

# Crystal dissolution and precipitation in porous media: formal homogenization and numerical experiments

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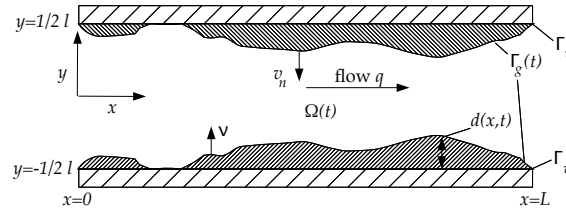
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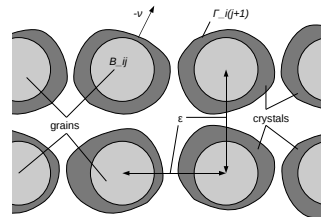
# Outline

- Introduction: crystals in porous media
- Model: free boundary problem

- Thin strip



- Perforated domain



- Open Problems / Future Directions

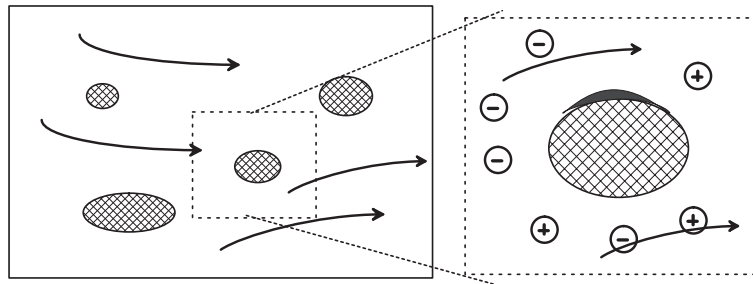
# Flow through porous medium

porous medium, fully saturated

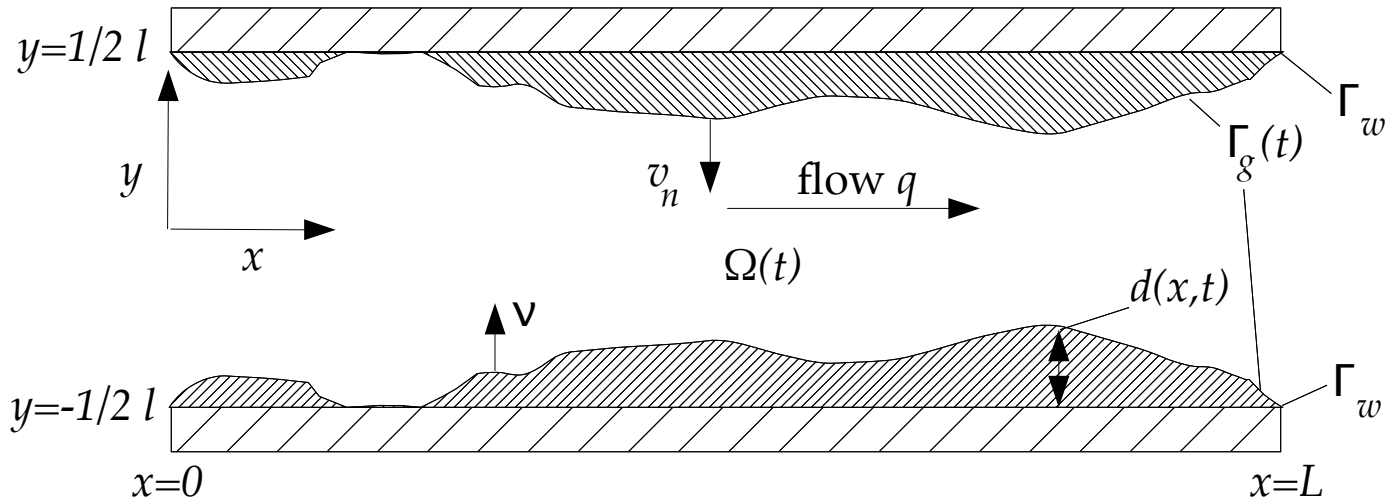
dissolved ions transported by the flow, e.g. sodium ( $Na^+$ ) and chlorine ( $Cl^-$ ) ions

crystals attached to the grain surface (porous matrix), e.g. sodium chloride ( $NaCl$ )

precipitation/dissolution reaction on the grain surface



# Model equations



## Flow:

$q$  – fluid velocity (m/s)

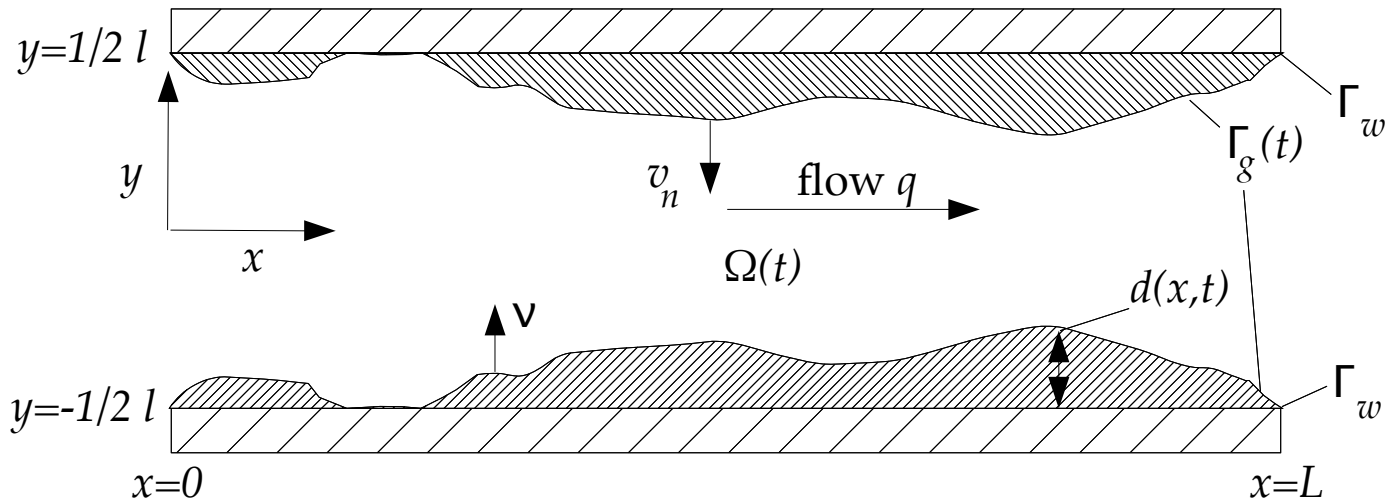
$p$  – pressure inside fluid (Pa)

$\mu$  – dynamic viscosity (kg/(ms))

$$\text{Stokes flow: } \left. \begin{aligned} \mu \Delta q &= \nabla p, \\ \nabla \cdot q &= 0. \end{aligned} \right\} \text{ in } \Omega_t \text{ and } q = K v_n \nu, \text{ on } \Gamma_t,$$

with  $K = \frac{\rho_f - (n_1 + n_2) \rho_c}{\rho_f}$ . (Using the assumption  $c_f + c_1 + c_2 \equiv \rho_f$ )

# Model equations



Ion concentration:

Precipitation, dissolution reaction:



Mass conservation for ion concentrations  $c_i$  (mol/m<sup>3</sup>) ( $i = 1, 2$ ):  
in fluid

$$\begin{aligned} \partial_t c_i + \nabla \cdot (q c_i - D \nabla c_i) &= 0 & \text{for } x \in \Omega_t \\ (n_i \rho - c_i) v_n &= D \nu \cdot \nabla c_i & \text{for } x \in \Gamma_t \end{aligned}$$

# Dissolution and precipitation rate

Thickness of **crystalline layer**:

normal velocity of interface between crystals and fluid

$$v_n = r_p - r_d,$$

1) *Precipitation rate*  $r_p$  (mol/m<sup>2</sup>s):

$$r_p = k_p r(c_1, c_2) = k_p [c_1]_+^{n_1} [c_2]_+^{n_2}$$

2) *Dissolution rate*  $r_d$  (mol/m<sup>2</sup>s)

$$r_d \in k_d H(d(x, \Gamma_w))$$

where  $H$  denotes the set-valued Heaviside graph

$$H(u) = \begin{cases} \{0\}, & \text{if } u < 0, \\ [0, 1], & \text{if } u = 0, \\ \{1\}, & \text{if } u > 0. \end{cases}$$

# 2D Model: dimensionless equations

Denote  $\epsilon := \frac{l}{L}$ , ...

Assumptions: symmetry w.r.t.  $y$ -axis,  $c_1 = c_2 = c_{ref}u^\epsilon$

$$\left\{ \begin{array}{l} u_t^\epsilon = \nabla \cdot (D\nabla u^\epsilon - q^\epsilon u^\epsilon), \\ \epsilon^2 \mu \Delta q^\epsilon = \nabla p^\epsilon, \\ \nabla \cdot q^\epsilon = 0, \\ u^\epsilon, q^\epsilon \text{ and } p^\epsilon \text{ symmetric around } y = 0, \end{array} \right. \quad \text{in } \Omega^\epsilon(t),$$
$$\left\{ \begin{array}{l} d_t^\epsilon = k(r(u^\epsilon) - w)\sqrt{1 + (\epsilon d_x^\epsilon)^2}, \\ w \in H(d^\epsilon), \\ \nu^\epsilon \cdot (D\nabla u^\epsilon - q^\epsilon u^\epsilon) = -\epsilon k(r(u^\epsilon) - w)(\rho - u^\epsilon), \\ q^\epsilon = -\epsilon K k(r(u^\epsilon) - w)\nu^\epsilon, \end{array} \right. \quad \text{on } \Gamma^\epsilon(t)$$

where

$$\Omega^\epsilon(t) := \{(x, y) \mid 0 \leq x \leq 1, -\epsilon(1/2 - d^\epsilon(x, t)) \leq y \leq \epsilon(1/2 - d^\epsilon(x, t))\},$$

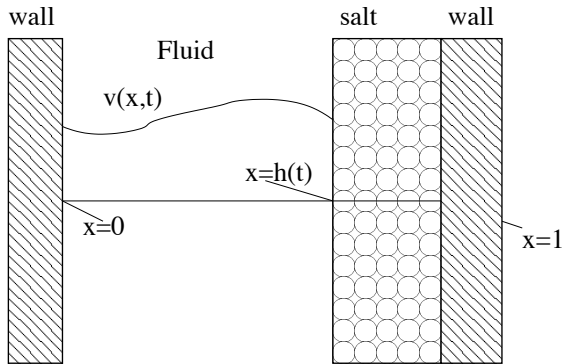
and where

$$\nu^\epsilon = (\epsilon \partial_x d^\epsilon, -1)^T / \sqrt{1 + (\epsilon \partial_x d^\epsilon)^2},$$

# 1D model

Assumptions:

- no flow:  $q = 0$
- 1D



$$\begin{cases} \partial_t v = \partial_x^2 v, & \text{for } x \in (0, h(t)), \\ \partial_x v = 0, & \text{for } x = 0, \\ \partial_x v = (\rho - v)h'(t), & \text{for } x = h(t), \\ h'(t) = D_a(w(t) - r(v)), & \text{for } x = h(t), \\ w(t) \in H(1 - h(t)). \end{cases}$$

Theorem: *There exists a unique, positive and bounded solution.*  
(Pop, v.N. *IMA J. Appl. Math.* 2008) ,

2D/3D: existence and uniqueness are open



# 2D Simulation: dissolution in strip

(Movie)

# Thin strip: upscaling

Formal asymptotics for  $\epsilon \rightarrow 0$

Assume

$$\begin{aligned}u^\epsilon(x, y, t) &= u_0(x, \frac{y}{\epsilon}, t) + \epsilon u_1(x, \frac{y}{\epsilon}, t) + \epsilon^2(\dots), \\q^\epsilon(x, y, t) &= q_0(x, \frac{y}{\epsilon}, t) + \epsilon q_1(x, \frac{y}{\epsilon}, t) + \epsilon^2(\dots), \\p^\epsilon(x, y, t) &= p_0(x, \frac{y}{\epsilon}, t) + \epsilon p_1(x, \frac{y}{\epsilon}, t) + \epsilon^2(\dots), \\d^\epsilon(x, t) &= d_0(x, t) + \epsilon d_1(x, t) + \epsilon^2(\dots).\end{aligned}$$

The vertical coordinate of the variables  $u_i(x, z, t)$ ,  $q_i(x, z, t)$  and  $p^\epsilon(x, z, t)$  are rescaled. They are defined on

$$\Omega(t) := \{(x, z) | 0 \leq x \leq 1, -1/2 + d^\epsilon \leq z \leq 1/2 - d^\epsilon\}.$$

# Formal asymptotics

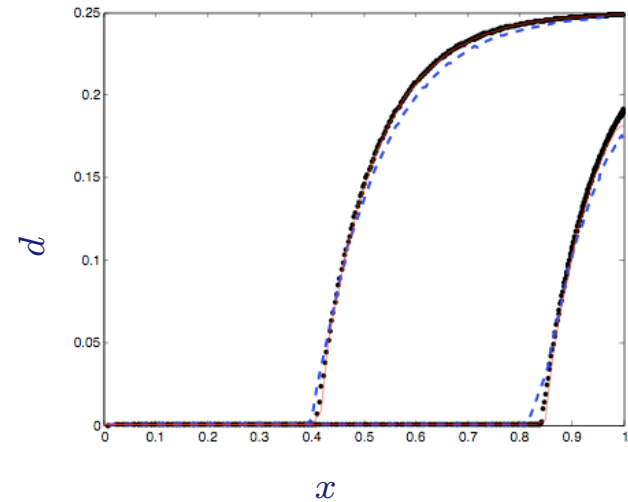
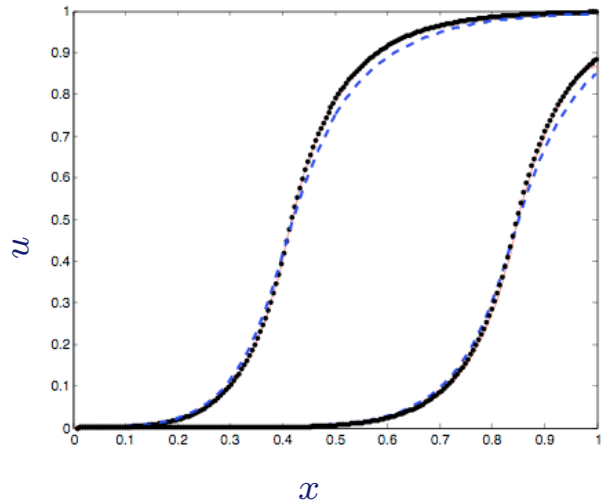
Substituting the asymptotic expansions, integrating along the  $z$ -coordinate, and retaining only terms independent of  $\epsilon$ , yields

$$\begin{cases} \partial_t((1 - 2d_0)u_0 + 2\rho d_0) = \partial_x(D(1 - 2d_0)\partial_x u_0 - \bar{q}u_0), \\ \partial_x \bar{q} - 2K\partial_t d_0 = 0, \\ \partial_t d_0 \in k(r(u_0) - H(d_0)), \end{cases}$$

where

$$\bar{q}(x, t) = \int_{-1/2+d_0(x,t)}^{1/2-d_0(x,t)} q_0^{(1)}(x, z, t) dz.$$

# Thin strip: upscaled vs. original equations



Profiles of both 2-D and effective model, for  $t = 20$  and  $t = 40$ .

Thin line: solution of the effective model

Dashed line: 2-D model with  $\epsilon = 0.1$

Dots: 2-D model with  $\epsilon = 0.01$

## Thin strip: traveling wave

Non-negative traveling wave solutions:

$u = u(\eta)$ ,  $d = d(\eta)$  and  $q = q(\eta)$  with  $\eta = x - at$ , and  $d < 1/2$ , satisfying

$$\left. \begin{aligned} -a((1 - 2d)u + 2\rho d)' - ((1 - 2d)Du' - qu)' &= 0, \\ -ad' \in k(r(u) - H(d)), \\ q' + 2aKd' &= 0, \end{aligned} \right\} \text{ in } \mathbb{R}.$$

and boundary conditions

$$\begin{aligned} u(-\infty) &= u^*, \quad u(\infty) = u_*, \\ d(-\infty) &= d^*, \quad d(\infty) = d_*, \\ q(-\infty) &= q^*, \end{aligned}$$

where  $0 \leq u^*, u_*, q^*$  and  $0 \leq d^*, d_* < 1/2$ .

## Thin strip: traveling wave (2)

$$I \begin{cases} d_* > 0, & d^* = 0 \\ u_* = u_s, & 0 \leq u^* < u_s \end{cases} \quad (\text{dissolution wave})$$
$$II \begin{cases} d^* > 0, & d_* = 0 \\ u^* = u_s, & 0 \leq u_* < u_s \end{cases} \quad (\text{precipitation wave})$$

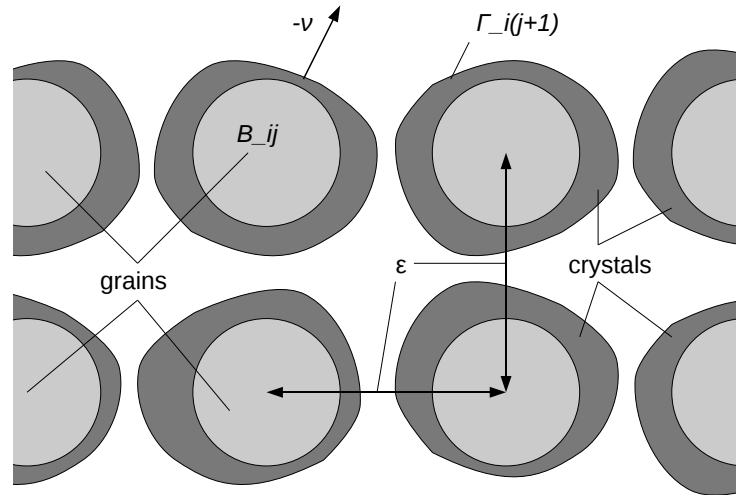
Theorem. *No traveling wave exists with boundary conditions from class II.*

Theorem. *For any set of boundary conditions from class I, there exists a traveling wave (unique up to a shift).*

(v.N. *EJAM* 2008)

(Compare to results in Knabner, Van Duijn, *EJAM* 1997: crystal layer has infinitesimal thickness, can be obtained as formal limit  $\rho \rightarrow \infty$ )

# Perforated Domain



Level set function  $S$  such that  $\Gamma = \{S = 0\}$ .

Evolution of  $\Gamma$  given by

$$S_t + |\nabla S|v_n = S_t - \frac{1}{\rho_c}(k_p r(c_1, c_2) - k_d w(x))|\nabla S| = 0$$

Expand  $S^\epsilon$

# Perforated Domain: homogenization

Formal asymptotics for  $\epsilon \rightarrow 0$

Assume

$$\begin{aligned}u^\epsilon(x, t) &= u_0\left(x, \frac{x}{\epsilon}, t\right) + \epsilon u_1\left(x, \frac{x}{\epsilon}, t\right) + \epsilon^2(\dots), \\q^\epsilon(x, t) &= q_0\left(x, \frac{x}{\epsilon}, t\right) + \epsilon q_1\left(x, \frac{x}{\epsilon}, t\right) + \epsilon^2(\dots), \\p^\epsilon(x, t) &= p_0\left(x, \frac{x}{\epsilon}, t\right) + \epsilon p_1\left(x, \frac{x}{\epsilon}, t\right) + \epsilon^2(\dots), \\S^\epsilon(x, t) &= S_0\left(x, \frac{x}{\epsilon}, t\right) + \epsilon S_1\left(x, \frac{x}{\epsilon}, t\right) + \epsilon^2(\dots).\end{aligned}$$

Where  $u_k(\cdot, y, \cdot)$ ,  $q_k(\cdot, y, \cdot)$ ,  $p_k(\cdot, y, \cdot)$  and  $S_k(\cdot, y, \cdot)$  are 1-periodic in  $y$ .



# Upscaled equations

$$\begin{cases} \partial_t S_0(x, y, t) - f(u_0(x, t), y) |\nabla_y S_0(x, y, t)| = 0 & y \in [0, 1]^2 \\ \partial_t (|Y_0(x, t)| u_0) = \nabla_x \cdot (D\mathcal{A}(x, t) \nabla_x u_0 - \bar{q} u_0) + |\Gamma_0(x, t)| f(u_0) \rho & x \in \Omega \\ \bar{q} = -\frac{1}{\mu} \mathcal{K}(x, t) \nabla_x p_0 & x \in \Omega \\ \nabla_x \cdot \bar{q} = |\Gamma_0(x, t)| K f(u_0) & x \in \Omega \end{cases}$$

where

$$\begin{aligned} f(u_0(x, t), y) &= k(u_0^2 - H_\delta(\text{dist}(y, \Gamma))) \\ Y_0(x, t) &= \{S_0 < 0\} \\ \Gamma_0 &= \{S_0 = 0\} \end{aligned}$$

(Hard step: interchange  $\nabla_x$  and integration

$$\begin{aligned} |Y_0(x, t)| \partial_t u_0 &= \int_{Y_0(x, t)} \nabla_y \cdot (\nabla_y u_2 + \nabla_x u_1 - q_1 u_0 - q_0 u_1) dy \\ &+ \int_{Y_0(x, t)} \nabla_x \cdot (\nabla_y u_1 + \nabla_x u_0 - q_0 u_0) dy \end{aligned}$$

(v.N. MSS 2008))

where the tensors  $\mathcal{A} = (a_{ij})_{i,j}$  and  $\mathcal{K} = (k_{ij})_{i,j}$  are given by

$$a_{ij} = \int_{Y_0(x,t)} \delta_{ij} + \partial_{y_i} v_j \, dy,$$

where  $v_j$  solves the cell-problem

$$\begin{cases} \Delta_y v_j = 0 & y \in Y_0(x, t) \\ \nu_0 \nabla_y v_j = -e_j & y \in \Gamma_0(x, t) \\ \text{periodicity in } y, \end{cases}$$

and

$$k_{ij} = \int_{Y_0(x,t)} w_{ji} \, dy,$$

where the vector  $w_j$  with components  $w_{ji}$  solves the cell-problem

$$\begin{cases} \Delta_y w_j = \nabla_y \pi_j + e_j & y \in Y_0(x, t) \\ \nabla_y \cdot w_j = 0 & y \in Y_0(x, t) \\ w_j = 0 & y \in \Gamma_0(x, t) \\ \text{periodicity in } y, \end{cases}$$

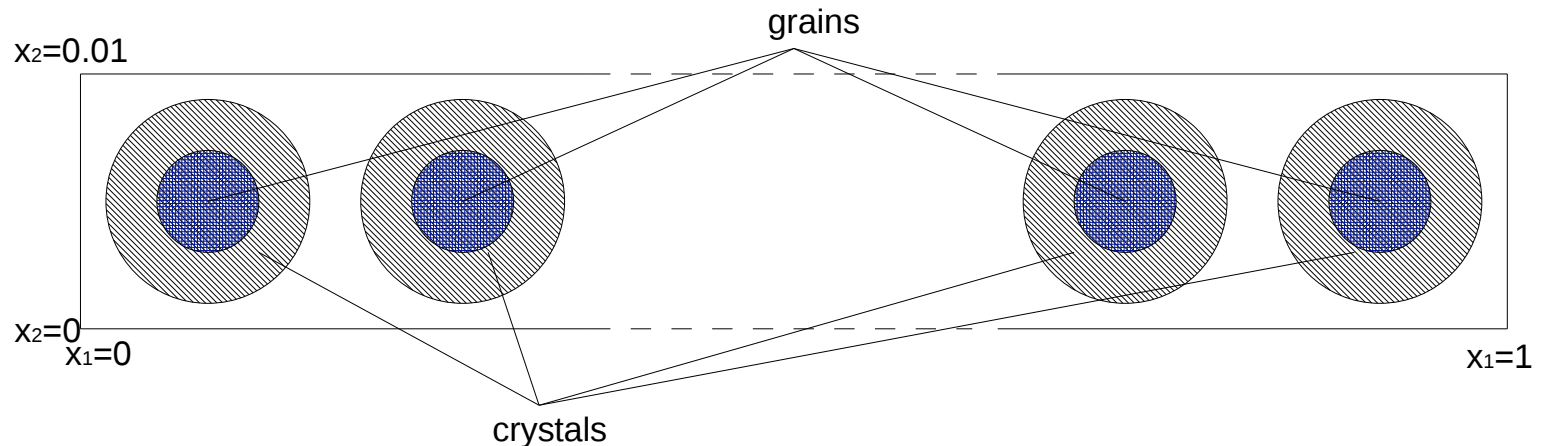
with  $\pi_j$  the corresponding pressure.

# Simplification: circular grains

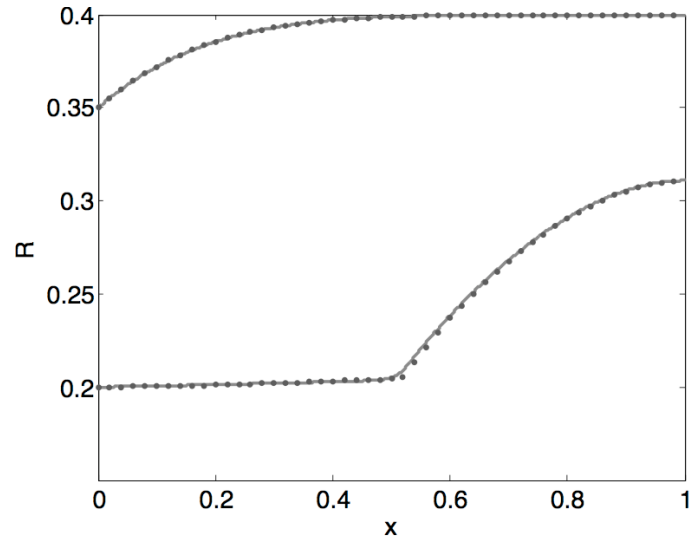
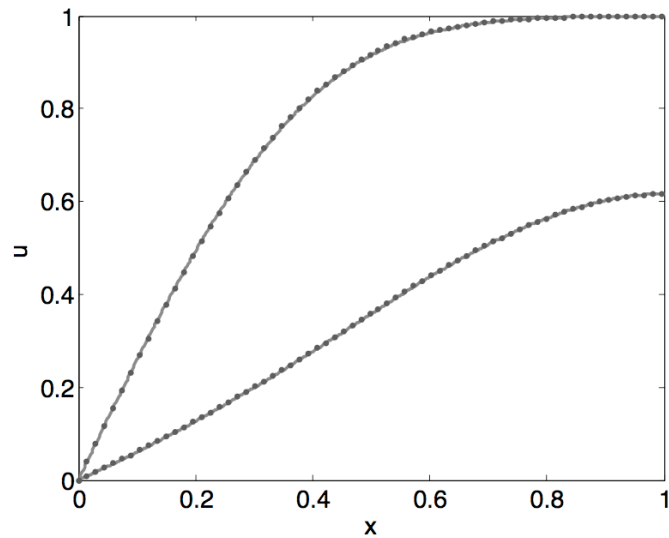
$$\begin{cases} \partial_t R(x, t) = f(u_0, R(x, t)) := k(u_0^2 - H_\delta(R - R_{min})) & x \in \Omega \\ \partial_t((1 - \pi R^2)u_0) = \nabla_x \cdot (DA(R)\nabla_x u_0 - \bar{q}u_0) + 2\pi Rf(u_0, R)\rho & x \in \Omega \\ \bar{q} = -\frac{1}{\mu}\mathcal{K}(R)\nabla_x p_0 & x \in \Omega \\ \nabla_x \cdot \bar{q} = 2\pi RKf(u_0) & x \in \Omega \end{cases}$$

Periodicity in  $x_2$  direction

(Similar simplification is possible for ellipses, not for squares!)



# Perforated domain upscaled vs. original equations



Profiles of both 2-D and effective model, for  $t = 10$  and  $t = 40$ .

Dots: 2-D model with  $\epsilon = 0.01$

Line: effective model

# Open problems / Future directions

- \* Existence, uniqueness, estimates for microscale free boundary model in 2D/3D?
- \* Rigorous upscaling (phase-field formulation, with Ch. Eck)
- \* Blocking of strip ( $d = 1/2$ )?
- \* Application to biofilm growth models (with R. Helmig)