# HYPERBOLAS, ORTHOLOGY, AND ANTIPEDAL TRIANGLES 

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#### Abstract

We obtain several characterisations of the Kiepert, Jarabek, and Feuerbach hyperbolas of a triangle $A B C$ using the antipedal triangles of a variable point $P$ in the plane and the notion of orthologic triangles. Our arguments are algebraic and use complex numbers.


## 1. Introduction

Among conics that pass through the vertices $A, B, C$ of a scalene triangle $A B C$ and its orthocenter $H$ - all of them are equilateral hyperbolas - the most interesting are Feuerbach, Kiepert, and Jarabek hyperbolas. These are hyperbolas that go through the incenter $I$, the centroid $G$, and the circumcenter $O$, respectively. They have been extensively studied in the past. The following are some more recent papers that consider them: [1], [2], [6], [7], [5], [12], [21], [20], and [24].

In this paper we shall present new characterisations of the Kiepert, Jarabek, and Feuerbach hyperbolas associated to a triangle $A B C$. We shall use the same method for all three hyperbolas. Our idea is to associate to every point $P$ its antipedal triangle $P^{a} P^{b} P^{c}$ and to look for triangles $X Y Z$ having the property that $P$ lies on a hyperbola if and only if the triangles $P^{a} P^{b} P^{c}$ and $X Y Z$ are orthologic.

Recall that triangles $A B C$ and $X Y Z$ are orthologic provided the perpendiculars from the vertices of $A B C$ on the sides $Y Z, Z X$, and $X Y$ of $X Y Z$ are concurrent. The point of concurrence of these perpendiculars is denoted by $[A B C, X Y Z]$. It is well-known (see [8] or [17]) that the relation of orthology for triangles is reflexive and symmetric. Hence, the perpendiculars from the vertices of $X Y Z$ on the sides $B C, C A$, and $A B$ of $A B C$ are concurrent at the point $[X Y Z, A B C]$.

In this definition and throughout this paper all triangles are nondegenerate, that is, their vertices are not collinear. The last assumption implies that in our approach we must exclude some points $P$ so that ours are characterisations of three named hyperbolas without a small number of their points.

For a triangle $A B C$, let $W(A B C)$ denote the complement in the plane of the union of the side lines $B C, C A, A B$ and the circumcircle $\gamma_{0}$ of $A B C$. Recall that for a point $P$ in $W(A B C)$, the antipedal triangle $P^{a} P^{b} P^{c}$ of $P$ has intersections of

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perpendiculars from $A, B, C$ on $A P, B P, C P$ as vertices. Let $\mathscr{A}$ denote the function that associates to a point $P$ its antipedal triangle $P^{a} P^{b} P^{c}$.

The domain of the function $\mathscr{A}$ is $W(A B C)$ because it follows immediately from Thales Theorem and incidence arguments that the points $P^{a}, P^{b}$, and $P^{c}$ coincide if and only if $P$ lies on the circumcircle $\gamma_{0}$.

Let $\gamma$ be a curve in the plane. Let $\mathscr{F}$ be a function from a subset $S$ of the plane that associates to each point $P$ of $S$ a triangle $\mathscr{F}(P)$. A triangle $X Y Z$ is called $(\mathscr{F}, \gamma)$-generating provided $X Y Z$ is orthologic to $\mathscr{F}(P)$ if and only if a point $P$ is in the set $\gamma \cap S$.

Let $\gamma_{F}, \gamma_{J}$, and $\gamma_{K}$ denote the Feuerbach, Jarabek, and Kiepert hyperbola of the triangle $A B C$, respectively. With the above definitions and notation we can formulate the results of this paper as contributions to the following problem.

Problem. For $\gamma \in\left\{\gamma_{F}, \gamma_{J}, \gamma_{K}\right\}$, find $(\mathscr{A}, \gamma)$-generating triangles.
Observe that when we know that, for $\gamma \in\left\{\gamma_{F}, \gamma_{J}, \gamma_{K}\right\}$, a triangle $X Y Z$ is $(\mathcal{A}, \gamma)$-generating, then we have the following characterisation of $\gamma$ :

The hyperbola $\gamma$ is the closure of all points $P$ in $W(A B C)$ such that the triangles $P^{a} P^{b} P^{c}$ and $X Y Z$ are orthologic.

The vertices of the triangles $X Y Z$ which we prove in this paper to provide solutions to the above problem are all endpoints of segments of controlled length perpendicular to sides of $A B C$. A more formal description uses the following notation.

For a triple $h=\left(s_{1}, s_{2}, s_{3}\right)$ of real numbers and for triangles $A B C$ and $X Y Z$, let [ $A B C, X Y Z, h]$ denote the triangle $U V W$ such that $U X, V Y, W Z$ are perpendicular to $B C, C A, A B$ and the directed distances $|U X|,|V Y|,|W Z|$ are equal to $s_{1}, s_{2}, s_{3}$, respectively. When $s_{1}=0$, we put $U=X$, and we do similar assignments when $s_{2}$ and $s_{3}$ are zero. For $s_{1}>0$ the vector $\overrightarrow{X U}$ points towards outside of $A B C$ while for $s_{1}<0$ it points towards inside.

For an expression $\varepsilon$ in terms of side lengths $a, b$, and $c$ of the triangle $A B C$ and a real number $h$, let $\varepsilon[h]$ denote the triple ( $h \varepsilon, h \varphi(\varepsilon), h \psi(\varepsilon))$. More precisely, the coordinates $\varepsilon[h]_{1}, \varepsilon[h]_{2}, \varepsilon[h]_{3}$ of $\varepsilon[h]$ are products with $h$ of $\varepsilon$, the first cyclic permutation $\varphi(\varepsilon)$ of $\varepsilon$, and the second cyclic permutation $\psi(\varepsilon)$ of $\varepsilon$, respectively. For example, $a[h]=(h a, h b, h c)$ and if $w_{a}=\frac{b+c-a}{2}, w_{b}=\frac{c+a-b}{2}$, and $w_{c}=\frac{a+b-c}{2}$, then $w_{a}[h]=\left(h w_{a}, h w_{b}, h w_{c}\right)$.

With this notation at hand, we can describe our task in this paper as a search for expressions $\varepsilon$ and points $X, Y$, and $Z$ in the plane of the triangle $A B C$ such that the triangles $[A B C, X Y Z, \varepsilon[h]]$ are $(\mathscr{A}, \gamma)$-generating for $\gamma$ either $\gamma_{F}, \gamma_{J}$, or $\gamma_{K}$.

Recall that the triangles $[A B C, X Y Z, \varepsilon[h]]$ have already been used for characterisations of Kiepert and Feuerbach hyperbolas. Indeed, the original description of the Kiepert hyperbola is that it is the locus of centers of perspective of triangles $A B C$ and $X_{h} Y_{h} Z_{h}$, where $X_{h} Y_{h} Z_{h}=\left[A B C, A_{m} B_{m} C_{m}, a[h]\right]$ and $A_{m}, B_{m}, C_{m}$ are midpoints of sides (see [6]).

Another application of triangles $X_{h} Y_{h} Z_{h}$ on vertices of similar isosceles triangles
build on sides of $A B C$ is a result in [13] which shows that triangles $A B C$ and $X_{h} Y_{h} Z_{h}$ are orthologic and the point $\left[A B C, X_{h} Y_{h} Z_{h}\right]$ traces again the Kiepert hyperbola as $h$ goes through the reals.

The Feuerbach hyperbola is the locus of centers of perspective of triangles $A B C$ and $P_{h} Q_{h} R_{h}$, where $P_{h} Q_{h} R_{h}=\left[A B C, A_{p} B_{p} C_{p}, 1[h]\right]$ and $A_{p}, B_{p}, C_{p}$ are projections of the incenter onto sides (see [11]).

Another application of triangles $P_{h} Q_{h} R_{h}$, whose vertices are intersections of circles concentric to the incircle with perpendiculars through incenter to sides, is a result which shows that triangles $A B C$ and $P_{h} Q_{h} R_{h}$ are orthologic and the point [ABC, $\left.P_{h} Q_{h} R_{h}\right]$ again traces the Feuerbach hyperbola as $h$ goes through the reals.

## 2. Preliminaries on complex numbers

We shall use complex numbers because they lead to the simplest expressions. Hence, our proofs are entirely algebraic. Every book on the use of complex numbers in geometry from the references below gives excellent and adequate introductions to this technique of proof. In this section we give only the most basic notions and conventions.

A point $P$ in the Gauss plane is represented by a complex number $p$. This number is called the affix of $P$ and we write $\widetilde{P}=p$ or $P(p)$ to indicate this. The complex conjugate of $p$ is denoted $\bar{p}$. However, we shall be avoiding this notation by using next letter (now letter $q$ ) for the complex conjugate and sometimes write $P(p, q)$ or $\widetilde{P}=(p, q)$ in order to describe affix of a point and to describe its complex conjugate. In order to avoid quotients, we shall use $z^{*}$ for $1 / z$.

In the sections on the Kiepert and Jarabek hyperbolas, we follow the standard assumption that the vertexes $A, B$, and $C$ of the reference triangle are represented by numbers $u, v$, and $w$ on the unit circle so that the circumcentre $O$ of $A B C$ is the origin. Hence, the affix of $O$ is number 0 (zero) and complex conjugates of $u, v$, and $w$ are $1 / u, 1 / v$, and $1 / w$ (or, in our notation, $u^{*}, v^{*}$, and $w^{*}$ ).

Most interesting points, lines, circles, curves,... associated with the triangle $A B C$ are expressions that involve symmetric functions of $u, v$, and $w$ that we denote as follows.

$$
\begin{gathered}
\sigma=u+v+w, \quad \tau=v w+u w+u v, \quad \mu=u v w \\
\sigma_{a}=-u+v+w, \quad \sigma_{b}=u-v+w, \quad \sigma_{c}=u+v-w \\
\tau_{a}=-v w+w u+u v, \quad \tau_{b}=v w-w u+u v, \quad \tau_{c}=v w+w u-u v \\
\mu_{a}=v w, \quad \mu_{b}=w u, \quad \mu_{c}=u v, \quad \delta_{a}=v-w \\
\delta_{b}=w-u, \quad \delta_{c}=u-v, \quad \zeta a=v+w, \quad \zeta_{b}=w+u, \quad \zeta c=u+v
\end{gathered}
$$

For each $k \geqslant 2, \sigma_{k}, \sigma_{k a}, \sigma_{k b}$, and $\sigma_{k c}$ are derived from $\sigma, \sigma_{a}, \sigma_{b}$, and $\sigma_{c}$ with the substitution $u=u^{k}, v=v^{k}, w=w^{k}$. In a similar fashion we can define analogous expressions using letters $\tau, \mu, \delta$, and $\zeta$. We shall use corresponding small Latin
letters to denote analogous symmetric functions in $a, b$, and $c$ (lengths of sides of $A B C$ ). For example, $m=a b c, s=a+b+c, t=b c+c a+a b, z_{a}=b+c$, and $s_{2 a}=b^{2}+c^{2}-a^{2}$.

The expressions which appear in triangle geometry usually depend on sets that are of the form $\{a, b, c, \ldots, x, y, z\}$ (that is, union of triples of letters). Let $\varphi$ and $\psi$ stand for permutations $|b, c, a,: \ldots, y, z, x|$ and $|c, a, b, \ldots, z, x, y|$.

Let $f=f(x, y, \ldots)$ be an expression that depends on a set $S=\{x, y, \ldots\}$ of variables and let $\varrho: S \rightarrow S$ be a permutation of $S$. Then $f^{\varrho}$ is a short notation for $f(\varrho(x), \varrho(y), \ldots)$. For permutations $\varrho, \ldots, \xi$ of $S$ we shall use $\mathbb{S}_{\varrho, \ldots, \xi} f$ and $\mathbb{P}_{\varrho}, \ldots, \xi f$ to shorten $f+f^{\varrho}+\cdots+f^{\xi}$ and $f f^{\varrho} \ldots f^{\xi}$. Finally, $\mathbb{S} f$ and $\mathbb{P} f$ replace $\mathbb{S}_{\varphi, \psi} f$ and $\mathbb{P}_{\varphi, \psi} f$.

For real numbers $f, g$, and $h$, let $\langle f, g, h\rangle$ be a notation for $-f \mu+\mathbb{S} u^{2}(g v+h w)$. For example, $\langle 6,1,1\rangle=u^{2} v+u^{2} w+v^{2} u+v^{2} w+w^{2} u+w^{2} v-6 u v w$. Let $S$ be the area of $A B C$.

Since points, lines, conics, ... associated to a triangle often appear in triples in which two members are build from a third by appropriate permutation, we shall often give only one of them while the other two (relatives) are obtained from it by cyclic permutations.

Let us close these preliminaries with few words on analytic geometry that we shall use.

In triangle geometry lines play an important role so that we have special notation $[f, g, h]$ for the set of all points $P(p, q)$ that satisfy the equation $f p+g q+h=0$. This set is a line iff there is a complex number $z \neq 0$ such that $z g$ is the complex conjugate of $z f$ and $z h$ is a real number.

Let $X(x, a), Y(y, b)$, and $Z(z, c)$ be three points and let $\ell$ be a line $[f, g, h]$ in the plane. Then the line $X Y$ is $[a-b, y-x, b x-a y]$, the parallel to $\ell$ through $X$ is $[f, g,-g a-f x]$ and the perpendicular to $\ell$ through $X$ is $[f,-g, g a-f x]$. The conditions for points $X, Y$, and $Z$ to be collinear and for lines $\ell_{1}=[f, g, h]$, $\ell_{2}=[k, m, n]$, and $\ell_{3}=[r, s, t]$ to be concurrent are $\Delta=0$ and $\Gamma=0$, where

$$
\Delta=\Delta(X, Y, Z)=\left|\begin{array}{ccc}
x & a & 1 \\
y & b & 1 \\
z & c & 1
\end{array}\right|, \quad \text { and } \quad \Gamma=\Gamma\left(\ell_{1}, \ell_{2}, \ell_{3}\right)=\left|\begin{array}{ccc}
f & g & h \\
k & m & n \\
r & s & t
\end{array}\right|
$$

Moreover, the (oriented) area of the triangle $X Y Z$ is $\frac{I \Delta}{4}$, where $I=\sqrt{-1}$ is the imaginary unit.

There are some notable exceptions to the rule that complex numbers give simpler expressions than trilinear and barycentric coordinates. As a convenience to readers that are more familiar with these coordinates, we shall describe transformation formulas between all three systems and present these shorter forms in relevant cases.

The above formula for the area of a triangle implies that a point $P(p, q)$ has with respect to the base triangle $A B C$ the absolute barycentric coordinates $(\alpha, \beta, \gamma)$,
where $\alpha=\frac{-u n_{a}}{\delta_{b} \delta_{c}}$ and $\beta$ and $\gamma$ are relatives of $\alpha$ and $n_{a}=p+\mu_{a} q-\zeta_{a}$. It follows that a point $P$ with barycentric coordinates $(\alpha, \beta, \gamma)$ has affix

$$
p=\frac{u \alpha+v \beta+w \gamma}{\alpha+\beta+\gamma}
$$

In order to have connection between complex and trilinear coordinates it suffices to recall that absolute trilinear coordinates $(x, y, z)$ and absolute barycentric coordinates $(\alpha, \beta, \gamma)$ of the same point are related by formulas

$$
\alpha=\frac{a x}{2 S}, \quad \beta=\frac{b y}{2 S}, \quad \gamma=\frac{c z}{2 S},
$$

where $S$ is the area of $A B C$ and the lengths of the sides are

$$
a=\left|\delta_{a}\right|=\sqrt{2-\zeta_{2 a} \mu_{a}^{*}}, \quad b=\left|\delta_{b}\right|=\sqrt{2-\zeta_{2 b} \mu_{b}^{*}}, \quad c=\left|\delta_{c}\right|=\sqrt{2-\zeta_{2 c} \mu_{c}^{*}}
$$

## 3. Statements of results

Let $n_{F}=6$ and $n_{J}=n_{K}=5$. For $X=K, F, J$, let $X_{i}$, for $i=1, \ldots, n_{X}$, denote the following expressions.

$$
K_{1}=a, \quad K_{2}=a z_{a}^{*}, \quad K_{3}=a^{2} z_{a}^{*}, \quad K_{4}=a s_{a} z_{a}^{*}, \quad K_{5}=a^{3}
$$

$$
\begin{gathered}
F_{1}=1, \quad F_{2}=s_{a}^{*}, \quad F_{3}=a s_{a}, \quad F_{4}=a s_{a}^{*}, \quad F_{5}=s_{2 a} z_{a} s_{a}^{*}, \quad F_{6}=z_{a} s_{a}^{*} . \\
J_{1}=a^{*}, \quad J_{2}=s_{a} z_{a}^{*}, \quad J_{3}=a s_{2 a}^{*}, \quad J_{4}=z_{a}^{*} s_{2 a}^{*}, \quad J_{5}=a^{*} s_{2 a}^{*} .
\end{gathered}
$$

For $i=J_{3}, J_{4}, J_{5}$ we must assume in addition that $A B C$ has no right angle.
THEOREM 1. Let $h \neq 0$ be a real number. For any triangle $P Q R$ homothetic to the triangle $A B C$, for $X=K, J, F$, and for $i=1, \ldots, n_{X}$, the triangle $\left[A B C, P Q R, X_{i}[h]\right]$ is $\left(\mathscr{A}, \gamma_{X}\right)$-generating.

Remark. Since there can be at most two values of the parameter $h$ for which the vertices of the "triangle" $\left[A B C, P Q R, X_{i}[h]\right]$ are collinear, we must exclude these values in addition to the value $h=0$. In the above statement this is implicit in the assumption that we consider only nondegenerate triangles.

In the above theorem the triangle $P Q R$ can be, for example, the triangle $A B C$, the complementary triangle $A_{m} B_{m} C_{m}$, the anticomplementary triangle $A_{a} B_{a} C_{a}$, the Euler triangle $A_{f} B_{f} C_{f}$, and the opposite triangle $A_{s} B_{s} C_{s}$, where $A_{m}, B_{m}, C_{m}$ denote midpoints of sides of the triangle $A B C, A_{a}, B_{a}, C_{a}$ intersections of parallels through vertices to sides, $A_{f}, B_{f}, C_{f}$ midpoints of segments joining vertices with the orthocenter $H$, and $A_{s}, B_{s}, C_{s}$ reflections of vertices at the circumcenter $O$.

THEOREM 2. For any triangle $P Q R$ homothetic to the triangle $A B C$, for $X=K, F$, $J$, and for $i, j=1, \ldots, n_{X}$, the triangle

$$
\left[A B C,\left[A B C, P Q R, X_{i}[h]\right], X_{j}[k]\right]
$$

is $\left(\mathscr{A}, \gamma_{X}\right)$-generating for all real numbers $h$ and all real numbers $k$ except the value $-h a_{i j}$, where $a_{i j}$ is the $(i, j)$ entry of the matrix $M_{X}$ with

$$
\begin{aligned}
& M_{K}=\left[\begin{array}{ccccc}
1 & \frac{2 z}{y} & \frac{2 z}{v} & \frac{2 z}{u} & 2 x \\
\frac{y}{2 z} & 1 & \frac{y}{v} & \frac{y}{u} & \frac{x y}{z} \\
\frac{v}{2 z} & \frac{y}{y} & 1 & \frac{v}{u} & \frac{v x}{z} \\
\frac{u}{2 z} & \frac{u}{y} & \frac{u}{v} & 1 & \frac{u x}{z} \\
\frac{1}{2 x} & \frac{z}{x y} & \frac{z}{v x} & \frac{z}{u x} & 1
\end{array}\right], \\
& x=s_{2}^{*}, \quad y=s^{2}, \quad z=z_{a} z_{b} z_{c}, \quad u=4 s t-4 m-s^{3}, \quad v=s^{3}-2 s t+2 m, \\
& M_{F}=\left[\begin{array}{cccccc}
1 & \frac{w}{v} & \frac{s}{x} & \frac{y}{x} & \frac{w}{z} & \frac{y}{u} \\
\frac{v}{w} & 1 & \frac{v}{x y} & \frac{v}{s x} & \frac{v}{z} & \frac{v}{s u} \\
\frac{x}{s} & \frac{x y}{v} & 1 & \frac{y}{s} & \frac{x y}{z} & \frac{x y}{s u} \\
\frac{x}{y} & \frac{s x}{v} & \frac{s}{y} & 1 & \frac{s x}{z} & \frac{x}{u} \\
\frac{z}{w} & \frac{z}{v} & \frac{z}{x y} & \frac{z}{s x} & 1 & \frac{z}{s u} \\
\frac{u}{y} & \frac{s u}{v} & \frac{s u}{x y} & \frac{u}{x} & \frac{s u}{z} & 1
\end{array}\right], \\
& x=2 m, y=s_{a} s_{b} s_{c}, z=s_{2 a} s_{2 b} s_{2 c}, u=4 s t-6 m-s^{3}, v=u+2 m, w=16 S^{2} \text {, } \\
& \begin{array}{c}
M_{J}=\left[\begin{array}{ccccc}
1 & \frac{z}{m s} & \frac{y}{4 m^{2}} & \frac{y z}{m s u} & \frac{y}{s x} \\
\frac{m s}{z} & 1 & \frac{s y}{4 m z} & \frac{y}{u} & \frac{m y}{x z} \\
\frac{4 m^{2}}{y} & \frac{4 m z}{s y} & 1 & \frac{4 m z}{s u} & \frac{4 m^{2}}{s x} \\
\frac{m s u}{y z} & \frac{u}{y} & \frac{s u}{4 m z} & 1 & \frac{m u}{x z} \\
\frac{s x}{y} & \frac{x z}{m y} & \frac{s x}{4 m^{2}} & \frac{x z}{m u} & 1
\end{array}\right], \\
x=s_{a} s_{b} s_{c}, \quad y=s_{2 a} s_{2 b} s_{2 c}, \quad z=z_{a} z_{b} z_{c}, \quad u=4 s t-4 m-s^{3} .
\end{array}
\end{aligned}
$$

Remark. Observe that some important triangles related to the triangle $A B C$ are of the form $\left[A B C, A_{m} B_{m} C_{m}, K_{1}[h]\right]$ for a suitable constant $h$. For example, the first Brocard triangle $A_{b} B_{b} C_{b}$ (for $h=2 S / s_{2}$ ), the Torricelli triangles $A_{v} B_{v} C_{v}$ and $A_{u} B_{u} C_{u}$ on vertices of equilateral triangles build on sides either towards outside or towards inside (for $h= \pm \sqrt{3} / 2$ ), and Napoleon triangles $A_{v n} B_{v n} C_{v n}$ and $A_{u n} B_{u n} C_{u n}$ on centers of these equilateral triangles (for $h= \pm \sqrt{3} / 6$ ).

The orthic triangle $A_{o} B_{o} C_{o}$ and the three images triangle $A_{r} B_{r} C_{r}$ whose vertices are reflections of $A, B$, and $C$ at opposite sides of $A B C$ are of the form $\left[A B C, A B C, J_{1}[h]\right]$. Also, the tangential triangle $A_{t} B_{t} C_{t}$ (formed by tangents to the circumcircle at vertices of $A B C$ ) has the form $\left[A B C, A_{m} B_{m} C_{m}, J_{3}[h]\right]$.

Let $v$ denote the expression $a\left(b^{2}+c^{2}-a^{2}\right)$.

THEOREM 3. Let $k \neq 0$ and $h$ be real numbers. For any triangle $P Q R$ homothetic to the triangle $A B C$, for $X=K, F, J$, and for $j=1, \ldots, n_{X}$, the triangle

$$
\left[A B C,[A B C, P Q R, v[h]], X_{j}[k]\right]
$$

is $\left(\mathscr{A}^{\prime}, \gamma_{X}\right)$-generating.
THEOREM 4. Let $k$ and $h \neq 0$ be real numbers. For any triangle $P Q R$ homothetic to the triangle $A B C$, for $X=K, F, J$, and for $j=1, \ldots, n_{X}$, the triangle
$\left[A B C,\left[A B C, P Q R, X_{j}[h]\right], v[k]\right]$
is $\left(\mathscr{A}, \gamma_{X}\right)$-generating.
Let $I_{K}=\{b, K, K b, K m, u, u b, v, v b, u n, v n\}, I_{J}=\{h, o, r, t, t r, w, H h, H o, O$, $O t\}$, and $I_{F}=\{e, e p, e r, k, k r, p, p p, I e, I k, I p, O i\}$. For each element $i$ of these three sets we define a triangle $A_{i} B_{i} C_{i}$ by describing the vertex $A_{i}$. The vertices $B_{i}$ and $C_{i}$ have analogous descriptions. Let $A_{e}$ be the centre of the $A$-excircle, $A_{e p}$ the projection of $A_{e}$ onto $B C$, the point $A_{e r}$ is the reflection of $A_{e}$ at $B C$, the vertex $A_{k}$ is the second intersection of the bisector of the angle $A$ with the circumcircle, $A_{k r}$ is the reflection of $A_{k}$ at $B C$, the point $A_{p}$ is the projection of the incentre $I$ onto $B C$, the vertex $A_{p p}$ is the projection of $A_{p}$ onto $A I, A_{O i}$ is a projection onto $B C$ of any point different from $O$ on line $I O$ joining the incentre with the circumcentre, $A_{I p}$ is a projection onto $B_{p} C_{p}$ of any point different from central point $X_{65}$ [10] on line $I O$, $A_{I e}$ and $A_{l k}$ are projections onto $B_{e} C_{e}$ and $B_{k} C_{k}$ of any point on $I O$ different from the incentre $I$, the point $A_{b}$ is the projection of the Grebe-Lemoine point $K$ onto the perpendicular bisector of $B C$, the vertices $A_{K}, A_{K b}$, and $A_{K m}$ are the projection of any point different from the circumcentre $O$ on the line $K O$ onto $B C, B_{b} C_{b}$, and $O A_{m}$, vertices $A_{u}$ and $A_{u n}$ are the vertex and the centre of the equilateral triangle build on $B C$ towards inside, $A_{v}$ and $A_{v n}$ are the vertex and the centre of the equilateral triangle build on $B C$ towards outside, $A_{u b}$ and $A_{v b}$ are projections of the Grebe-Lemoine points of $A_{u} B_{u} C_{u}$ and $A_{v} B_{v} C_{v}$ onto perpendicular bisectors of $B_{u} C_{u}$ and $B_{v} C_{v}, A_{h}$ is the second intersection of altitude line $A H$ with the circumcircle, $A_{o}$ is the projection of $A$ onto $B C$, the point $A_{r}$ is the reflection of $A$ at $B C$, the intersection of tangents to the circumcircle at $B$ and $C$ is $A_{t}$, the reflection of $A_{t}$ at $B C$ is $A_{t r}, A_{w}$ is the intersection of common tangents of the $A$-excircle with $B$-excircle and $C$-excircle, $A_{H h}$ and $A_{H o}$ are the projections onto $B_{h} C_{h}$ and $B_{o} C_{o}$ of any point $X$ on the Euler line of $A B C$ different from the orthocentre $H$, and $A_{O}$ and $A_{O t}$ are the projections onto $B C$ and $B_{t} C_{t}$ of any point $X$ on the Euler line of $A B C$ different from the circumcentre $O$.

Some of the cases in the following theorem are clearly consequences of the previous theorem (for example, the first Brocard triangle $A_{b} B_{b} C_{b}$ has the form $\left[A B C, A_{m} B_{m} C_{m}, K_{1}[k]\right]$, for a suitable $k \neq 0$ ). Moreover, in some cases we must make additional assumptions about the triangle $A B C$. For example, for $i=b$, the triangle $A B C$ can not be equilateral and for $i=t$ and $i=w$ it can not have right angle.

THEOREM 5. For $X=K, J, F$, for $i \in I_{X}$, and for all real numbers $h$, the triangle $\left[A B C, A_{i} B_{i} C_{i}, v[h]\right]$ is $\left(\mathcal{A}, \gamma_{X}\right)$-generating.

Theorem 6. For $X=K, J, F$, for any $i \in I_{X}$, and for all $j, j^{\prime}=1, \ldots, n_{X}$ the triangles

$$
\begin{aligned}
& {\left[A B C,\left[A B C, A_{i} B_{i} C_{i}, v[h]\right], X_{j}[k]\right],} \\
& {\left[A B C,\left[A B C, A_{i} B_{i} C_{i}, X_{j}[h]\right], v[k]\right],} \\
& {\left[A B C,\left[A B C, A_{i} B_{i} C_{i}, X_{j^{\prime}}[h]\right], X_{j}[k]\right],}
\end{aligned}
$$

are $\left(\mathscr{A}, \gamma_{X}\right)$-generating for all real values of constants $h$ and $k$ except exactly one value of either h or $k$. The matrices of exceptions are similar to the matrices $M_{K}$, $M_{J}$, and $M_{F}$ from the Theorem 2.

An important source of $\left(\mathscr{A}, \gamma_{X}\right)$-generating triangles is the following general result.

THEOREM 7. Let $Q \in W(A B C)$ be a point different from the orthocentre $H$. The antipedal triangle $Q^{a} Q^{b} Q^{c}$ of $Q$ with respect to $A B C$ is orthologic with the triangle $P^{a} P^{b} P^{c}$ if and only if $P$ lies on a conic through the points $A, B, C, H$, and $Q$.

Corollary. For $X=K, J, F$, the antipedal triangle $Q^{a} Q^{b} Q^{c}$ with respect to $A B C$ of any point $Q$ on the hyperbola $\gamma_{X}$ outside the circumcircle $\gamma_{0}$ and different from the orthocentre $H$ is $\left(\mathscr{A}, \gamma_{X}\right)$-generating.

The next result can also be useful in search for $\left(\mathscr{A}, \gamma_{X}\right)$-generating triangles.
Theorem 8. For $X=F, J, K$, if $D E F$ is a $\left(\mathscr{A}, \gamma_{X}\right)$-generating in $W(A B C)$, then triangles
$[A B C, D E F, v[h]]$ and $\left[A B C, D E F, X_{i}[h]\right]$
$\left(i=1, \ldots, n_{X}\right)$ are also $\left(\Omega, \gamma_{X}\right)$-generating for all real numbers $h$ with at most one exception.

## 4. Preliminaries for proofs

Let us first determine the affixes of points $P^{a}, P^{b}$, and $P^{c}$. Since the affix of $A$ is $u$ and the affix of $P$ is $p$, the line $A P$ is $\left[1-u q, u(p-u), u^{2} q-p\right]$, where $q$ is a complex conjugate of $p$. The lines $B P$ and $C P$ are relatives of $A P$. It follows that the perpendicular $\operatorname{per}_{A}$ at $A$ to $A P$ is $\left[1-u q, u(u-p), u^{2} q+p-2 u\right]$, while the perpendiculars per $_{B}$ and $\operatorname{per}_{C}$ at $B$ and $C$ to $B P$ and $C P$ are its relatives. The intersection of $\operatorname{per}_{B}$ and $p e r_{C}$ is a point $P^{a}$ with affix $n_{a}^{*}\left[\mu_{a}(p q-2)+p\left(\zeta_{a}-p\right)\right]$, where $n_{a}=p+\mu_{a} q-\zeta_{a}$. The affixes of $P^{b}$ and $P^{c}$ are relatives of the affix of $P^{a}$.

Recall that points $P^{a}, P^{b}, P^{c}$ coincide if and only if the point $P$ lies on the circumcircle $\gamma_{0}$ with the equation $p q-1=0$.

THEOREM 9. Triangles $X Y Z$ and $P Q R$ with affixes of vertices $x, y, z, p, q$, and $r$ are orthologic if and only if $(X Y Z, P Q R)=0$, where

$$
(X Y Z, P Q R)=\mathbb{S}[x(\bar{q}-\bar{r})+\bar{x}(q-r)] .
$$

Proof. The line $Q R$ is $[\bar{q}-\bar{r}, r-q, q \bar{r}-\bar{q} r]$ so that the perpendicular $\operatorname{per}_{Q R}^{X}$ through $X$ onto $Q R$ is the line $[\bar{q}-\bar{r}, q-r, x(\bar{r}-\bar{q})+\bar{x}(r-q)]$. The perpendiculars $\operatorname{per}_{R P}^{Y}$ and $\operatorname{per}_{P Q}^{Z}$ through $Y$ and $Z$ onto $R P$ and $P Q$ are relatives of $p e r_{Q R}^{X}$. These three perpendiculars are concurrent if and only if $\Theta=0$, where $\Theta$ denotes the determinant

$$
\left|\begin{array}{ccc}
\bar{q}-\bar{r} & q-r & x(\bar{r}-\bar{q})+\bar{x}(r-q) \\
\bar{r}-\bar{p} & r-p & y(\bar{p}-\bar{r})+\bar{y}(p-r) \\
\bar{p}-\bar{q} & p-q & z(\bar{q}-\bar{p})+\bar{z}(q-p)
\end{array}\right| .
$$

But, $\Theta=(X Y Z, P Q R) m$, where $m=p(\bar{q}-\bar{r})+q(\bar{r}-\bar{p})+r(\bar{p}-\bar{q})$. Since $m=0$ if and only if points $P, Q$, and $R$ are collinear (and our assumptions exclude this possibility), we conclude that the triangles $X Y Z$ and $P Q R$ are orthologic if and only if $(X Y Z, P Q R)=0$.

Let us observe that the condition for orthology of two triangles in both barycentric and trilinear coordinates is very complicated because it involves eighteen coordinates of vertices of these triangles. This is the main reason why we are making all calculations with complex numbers.

## 5. Proof of Theorem 1 for $X=K$ and $i=1$

Since triangles $A B C$ and $P Q R$ are homothetic, there is a point $T(x, y)$ and a real number $\xi \neq-1$ such that $\widetilde{P}=\eta(u+\xi x), \widetilde{Q}=\varphi(\widetilde{P})$, and $\widetilde{R}=\psi(\widetilde{P})$, where $\eta=(\xi+1)^{*}$.

Let $h$ be a real number. Let $U, V$, and $W$ be vertices of the triangle $[A B C, P Q R$, $\left.K_{1}[h]\right]$. Then $\widetilde{U}=\widetilde{P}+I h(v-w)$, where $I=\sqrt{-1}$. Also, $\widetilde{V}=\varphi(\widetilde{U})$ and $\widetilde{W}=\psi(\widetilde{U})$.

Since

$$
\Delta(U, V, W)=\left|\begin{array}{ccc}
\eta(u+\xi x)+I h \delta_{a} & u^{*} \eta(1+\xi u y)+I h \delta_{a} \mu_{a}^{*} & 1 \\
\eta(v+\xi x)+I h \delta_{b} & v^{*} \eta(1+\xi v y)+I h \delta_{b} \mu_{b}^{*} & 1 \\
\eta(w+\xi x)+I h \delta_{c} & w^{*} \eta(1+\xi w y)+I h \delta_{c} \mu_{c}^{*} & 1
\end{array}\right|
$$

has up to a constant factor the form

$$
\left(h-\frac{I \eta(\sigma \tau-9 \mu)}{3 \mathbb{P} \delta_{a}}\right)^{2}+\frac{4 \eta^{2}\left(\tau^{2}-3 \mu \sigma\right)\left(\sigma_{2}-\tau\right)}{9 \mathbb{P} \delta_{a}^{2}}
$$

it follows that points $U, V$, and $W$ will not be collinear if and only if $h$ is different from

$$
\frac{s_{2} \pm 2 \sqrt{s_{4}-t_{2}}}{12 S(\xi+1)}
$$

Then $\left(P^{a} P^{b} P^{c}, U V W\right)=4 I h j_{K} j_{0} \mathbb{P} u^{*} n_{a}^{*}$, where $j_{0}=1-p q$ and

$$
\begin{aligned}
j_{K}=\left(\tau^{2}-3 \mu \sigma\right) p^{2}-\mu^{2}\left(\sigma^{2}-3 \tau\right) q^{2} & +\left(4 \mu \sigma^{2}-\sigma \tau^{2}-3 \mu \tau\right) p \\
& -\mu\left(4 \tau^{2}-\sigma^{2} \tau-3 \mu \sigma\right) q+\tau^{3}-\mu \sigma^{3}
\end{aligned}
$$

Notice that $j_{0}=0$ is the equation of the circumcircle of $A B C$ while $j_{K}=0$ is the equation of the Kiepert hyperbola of $A B C$ since the vertices $A\left(u, u^{*}\right), B\left(v, v^{*}\right)$, and $C\left(w, w^{*}\right)$, the orthocenter $H\left(\sigma, \tau \mu^{*}\right)$, and the centroid $G\left(3^{*} \sigma, 3^{*} \tau \mu^{*}\right)$ satisfy it. This shows that $U V W$ is $\left(\mathscr{A}, \gamma_{K}\right)$-generating for all $h \neq 0$ except for at most two additional values of $h$ found above when points $U, V$, and $W$ are collinear.

The polynomial $j_{K}$ is rather complicated. When we transfer it to barycentric coordinates it becomes significantly shorter so that the equation of the Kiepert hyperbola is $m_{K}=0$, where $m_{K}=\mathbb{S} \delta_{a}\left(u^{2}-\mu_{a}\right) y z$ or $m_{K}=\mathbb{S} d_{2 a} y z$. The last form is simpler than the equation (5) in the excellent recent review article [6] on the Kiepert conics.

## 6. Proof of Theorem 1 for $X=J$ and $i=1$

We first determine $\widetilde{P}, \widetilde{Q}$, and $\widetilde{R}$ as above. Let $h$ be a real number. Let $U, V$, and $W$ be vertices of the triangle $\left[A B C, P Q R, J_{1}[h]\right]$. Then $\widetilde{U}=\widetilde{P}+I h v w(v-w)^{*}$, $\widetilde{V}=\varphi(\widetilde{U})$, and $\widetilde{W}=\psi(\widetilde{U})$.

Notice that points $U, V$, and $W$ will not be collinear if and only if $h$ is different from

$$
\frac{m\left(3 m \pm \sqrt{3 m_{2}-\mathbb{S} a^{4} s_{2 a}}\right)}{4 S(\xi+1) s_{2}}
$$

This follows from the fact that

$$
\Delta(U, V, W)=\left|\begin{array}{ccc}
\eta(u+\xi x)+I h \delta_{a}^{*} \mu_{a} & u^{*} \eta(1+\xi u y)+I h \delta_{a}^{*} & 1 \\
\eta(v+\xi x)+I h \delta_{b}^{*} \mu_{b} & v^{*} \eta(1+\xi v y)+I h \delta_{b}^{*} & 1 \\
\eta(w+\xi x)+I h \delta_{c}^{*} \mu_{c} & w^{*} \eta(1+\xi w y)+I h \delta_{c}^{*} & 1
\end{array}\right|
$$

has up to a constant factor the form

$$
\left(h+\frac{3 I \eta\langle 0,1,-1\rangle}{\langle 6,1,1\rangle}\right)^{2}+\eta^{2} \sigma \tau \mathbb{P} \delta_{a}^{2}
$$

Then $\left(P^{a} P^{b} P^{c}, U V W\right)=2 I h j_{J} j_{0} \mathbb{P} n_{a}^{*}$, where

$$
j_{J}=\sigma p^{2}-\mu \tau q^{2}+\left(\tau-\sigma^{2}\right) p+\left(\tau^{2}-\mu \sigma\right) q
$$

The equation of the Jarabek hyperbola of $A B C$ is $j_{J}=0$ since the vertices $A, B$, and $C$, the orthocenter $H$, and the circumcenter $O(0,0)$ satisfy it.

The polynomial $j_{J}$ which represents the Jarabek hyperbola is quite simple so that its forms in other coordinate systems do not lead to significant simplifications. For completeness, let us observe that in barycentric coordinates the equation of the Jarabek hyperbola is $m_{J}=0$, where $m_{J}=\mathbb{S} u \delta_{a}^{2} \zeta_{a}\left(u^{2}-\mu_{a}\right) y z$ or $m_{J}=\mathbb{S} a^{2} d_{2 a} s_{2 a} y z$.

## 7. Proof of Theorem 1 for $X=F$ and $i=1$

In contrast with the previous two sections, in order to avoid square roots, here we shall assume that the vertices $A, B$, and $C$ of the base triangle have affixes $u^{2}, v^{2}$, and $w^{2}$, with the same assumption about $u, v$, and $w$. Let $\varrho$ denote a transformation which replaces variables $u, v$, and $w$ with $u^{2}, v^{2}$, and $w^{2}$.

This time $\widetilde{P}=(\xi+1)^{*}\left(u^{2}+\xi x\right), \widetilde{Q}=\varphi(\widetilde{P})$, and $\widetilde{R}=\psi(\widetilde{P})$. Let $h$ be a real number. Let $U, V$, and $W$ be vertices of the triangle $\left[A B C, P Q R, F_{1}[h]\right]$. Then $\widetilde{U}=\widetilde{P}+h v w, \widetilde{V}=\varphi(\widetilde{U})$, and $\widetilde{W}=\psi(\widetilde{U})$.

Since

$$
\Delta(U, V, W)=\left|\begin{array}{ccc}
\eta\left(u^{2}+\xi x\right)+h \mu_{a} & \frac{\eta\left(1+\xi u^{2} y\right)}{u^{2}}+h \mu_{a}^{*} & 1 \\
\eta\left(v^{2}+\xi x\right)+h \mu_{b} & \frac{\eta\left(1+\xi v^{2} y\right)}{v^{2}}+h \mu_{b}^{*} & 1 \\
\eta\left(w^{2}+\xi x\right)+h \mu_{c} & \frac{\eta\left(1+\xi w^{2} y\right)}{w^{2}}+h \mu_{c}^{*} & 1
\end{array}\right|
$$

has up to a constant factor the form $(h+\eta)^{2}-\eta^{2} \mu^{*} \sigma \tau$, it follows that points $U$, $V$, and $W$ will not be collinear if and only if $h$ is different from

$$
\frac{m \pm \sqrt{m\left(s^{3}-4 m t+9 m\right)}}{4 S(\xi+1)}
$$

Then $\left(P^{a} P^{b} P^{c}, U V W\right)=2 h j_{F} j_{0} \mathbb{P} \delta_{a} u^{*} \varrho\left(n_{a}\right)^{*}$, where
$j_{F}=\tau p^{2}-\mu_{3} \sigma q^{2}+\left(\mu \sigma+2 \mu \sigma^{2}-\sigma^{2} \tau\right) p+\mu\left(\sigma \tau^{2}-2 \sigma^{2} \mu-\mu \tau\right) q+\tau^{3}-\sigma^{3} \mu$.
Observe that $j_{F}=0$ is the equation of the Feuerbach hyperbola of $A B C$ since the vertices $A\left(u^{2}, 1 / u^{2}\right), B\left(v^{2}, 1 / v^{2}\right)$, and $C\left(w^{2}, 1 / w^{2}\right)$, the orthocenter $H\left(\varrho\left(\sigma, \tau \mu^{*}\right)\right)$, and the incenter $I\left(-\tau,-\sigma \mu^{*}\right)$ satisfy it.

Just as with the Kiepert hyperbola, the polynomial $j_{F}$ which represents the Feuerbach hyperbola is rather complicated. In barycentric and trilinear coordinates its equations are far simpler. More precisely, in barycentric coordinates the Feuerbach hyperbola has the equation $m_{F}=0$, where $m_{F}=\mathbb{S} u \delta_{a}^{2} \zeta_{a}\left(u^{2}-\mu_{a}\right) y z$ or $m_{F}=\mathbb{S} a d_{a} s_{a} y z$.

## 8. Proof of Theorem 2 for $X=K, i=1$, and $j=5$

Let $U V W=\left[A B C, P Q R, K_{1}[h]\right]$ and $L M N=\left[A B C, U V W, K_{5}[k]\right]$. We know $\widetilde{U}, \widetilde{V}$, and $\widetilde{W}$ from the proof of Theorem 1 , so that it is not difficult to see that $\widetilde{L}=\widetilde{U}+I k \delta_{a}^{3} \mu_{a}^{*}, \widetilde{M}=\varphi(\widetilde{L})$, and $\widetilde{N}=\psi(\widetilde{L})$.

Let us note that there exist at most two values of $k$ when points $L, M$, and $N$ are collinear. These values have rather complicated form.

The orthology condition for triangles $P^{a} P^{b} P^{c}$ and $L M N$ is

$$
\left(P^{a} P^{b} P^{c}, L M N\right)=2 I(\langle 6,1,1\rangle k+2 \mu h) j_{K} j_{0} \mu_{2}^{*} \mathbb{P} n_{a}^{*},
$$

This shows that $L M N$ is $\left(\mathscr{A}, \gamma_{K}\right)$-generating for all $k$ except the value $-2 h s_{2}^{*}$ and at most two more values for which points $L, M$, and $N$ are collinear.

## 9. Proof of Theorem 3 for $X=K$ and $i=1$

Let $U V W=[A B C, P Q R, v[h]]$ and $L M N=\left[A B C, U V W, K_{1}[k]\right]$. It is easy to check that $\widetilde{U}=\widetilde{P}+I h \zeta_{a} \mu^{*} \mathbb{P} \delta_{a}, \widetilde{V}=\varphi(\widetilde{U})$, and $\widetilde{W}=\psi(\widetilde{U})$. It follows that $\widetilde{L}=\widetilde{U}+I k \delta_{a}, \widetilde{M}=\varphi(\widetilde{L})$, and $\widetilde{N}=\psi(\widetilde{L})$. Once again there exist at most two values of $k$ when points $L, M$, and $N$ are collinear. These values have complicated expressions in terms of side lengths. Finally, $\left(P^{a} P^{b} P^{c}, L M N\right)=4 I k j_{K} j_{0} \mu^{*} \mathbb{P} n_{a}^{*}$.

## 10. Proof of Theorem $\mathbf{5}$ for $X=F$ and $i=e$

Assume $\widetilde{A}=u^{2}, \widetilde{B}=v^{2}$, and $\widetilde{C}=w^{2}$. Recall [14] that $\widetilde{A_{e}}=\tau_{a}, \widetilde{B_{e}}=\tau_{b}$, and $\widetilde{C_{e}}=\tau_{c}$. Let $U, V, W$ denote vertices of the triangle $\left[A B C, A_{e} B_{e} C_{e}, v[h]\right]$. It is easy to check that $\widetilde{U}=\tau_{a}+I h \zeta_{2 a} \mu_{2}^{*} \mathbb{P} \delta_{2 a}, \widetilde{V}=\varphi(\widetilde{U})$, and $\widetilde{W}=\psi(\widetilde{U})$.

Once again there exist at most two values of $h$ when points $U, V$, and $W$ are collinear. These are $2^{*} S^{*}\left(-m \pm \sqrt{m\left(s^{3}-4 s t+9 m\right)}\right) \mathbb{P} s_{a}^{*}$. Finally, $\left(P^{a} P^{b} P^{c}\right.$, $U V W)$ is equal to $4 j_{F} j_{0} \mu^{*} \mathbb{P} \delta_{a} \varrho\left(n_{a}\right)^{*}$.

## 11. Proof of Theorem 7

Let $\widetilde{Q}=(x, y)$. Then $\widetilde{Q^{a}}=\left(\mu_{a} x y-x^{2}+\zeta_{a} x-2 \mu_{a}\right)\left(x+\mu_{a} y-\zeta_{a}\right)^{*}, \widetilde{Q^{b}}=$ $\varphi\left(\widetilde{Q^{a}}\right)$, and $\widetilde{Q^{c}}=\psi\left(\widetilde{Q^{a}}\right)$. It follows that $\left(P^{a} P^{b} P^{c}, Q^{a} Q^{b} Q^{c}\right)=4(x y-1) j_{Q j_{0}} \mathbb{P} \delta_{a} n_{a}^{*}(x$ $\left.+\mu_{a} y-\zeta_{a}\right)^{*}$, where $j_{Q}=a p^{2}+b q^{2}+c p+d q+e$,

$$
\begin{aligned}
& a=\mu y^{2}-x-\tau y+\sigma, b=\mu\left(\sigma x-x^{2}+\mu y-\tau\right), c=x^{2}-\mu \sigma y^{2}+\zeta_{a} \zeta_{b} \zeta_{c} y-\sigma_{2}-\tau \\
& d=\tau x^{2}-\zeta_{a} \zeta_{b} \zeta_{c} x-\mu_{2} y^{2}+\tau_{2}+\mu \sigma, \quad e=\left(\sigma_{2}+\tau\right) x-\sigma x^{2}+\mu \tau y^{2}-\left(\tau_{2}+\mu \sigma\right) y .
\end{aligned}
$$

It is obvious that $j_{Q}=0$ is an equation of a conic. One can easily check that it goes through $A, B, C, H$, and $Q$.

## 12. Outline of proof of Theorem 8

Let $\widetilde{D}=(x, a), \widetilde{E}=(y, b)$, and $\widetilde{F}=(z, c)$. The expression $\left(P^{a} P^{b} P^{c}, D E F\right)$ has two major factors. The first is $j_{0}$ (the equation of the circumcircle). The second is the polynomial of degree two in $p$ and $q$. We assume that its coefficients are equal to the product of a constant with corresponding coefficients of the polynomial representing $\gamma_{X}$. This gives six equations for variables $x, a, y, b, z, c$. Let the solutions have index 0 and let $\widetilde{D_{0}}=x_{0}, \ldots$. Finally, we check that the triangles

$$
\left[A B C, D_{0} E_{0} F_{0}, v[h]\right] \quad \text { and } \quad\left[A B C, D_{0} E_{0} F_{0}, X_{i}[h]\right]
$$

$\left(i=1, \ldots, n_{X}\right)$ are $\left(\mathscr{A}, \gamma_{X}\right)$-generating for all real numbers $h$ except at most one value.

## 13. Concluding remarks and an introduction to the appendix

A careful reader should have noticed that we gave proofs of a very few of our results and that no case of both Theorems 4 and 6 was proved. One reason for this is that even with complex numbers we quickly get rather complicated expressions with lots of absolute values that are difficult to handle and hard to write down. In order to overcome these difficulties we must position a base triangle $A B C$ so that lengths of sides are rational functions of three parameters. Only in this way we can avoid square-root and absolute value functions that are creating problems.

In an appendix to this paper we shall describe how one can (with the help from a computer) do all this calculations using only elementary analytic geometry in the plane. We shall limit ourselves to proofs of a few cases of Theorems 4 and 6 hoping that the reader will be able to infer proofs of all our claims following the same technique.

## 14. Appendix - Preliminaries

For an expression $f$, let $[f]$ denote a triple $(f, \varphi(f), \psi(f))$, where $\varphi(f)$ and $\psi(f)$ are cyclic permutations of $f$. For example, if $f=\sin A$ and $g=b+c$, then

$$
[f]=(\sin A, \sin B, \sin C) \quad \text { and } \quad[g]=(b+c, c+a, a+b) .
$$

Let $T$ denote a function that maps each triple $[a]$ of real numbers to a number

$$
T([a])=(a+b+c)(b+c-a)(a-b+c)(a+b-c) .
$$

We shall position the triangle $A B C$ in the following fashion with respect to the rectangular coordinate system in order to simplify our calculations. The vertex $A$ is the origin with coordinates $(0,0)$, the vertex $B$ is on the $x$-axis and has coordinates ( $r e, 0$ ), and the vertex $C$ has coordinates ( $g q r / w, 2 f g r / w$ ), where $e=f+g$, w $=f g-1, p=f^{2}+1, q=f^{2}-1, s=g^{2}+1, t=g^{2}-1$, $u=f^{4}+1$, and $v=g^{4}+1$. The three parameters $r, f$, and $g$ are the inradius and the cotangents of half of angles at vertices $A$ and $B$. Without loss of generality, we can assume that both $f$ and $g$ are larger than 1 (i. e., that angles $A$ and $B$ are acute).

Nice features of this placement are that all central points from Table 1 in [10] have rational functions in $f, g$, and $r$ as coordinates and that we can easily switch from $f, g$, and $r$ to side lengths $a, b$, and $c$ and back with substitutions

$$
\begin{gathered}
a=\frac{r f s}{w}, \quad b=\frac{r g p}{w}, \quad c=r e \\
f=\frac{(b+c)^{2}-a^{2}}{\sqrt{T([a])}}, \quad g=\frac{(a+c)^{2}-b^{2}}{\sqrt{T([a])}}, \quad r=\frac{\sqrt{T([a])}}{2(a+b+c)} .
\end{gathered}
$$

Moreover, since we use the Cartesian coordinate system, computation of distances of points and all other formulas and techniques of analytic geometry are available and well-known to widest audience. A price to pay for these conveniences is that symmetry has been lost.

The third advantage of the above position of the base triangle is that we can easily find coordinates of a point with given trilinears. More precisely, if a point $P$ with coordinates $x$ and $y$ has projections $P_{a}, P_{b}$, and $P_{c}$ onto the side lines $B C, C A$, and $A B$ and $\lambda=P P_{a} / P P_{b}$ and $\mu=P P_{b} / P P_{c}$, then

$$
x=\frac{e g(p \mu+q) r}{f s \lambda \mu+g p \mu+e w}, \quad y=\frac{2 e f g r}{f s \lambda \mu+g p \mu+e w} .
$$

This formulas will greatly simplify our exposition because there will be no need to give explicitly coordinates of points but only its first trilinear coordinate. For example, we write $X_{6}[a]$ to indicate that the symmedian point $X_{6}$ has trilinears equal to $a: b: c$. Then we use the above formulas with $\lambda=a / b$ and $\mu=b / c$ to get the coordinates

$$
\left(\frac{(f q t+2 g u) e g r}{2\left(f^{2} v+f g q s+g^{2} u\right)}, \frac{f g e^{2} w r}{f^{2} v+f g q s+g^{2} u}\right)
$$

of $X_{6}$ in our coordinate system.
Let $U V W$ denote a function which to a triple $(P, Q, R)$ of points $P\left(x, x^{\prime}\right)$, $Q\left(y, y^{\prime}\right)$, and $R\left(z, z^{\prime}\right)$ and a triple $\left(h_{a}, h_{b}, h_{c}\right)$ of real numbers associates a triple $(U, V, W)$ of points, where

$$
U\left(x+\frac{2 g h_{a}}{s}, x^{\prime}+\frac{t h_{a}}{s}\right), \quad V\left(y-\frac{2 f h_{b}}{p}, y^{\prime}+\frac{q h_{b}}{p}\right), \quad W\left(z, z^{\prime}-h_{c}\right)
$$

On the other hand, for triangles $P Q R$ and $X Y Z$, let $O R(P Q R, X Y Z)$ be the sum

$$
\mathbb{S}\left[p(y-z)+p^{\prime}\left(z^{\prime}-y^{\prime}\right)\right]
$$

where $P\left(p, p^{\prime}\right), Q\left(q, q^{\prime}\right), R\left(r, r^{\prime}\right), X\left(x, x^{\prime}\right), Y\left(y, y^{\prime}\right)$, and $Z\left(z, z^{\prime}\right)$. Observe that triangles $P Q R$ and $X Y Z$ are orthologic if and only if $O R(P Q R, X Y Z)=0$.

Let $P(x, y)$ be a point. Then the vertices of the antipedal triangle $P^{a} P^{b} P^{c}$ are

$$
\begin{gathered}
P^{a}\left(\frac{2 g w y^{2}-w t x y+2 r g e w x+r(2 w+s)(f t-2 g) y-2 r^{2} g e^{2} w}{w(2 g x+t y-2 r g e)}\right. \\
\left.\frac{(r e-x)\left(2 g w y-t w x+r g\left(w^{2}-e^{2}\right)\right)}{w(2 g x+t y-2 r g e)}\right), \\
P^{b}\left(\frac{\left(w q x+2 f w y-r g p^{2}\right) y}{w(q y-2 f x)}, \frac{\left(w q x+2 f w y-r g p^{2}\right) x}{w(q y-2 f x)}\right) \\
P^{c}\left(r e-x, \frac{x^{2}-r e x}{y}\right)
\end{gathered}
$$

## 15. Appendix - Proof of Theorem 4 for $X=K$ and $j=1$

Since triangles $A B C$ and $P Q R$ are homothetic, there is a point $T(\bar{x}, \bar{y})$ and a real number $\xi$ different from -1 such that with $\eta=(\xi+1)^{*}$, $P(\eta \xi \bar{x}, \eta \xi \bar{y}), Q(\eta(\xi \bar{x}+e r), \eta \xi \bar{y}), R\left(\eta\left(\xi \bar{x}+g w^{*} q r\right), \eta\left(\xi \bar{y}+2 f g w^{*} r\right)\right)$.

Let $h$ be a real number. Let $(U, V, W)=U V W\left(P, Q, R, K_{1}[h]\right)$. Then $U$, $V$, and $W$ are vertices of the triangle $\left[A B C, P Q R, K_{1}[h]\right]$. Since $K_{1}[h]=\left(f h r s w^{*}\right.$, ghprw* ${ }^{*}$ ehr $)$, it follows that $U\left(P_{x}+2 f g h r w^{*}, P_{y}+f h r t w^{*}\right), W\left(R_{x}, R_{y}-e h r\right)$, and $V\left(Q_{x}-2 f g h r w^{*}, Q_{y}+g h q r w^{*}\right)$, where $P_{x}$ and $P_{y}$ denote the first and the second coordinate of $P$.

Let $k$ be a real number. Let $(L, M, N)=U V W(U, V, W, v[k])$. Then $L, M$, and $N$ are vertices of the triangle $[A B C, U V W, v[k]]$. Since $v[k]=2 e f g k r^{3} w^{* 2}(q s, p t$, $e^{2}-w^{2}$ ), it follows that

$$
\begin{gathered}
L\left(U_{x}+4 e f g^{2} k q r^{3} w^{* 2}, U_{y}+2 e f g k q r^{3} t w^{* 2}\right) \\
M\left(V_{x}-4 e f^{2} g k r^{3} t w^{* 2}, V_{y}+2 e f g k q r^{3} t w^{* 2}\right) \\
\quad N\left(W_{x}, W_{y}+2 e f g k r^{3}\left(w^{2}-e^{2}\right) w^{* 2}\right)
\end{gathered}
$$

The orthology condition is $O R\left(P^{a} P^{b} P^{c}, L M N\right)=h m_{0} m_{K} q_{a}^{*} q_{b}^{*} y^{*} w^{* 2}$, where $q_{a}=2 g(e r-x)-t y, q_{b}=q y-2 f x, m_{0}=2 w\left(x^{2}+y^{2}\right)-2 e r w x+r\left(w^{2}-e^{2}\right) y$,

$$
\begin{aligned}
& m_{K}=2 f g(f-g)(w+2)\left(x^{2}-e r x-y^{2}\right)- \\
& \quad 2\left(g^{2} u+f g q t+f^{2} t^{2}-6 f^{2} g^{2}\right) x y+e g r\left(2 g u+f q t-8 f^{2} g\right) y
\end{aligned}
$$

Notice that $m_{0}=0$ is the equation of the circumcircle of $A B C$ because it is equivalent to the equation $\left(x-2^{*} e r\right)^{2}+\left(y+4^{*}\left(w^{2}-e^{2}\right) r w^{*}\right)^{2}-16^{*} p^{2} r^{2} s^{2} w^{* 2}=0$ of the circle with center at the circumcenter $O\left(2^{*} e r,-4^{*}\left(w^{2}-e^{2}\right) r w^{*}\right)$ and the radius equal to the circumradius $4^{*} p r s w^{*}$. Also, $m_{K}=0$ is the equation of the Kiepert hyperbola of $A B C$ since the vertices $A(0,0), B(e h, 0)$, and $C\left(g q r w^{*}, 2 f g r w^{*}\right)$, the orthocenter $H\left(g q r w^{*}, 2^{*} q r t w^{*}\right)$, and the centroid $G\left(3^{*} r(f t+2 g q), 3^{*} 2 f g r w^{*}\right)$ satisfy it. This shows that $L M N$ is $\left(\mathscr{A}, \gamma_{K}\right)$-generating for all real numbers $h \neq 0$ and $k$.

## 16. Appendix - Proof of Theorem 4 for $X=J$ and $j=2$

We first determine $P, Q$, and $R$ as above. Let $h$ be a real number. Let $U, V$, and $W$ be vertices of the triangle $\left[A B C, P Q R, J_{2}[h]\right]$. Since

$$
J_{2}[h]=2 h w\left((2 w+s)^{*},(2 w+p)^{*}, w^{*}(w+2)^{*}\right)
$$

it follows that $U\left(P_{x}+4 g h w s^{*}(2 w+s)^{*}, P_{y}+2 h t w s^{*}(2 w+s)^{*}\right)$,

$$
V\left(Q_{x}-4 f h w p^{*}(2 w+p)^{*}, Q_{y}+2 h q w p^{*}(2 w+p)^{*}\right), W\left(R_{x}, R_{y}-2 h(w+2)^{*}\right)
$$

Let $k$ be a real number. Let $(L, M, N)=U V W(U, V, W, v[k])$. Then $L, M$, and $N$ are vertices of the triangle [ABC, UVW,v[k]]. It follows that
$L\left(U_{x}+4 e f g^{2} k q r^{3} w^{* 2}, U_{y}+2 e f g k q r^{3} t w^{* 2}\right), N\left(W_{x}, W_{y}+2 e f g k\left(w^{2}-e^{2}\right) r^{3} w^{* 2}\right)$, and $M\left(V_{x}-4 e f^{2} g k r^{3} t w^{* 2}, V_{y}+2 e f g k q r^{3} t w^{* 2}\right)$.

The orthology condition is

$$
O R\left(P^{a} P^{b} P^{c}, L M N\right)=2 e f g h m_{0} m_{J} q_{a}^{*} q_{b}^{*} y^{*} w^{*}(w+2)^{*} p^{*} s^{*}(2 w+p)^{*}(2 w+s)^{*}
$$

where

$$
\begin{gathered}
m_{J}=2 w(w+2)(f-g)\left(w^{2}-e^{2}\right)\left(y^{2}+e r x-x^{2}\right)+w\left(2 g^{2} u+2 f^{2} v+20 f^{2} g^{2}-3 u v\right) x y \\
+r\left(2 g v\left(f^{6}-1\right)+f t^{3} u-2 f^{2}\left(v+4 g^{2}\right)(f t+g q)\right) y
\end{gathered}
$$

Observe that $m_{J}=0$ is the equation of the Jarabek hyperbola of $A B C$ since the vertices the orthocenter, and the circumcenter $O\left(2^{*} e r,-4^{*}\left(w^{2}-e^{2}\right) r w^{*}\right)$ satisfy it. This shows that $L M N$ is $\left(\mathscr{A}, \gamma_{J}\right)$-generating for all real numbers $h \neq 0$ and $k$.

## 17. Appendix - Proof of Theorem 4 for $X=F$ and $j=2$

We first determine $P, Q$, and $R$ as above. Let $h$ be a real number. Let $U V W$ be the triangle $\left[A B C, P Q R, F_{2}[h]\right]$. Since $F_{2}[h]=2^{*} r^{*} h\left(f^{*}, g^{*}\right.$, we $\left.e^{*}\right)$, it follows that

$$
U\left(P_{x}+f^{*} g h r^{*} s^{*}, P_{y}+2^{*} f^{*} h r^{*} s^{*} t\right), \quad V\left(Q_{x}-f g^{*} h p^{*} r^{*}, Q_{y}+2^{*} g^{*} h p^{*} q r^{*}\right)
$$

and $W\left(R_{x}, R_{y}-2^{*} e^{*} h r^{*} w\right)$.
Let $k$ be a real number. Let $(L, M, N)=U V W(U, V, W, v[k])$. Then $L, M$, and $N$ are vertices of the triangle $[A B C, U V W, v[k]]$. It follows that
$L\left(U_{x}+4 e f g^{2} k q r^{3} w^{* 2}, U_{y}+2 e f g k q r^{3} t w^{* 2}\right), \quad N\left(W_{x}, W_{y}+2 e f g k\left(w^{2}-e^{2}\right) r^{3} w^{* 2}\right)$,
and $M\left(V_{x}-4 e f^{2} g k r^{3} t w^{* 2}, V_{y}+2 e f g k q r^{3} t w^{* 2}\right)$. The orthology condition is

$$
2^{*}\left(e^{2}+f^{2} g^{2}-1\right) h m_{0} m_{F} p^{*} q_{a}^{*} q_{b}^{*} r^{*} s^{*} w^{*} y^{*}
$$

where

$$
m_{F}=2(f-g)\left(x^{2}-e r x-y^{2}\right)+(4-q-t+w(2-w)) x y+r(f q s-2 g p) y
$$

Observe that $m_{F}=0$ is the equation of the Feuerbach hyperbola of $A B C$ since the vertices, the orthocenter, and the incenter $I(f r, r)$ satisfy it. This shows that $L M N$ is $\left(\mathscr{A}, \gamma_{F}\right)$-generating for all real numbers $h \neq 0$ and $k$.

## 18. Appendix - Proof of Theorem 6 for $X=F, i=O i, j^{\prime}=1$, and $j=2$

An arbitrary point $X$ different from the circumcenter $O$ on the line $I O$ joining the incenter with the circumcenter can be represented as a point with coordinates

$$
X\left(2^{*} \eta r(e \xi+2 f),-4^{*} \eta r\left(\left(w^{2}-e^{2}\right) \xi-4 w\right) w^{*}\right)
$$

for a real number $\xi$ different from -1 , where $\eta=(\xi+1)^{*}$. Projections $P, Q$, and $R$ of $X$ onto the sidelines $B C, C A$, and $A B$ are

$$
\begin{gathered}
P\left(2^{*} \eta r s^{*} w^{*}(s(f t+2 g q) \xi+2(f s+2 g) w), \eta g r s^{*} w^{*}(f s \xi+2 g w)\right) \\
Q\left(2^{*} \eta(g p \xi+2 f w) p^{*} q r w^{*}, \eta f(g p \xi+2 f w) p^{*} r w^{*}\right), \quad R\left(2^{*} \eta r(e \xi+2 f), 0\right)
\end{gathered}
$$

Let $h$ be a real number. Let $(U, V, W)=U V W\left(P, Q, R, F_{1}[h]\right)$. Then $U, V$, and $W$ are vertices of the triangle $\left[A B C, P Q R, F_{1}[h]\right]$. It follows that

$$
U\left(P_{x}+2 g h s^{*}, P_{y}+h s^{*} t\right), \quad V\left(Q_{x}-2 f h p^{*}, Q_{y}+h q p^{*}\right), \quad W\left(R_{x},-h\right)
$$

where $P_{x}$ and $P_{y}$ denote the first and the second coordinate of $P$.
Let $k$ be a real number. Let $(L, M, N)=U V W\left(U, V, W, F_{2}[k]\right)$. Then $L, M$, and $N$ are vertices of the triangle [ $\left.A B C, U V W, F_{2}[k]\right]$. Hence,

$$
L\left(U_{x}+f^{*} g k r^{*} s^{*}, U_{y}+2^{*} f^{*} k r^{*} s^{*} t\right), \quad M\left(V_{x}-f g^{*} k p^{*} r^{*}, V_{y}+2^{*} g^{*} k p^{*} q r^{*}\right)
$$

and $N\left(W_{x}, W_{y}-2^{*} e^{*} k r^{*} w\right)$.
The orthology condition is $2^{*} \eta m_{0} m_{1} m_{F} p^{*} q_{a}^{*} q_{b}^{*} r^{*} s^{*} w^{*} y^{*}$, where

$$
m_{1}=(\xi+1)\left[4 e f g h r+\left(e^{2}+f^{2} g^{2}-1\right) k\right]+4 e f g r^{2}
$$

This shows that $L M N$ is $\left(\mathscr{A}, \gamma_{F}\right)$-generating for all real numbers $h$ and $k$ which satisfy the relation $m_{1} \neq 0$.

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