

1

Approximation by P_1 finite elements
of second order linear elliptic equations
in divergence form
with right hand side in $L^2(\Omega)$

Juan Casado-Díaz (Sevilla)

Tomás Chacón Rebollo (Sevilla)

Vivette Girault (Paris VI)

Macarena Gomez Marinol (Sevilla)

François Murat (Paris VI)

The problem

Data: $\Omega \subset \mathbb{R}^N$ open, bounded
 $A \in L^\infty(\Omega)^{N \times N}$, $A(x) \geq \alpha I$, $\alpha > 0$
 $f \in L^1(\Omega)$

find u such that:
$$\begin{cases} -\operatorname{div} A \nabla u = f & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases}$$

Approximation by finite elements:

Find u_h such that: $u_h \in V_h$

$\forall v_h \in V_h$,
$$\int_{\Omega} A \nabla u_h \cdot \nabla v_h = \int_{\Omega} f v_h$$

V_h : P1 finite elements

Existence of u_h : OK Convergence $u_h \rightarrow u$: ???

Convergence of u_k ?

- in what space?
- to what?

When $f \in L^1(\Omega)$, what is the meaning of the solution to

$$\begin{cases} -\operatorname{div} A \operatorname{D} u = f & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases} ?$$

not a weak solution $u \in H^1_0(\Omega) \dots$

... but a renormalized solution (P.L. Lions - Muskat)

or an entropy solution (Benilan - Boccardo - Gallouët ... Vazquez)

or a solution by transposition (Stampacchia)

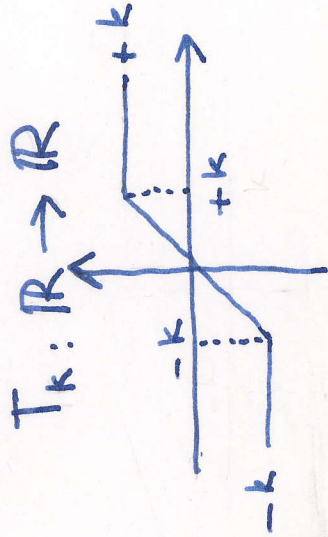
Definition of renormalized solution

When $f \in L^1(\Omega)$, u is a renormalized solution

of $\left. \begin{array}{l} -\operatorname{div} A Du = f \text{ in } \Omega \\ u = 0 \text{ on } \partial\Omega \end{array} \right\}$ if:

- $u \in L^1(\Omega)$
- $T_k(u) \in H^1_0(\Omega) \quad \forall k > 0$
- $\frac{1}{k} \int_{\Omega} |DT_k(u)|^2 \rightarrow 0 \quad \text{if } k \rightarrow +\infty$
- $\forall k > 0, \forall S \in C^1_c(\mathbb{R})$ with $\operatorname{supp} S \subset [-k, +k]$
- $\forall v \in H^1_0(\Omega) \cap L^\infty(\Omega)$

$$\left\{ \int_{\Omega} A DT_k(u) Dv S(u) + \int_{\Omega} A DT_k(u) DT_k(u) S'(u) v = \int_{\Omega} f S(u) v \right.$$



Theorem $\forall f \in L^1(\Omega)$

- there exists a renormalized solution u
- this solution is unique
- moreover $u \in W_0^{1,q}(\Omega) \quad \forall q < \frac{N}{N-1}$
- u depends continuously on f :

if $f^\varepsilon \rightarrow f$ in $L^1(\Omega)$ strongly, then

$$T_k(u^\varepsilon) \rightarrow T_k(u) \text{ in } H_0^1(\Omega) \text{ strongly } \forall k > 0$$

$$\alpha \|T_k(u^\varepsilon - u)\|_{H_0^1(\Omega)} \leq k \|f^\varepsilon - f\|_{L^1(\Omega)} \quad \forall \varepsilon > 0$$

$$\alpha \|u^\varepsilon - u\|_{W_0^{1,N}(\Omega)} \leq C(N, \alpha, \gamma) \|f^\varepsilon - f\|_{L^1(\Omega)} \quad \forall \varepsilon > 0$$

Our result: Theorem

- if $f \in L^1(\Omega)$
- if the transition is regular
- if V_h is the space of continuous P1 finite elements
- if the discrete maximum principle holds

then the unique solution of $u_h \in V_h$

$$\forall v_h \in V_h \quad \int_{\Omega} A D u_h D v_h = \int_{\Omega} f v_h$$

satisfies

$$u_h \rightarrow u \text{ in } W_0^{1,p}(\Omega) \text{ strong } \forall p < \frac{N}{N-1}$$
$$\Pi_h T_k(u_h) \rightarrow T_k(u) \text{ in } H^1_0(\Omega) \text{ strong } \forall k$$

where u is the normalized solution

Regular triangulation

- \mathcal{C}_k = finite number of closed triangles ($N=2$), closed tetrahedra ($N=3$), ...
- $\Omega_k =: \cup \{T : T \in \mathcal{C}_k\}$ $\Omega_k \subset \Omega$
- $\forall K$ compact, $K \subset \Omega$, then K is absorbed by Ω_k
- $\forall T_1, T_2 \in \mathcal{C}_k$, then $T_1 \cap T_2 = \emptyset$
- conforming triangulation: every face of $T \in \mathcal{C}_k$ is either a face of $T' \in \mathcal{C}_k$ or a subset of $\partial \Omega_k$
- $h_T =: \text{diameter of } T, \mathcal{S}_T = \text{diameter of the inscribed ball}$
- $h =: \max \{h_T : T \in \mathcal{C}_k\} \rightarrow 0$
- $\exists \epsilon$ such that $h_T \leq \epsilon \mathcal{S}_T \quad \forall T \in \mathcal{C}_k, \forall k$

Discrete maximum principle

Define Q_{ij} by $Q_{ij} = \int_{\Omega} A D_j \phi_i D_j \phi_j$

We will assume that

$$\forall i \in I \quad Q_{ii} - \sum_{\substack{j \in I \\ j \neq i}} |Q_{ij}| \geq 0$$

(almost equivalent to assume $Q_{ij} \leq 0 \quad \forall j \neq i$)

Then for every $f \in H^{-1}(\Omega)$, one has

$$\begin{cases} u_h \in V_h \\ \int_{\Omega} A D u_h D v_h = \int_{\Omega} f v_h \end{cases}$$

satisfies $f \geq 0 \Rightarrow u_h \geq 0$

Examples of convex and regular triangulations

for which the discrete maximum principle DMP holds

• $A = Id$ i.e. $-\operatorname{div} A(x)D = -\Delta$

n_i the exterior normals to the faces

DMP holds if $\forall T \in \mathcal{T}_h \quad \min_j n_i \cdot n_j \leq 0 \quad \forall i \neq j$

i.e. every angle of every triangle is acute ($N=2$)
every dihedral angle of every tetrahedron is acute ($N=3$), ...

• Variant: $A(x) = a(x) Id \quad a(x) \in L^\infty(\Omega) \quad a(x) \geq \alpha > 0$

DMP holds under the same condition (acute angles)

11

- $A \in \mathbb{R}^{N \times N}$ coercive (constant coefficients)

making a change of variables transforms

- div $A \Delta$ into $-\Delta$

Assume that the angles are acute after

this change of variables \Rightarrow DMP holds

- Variant: $A(x) = a(x)C$ $a(x) \in L^\infty(\Omega)$, $a \geq \alpha > 0$
 $C \in \mathbb{R}^{N \times N}$ coercive

DMP holds under the same condition

- $A(x) = a(x)C + E(x)$
 $a(x) \in L^\infty(\Omega)$, $a(x) \geq \alpha > 0$, $C \in \mathbb{R}^{N \times N}$ coercive
 $E(x) \in L^\infty(\Omega)^{N \times N}$ $\|E\|_{L^\infty(\Omega)^{N \times N}}$ small

- $N=2$ if the matrix is $A(x) = \begin{pmatrix} a(x) & b(x) \\ b(x) & d(x) \end{pmatrix}$

we are able to build a regular triangulation for which DMP holds if

$$a(x) \geq \alpha, d(x) \geq \alpha, \alpha > 0, |b(x)| \leq \alpha f(a(x), d(x))$$

while coerciveness of the matrix holds iff

$$\underline{\quad}, \underline{\quad}, \underline{\quad}, |b(x)| \leq \sqrt{(a(x) - \alpha)(d(x) - \alpha)}$$

- In general for a given coercive matrix $A(x)$

we do not know whether it is possible to build a regular triangulation for which DMP holds

The proof: a priori estimate

$$u_h \in V_h, \int_{\Omega} A D u_h D v_h = \int_{\Omega} f v_h \quad \forall v_h \in V_h$$

Take $v_h = u_h$? no! Take $v_h = T_k(u_h)$? no!

Take $v_h = T_h T_k(u_h) \in V_h$

$$\int_{\Omega} A D u_h D T_h T_k(u_h) = \int_{\Omega} f T_h T_k(u_h)$$

$$\int_{\Omega} A D T_h T_k(u_h) D T_h T_k(u_h) + \int_{\Omega} A (D u_h - D T_h T_k(u_h)) D T_h T_k(u_h) =$$

$$= \int_{\Omega} f T_h T_k(u_h)$$

coerciveness

$$\geq \alpha \int_{\Omega} |D T_h T_k(u_h)|^2$$

$$\leq \int_{\Omega} |f| k = k \|f\|_{L^2(\Omega)}$$

?

14
Lemma If DMP holds, i.e. if

$$\forall i \quad Q_{ii} - \sum_{j \neq i} |Q_{ij}| \geq 0$$

then

$$\int_{\Omega} A(Dv_k - D\Gamma_k \Gamma_k(v_k)) D\Gamma_k \Gamma_k(v_k) \geq 0$$

$$\forall k, \forall v_k \in V_k$$

(and almost conversely)

Compare with

$$\int_{\Omega} A(\Phi_v - D\Gamma_k(v)) D\Gamma_k(v) = 0$$

$$\forall k, \forall v \in H^1(\Omega)$$

therefore a priori estimate

$$(1) \quad u_h \in V_h \quad \int_{\Omega} |D \tau_h \tau_h(u_h)|^2 \leq k \frac{\|f\|_{L^1}^2}{\alpha}$$

Lemma discrete version of Boccardo - Gallouet

If (1) holds, then

$$\|u_h\|_{W_0^{1,q}(\Omega)} \leq C(N, \Omega, \gamma) \frac{\|f\|_{L^1}}{\alpha}$$

$\forall q < \frac{N}{N-1}$

Proof of $u_h \rightarrow u$ in $W_0^{1,1}(\Omega)$ strong (a remark. ad.)

Let $f \in L^2(\Omega)$ $f^\varepsilon \rightarrow f$ in $L^2(\Omega)$ strong

Define u_h^ε by

$$u_h^\varepsilon \in V_h \quad \int_{\Omega} A D u_h^\varepsilon D v_h = \int_{\Omega} f v_h \quad \forall v_h \in V_h$$

① Then for ε fixed $u_h^\varepsilon \rightarrow u^\varepsilon$ in $H_0^1(\Omega)$ strong

$\Rightarrow u_h^\varepsilon \rightarrow u^\varepsilon$ in $W_0^{1,1}(\Omega)$ strong

② On the other hand

$$u_h^\varepsilon - u_h \in V_h \quad \int_{\Omega} A D(u_h^\varepsilon - u_h) D v_h = \int_{\Omega} (f^\varepsilon - f) v_h \quad \forall v_h \in V_h$$

Then (Boccardo Gallouet)

$$\int_{\Omega} |D \Pi_h \text{Tr}(u_h^\varepsilon - u_h)|^2 \leq k \|f^\varepsilon - f\|_{L^1} \\ \Rightarrow \|u_h^\varepsilon - u_h\|_{W_0^{1,1}(\Omega)} \leq C \frac{\|f^\varepsilon - f\|_{L^1(\Omega)}}{\alpha}$$

$$\|u_k - u\|_{W^{1,q}} \leq \|u_k - u_h^\varepsilon\|_{W^{1,q}} + \|u_h^\varepsilon - u^\varepsilon\|_{W^{1,q}} + \|u^\varepsilon - u\|_{W^{1,q}}$$

$$\leq c \frac{\|f^\varepsilon - f\|_{L^2}}{\alpha}$$

ε fixed

discrete Boccardo Gollouet

Rehman: vol. continuous Boccardo Gollouet

$$\Rightarrow u_k \rightarrow u \quad W^{1,q}(\Omega) \text{ strong} \quad \forall q < \frac{N}{N-1} \quad \text{QED}$$

Error estimate Take $f \in L^2(\Omega)$, $f^\varepsilon = T_{1/\varepsilon}(f)$, $n > 1$

then $\|f^\varepsilon - f\|_{L^2} \leq c \varepsilon^{n-1} \|f\|_{L^2}$

On the other hand, if A smooth, $N=2$ or 3

$$\|u_k^\varepsilon - u^\varepsilon\|_{H^1_0} \leq C_A h \|f^\varepsilon\|_{L^2(\Omega)}$$

Taking $\varepsilon = \frac{h^{2/n}}{\|f\|_{L^2}}$ gives $\|u_k - u\|_{W^{1,q}} \leq c h^{2(1-1/n)} \|f\|_{L^2}$