circ \phi_\theta) D\phi_\theta^{-1}) J_\theta = \int_{\Gamma_N} h \cdot v$$

Znači  $(u_\theta \circ \phi_\theta, \rho_\theta \circ \phi_\theta)$  zadovoljava gornju jednačinu.

Može se pokazati da je  $\theta \mapsto (u_\theta \circ \phi_\theta, \rho_\theta \circ \phi_\theta)$

Fréchet diferencijabilno u 0, ali dobaz preskačen.

Ideja je primjeniti istu proceduru kao i u

J. A. Bello, E. Fernández-Cara, J. Lemoine, J. Simon:

"The differentiability of the drag with respect to the variations of a Lipschitz domain in a Navier-Stokes Flow"

Konkretno, može se pokazati korištenjem teorema o implicitnoj funkciji.