

# Structure-preserving low multilinear rank approximation of antisymmetric tensors

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Joint work with Daniel Kressner (EPF Lausanne)

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# OUTLINE

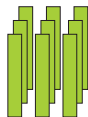
- Introduction
- Tensor decompositions and tensor rank
- Low multilinear rank approximation
- Jacobi method
- Multilinear rank  $d$  approximation

E. Begović Kovač, D. Kressner: Structure-preserving low multilinear rank approximation of antisymmetric tensors. arXiv:1603.05010 [math.NA]

# TENSORS - Basic concept and notation

- **Tensor** is multidimensional (finite) array
- **Order** of the tensor - dimension  $d$
- Matrix  $\mathbf{M}(i,j) \rightarrow$  Tensor  $\mathcal{T}(i_1, i_2, \dots, i_d)$
- **Fiber** - vector obtained by fixing all but one indices, i.e.  $\mathcal{T}(:, i_2, \dots, i_d)$

**Mode- $k$  fibers**



- **Slice** - matrix obtained by fixing all but two indices, i.e.  $\mathcal{T}(:, :, i_3, \dots, i_d)$



# ANTISYMMETRIC TENSORS

- Symmetric:  $\mathcal{X}(i_1, i_2, \dots, i_d) = \mathcal{X}(i_{\sigma(1)}, i_{\sigma(2)}, \dots, i_{\sigma(d)})$
- Antisymmetric tensor

$$\mathcal{A}(i_1, i_2, \dots, i_d) = (-1)^{|\sigma|} \mathcal{A}(i_{\sigma(1)}, i_{\sigma(2)}, \dots, i_{\sigma(d)})$$

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## Löwdin rules:

- (i)  $\mathcal{A}(i, j, k) = 0$ , if  $i = j$  or  $i = k$  or  $j = k$ ,
- (ii)  $\mathcal{A}(i, j, k) = \mathcal{A}(j, k, i) = \mathcal{A}(k, i, j)$   
 $= -\mathcal{A}(j, i, k) = -\mathcal{A}(k, j, i) = -\mathcal{A}(i, k, j)$ , otherwise.

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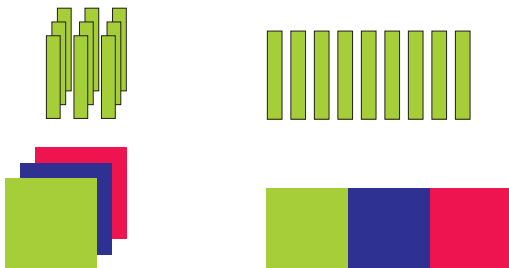
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- **Antisymmetrizer**  $\text{anti}(\mathcal{X})$  - projection on the space of antisymmetric tensors
- Applications: Quantum physics and quantum chemistry

# MATRICIZATION

- **Unfolding** (matricization/flattening) - matrix representation of the tensor

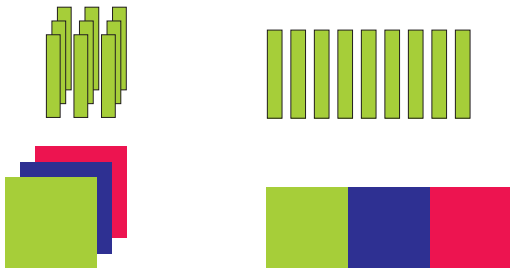
$$\mathcal{T} \in \mathbb{R}^{n_1 \times n_2 \times \dots \times n_d} \quad \dashrightarrow \quad \mathbf{T}_{(k)} \in \mathbb{R}^{n_k \times (n_1 \dots n_{k-1} n_{k+1} \dots n_d)}$$



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- Let  $\mathcal{A} \in \mathbb{R}^{n \times n \times \dots \times n}$  be an antisymmetric tensor of order  $d$ . Then

$$\mathbf{A}_{(k)} = (-1)^{|k-l|} \mathbf{A}_{(l)}, \quad 1 \leq k, l \leq d.$$



# MULTIPLICATION AND NORM

- **Mode- $k$  product**

$$\mathcal{X} \times_k \mathbf{M}$$

Property:

$$\mathcal{Y} = \mathcal{X} \times_k \mathbf{M} \quad \Leftrightarrow \quad \mathbf{Y}_{(k)} = \mathbf{M}\mathbf{X}_{(k)}$$

- $\mathcal{X} \in \mathbb{R}^{n_1 \times n_2 \times \dots \times n_d}$ , Frobenius norm

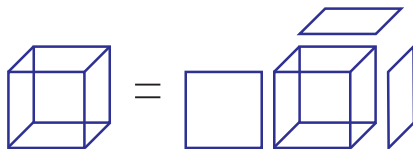
$$\|\mathcal{X}\|^2 = \sum_{i_1=1}^{n_1} \sum_{i_2=1}^{n_2} \dots \sum_{i_d=1}^{n_d} \mathcal{X}(i_1, i_2, \dots, i_d)^2$$

# TUCKER DECOMPOSITION AND HOSVD

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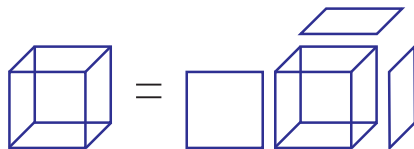
- Tucker (1966)  $\mathcal{X} = \mathcal{T} \times_1 \mathbf{M}_1 \times_2 \mathbf{M}_2 \times_3 \cdots \times_d \mathbf{M}_d$



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- **Higher order SVD** De Lathauwer et al. (2000)

$$\mathcal{X} = \mathcal{S} \times_1 \mathbf{U}_1 \times_2 \mathbf{U}_2 \times_3 \cdots \times_d \mathbf{U}_d,$$

where  $\mathcal{S} \in \mathbb{R}^{n_1 \times n_2 \times \cdots \times n_d}$  is core tensor, and  $\mathbf{U}_k \in \mathbb{R}^{n_k \times n_k}$  are unitary matrices,  $1 \leq k \leq d$ .

For  $d \geq 3$ ,  $\mathcal{S}$  is not a diagonal tensor!

# CP DECOMPOSITION

- Hitchcock (1927)
- CANDECOMP (canonical decomposition), Carroll and Chang (1970) / PARAFAC (parallel factors), Harshman (1970)



- **CP decomposition**,  $\mathcal{X} \in \mathbb{R}^{n_1 \times n_2 \times \dots \times n_d}$

$$\mathcal{X} \approx \sum_{j=1}^R x_1^{(j)} \circ x_2^{(j)} \circ \dots \circ x_d^{(j)},$$

with  $R \in \mathbb{N}$ ,  $x_k^{(j)} \in \mathbb{R}^{n_k}$ ,  $1 \leq k \leq d$ ,  $1 \leq j \leq R$ .

○ stands for the outer product,

$$\mathcal{T} = x \circ y \circ z \quad \Leftrightarrow \quad \mathcal{T}(i, j, k) = x(i)y(j)z(k).$$

# RANK AND MULTILINEAR RANK

- The smallest number  $R$  in the exact CP decomposition is called **tensor rank** (CP rank).
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- The smallest number  $R$  in the exact CP decomposition is called **tensor rank** (CP rank).
- There is no straightforward algorithm to determine the rank of a specific tensor. The problem is NP-hard.
- **Multilinear rank** of  $\mathcal{X} \in \mathbb{R}^{n_1 \times n_2 \times \cdots \times n_d}$  is  $d$ -tuple

$$(r_1, r_2, \dots, r_d), \quad \text{where } r_k = \text{rank}(\mathbf{X}_{(k)}), \quad 1 \leq k \leq d.$$

- If  $\mathcal{A}$  is antisymmetric, then  $r_1 = r_2 = \cdots = r_d = r$ .
- We say that  $\mathcal{A}$  has multilinear rank  $r$  and write  $\mathcal{A} \in \mathcal{M}_r$ .

# MULTILINEAR RANK - antisymmetric tensor

## Theorem (B., Kressner)

Let  $\mathcal{A} \in \mathbb{R}^{n \times n \times \dots \times n}$  be an antisymmetric tensor of order  $d \geq 3$ . Then the multilinear rank  $r$  of  $\mathcal{A}$  satisfies

- (i)  $r = 0$ , for  $n < d$ ;
- (ii)  $r \leq d$ , for  $n = d$  or  $n = d + 1$ ;
- (iii)  $r \leq n$ , for  $n \geq d + 2$ .

There exist tensors  $\mathcal{A}$  for which equality is attained in (i)–(iii).

## Corrolary (B., Kressner)

Let  $\mathcal{A} \in \mathbb{R}^{n \times n \times \dots \times n}$  be an antisymmetric tensor of order  $d \geq 3$ . Then the multilinear rank  $r$  of  $\mathcal{A}$  attains the values from the set

$$\{0, d, d + 2, \dots, n\}.$$



# LOW MULTILINEAR RANK APPROXIMATION

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- **Minimization problem:** For a given antisymmetric tensor  $\mathcal{A}$ , find an antisymmetric tensor  $\hat{\mathcal{A}} \in \mathcal{M}_r$ , such that

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- Dual **maximization problem** (De Lathauwer, 2000): find matrices  $\mathbf{U}_1, \mathbf{U}_2, \dots, \mathbf{U}_d$  with orthonormal columns, such that

$$\|\mathcal{A} \times_1 \mathbf{U}_1^T \times_2 \mathbf{U}_2^T \times_3 \cdots \times_d \mathbf{U}_d^T\|^2 \rightarrow \max.$$

Then,

$$\mathcal{S} = \mathcal{A} \times_1 \mathbf{U}_1^T \times_2 \mathbf{U}_2^T \times_3 \cdots \times_d \mathbf{U}_d^T,$$

$$\hat{\mathcal{A}} = \mathcal{S} \times_1 \mathbf{U}_1 \times_2 \mathbf{U}_2 \times_3 \cdots \times_d \mathbf{U}_d.$$

$\mathcal{A}$  antisymmetric  $\rightarrow \mathbf{U}_1 = \cdots = \mathbf{U}_d$

# T-HOSVD and HOOI

- **Truncated HOSVD** ( $\sim 2000$ )
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- **Truncated HOSVD** ( $\sim 2000$ )
  - Direct method
  - Unlike T-SVD, does not give the best approximation
  - Gives a good starting point for iterative algorithms
  
- **Higher order orthogonal iterations** ( $\sim 2006$ )
  - ALS algorithm,  
in each microiteration one matrix  $\mathbf{U}_k$ ,  $1 \leq k \leq d$ , is updated
  - In practice, converges to the stationary point

# JACOBI METHOD

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**Idea:** Apply Jacobi rotations in order to maximize the norm of  $(r, r, \dots, r)$ -subtensor with smallest indices. (Ishteva et al., 2013)

Jacobi rotations are  $n \times n$  matrices

$$R(i, j, \phi) = \begin{bmatrix} 1 & & & & & & & & & \\ & \ddots & & & & & & & & \\ & & 1 & & & & & & & \\ & & & \cos \phi & & & & & & \\ & & & & 1 & & & & & \\ & & & & & \ddots & & & & \\ & & & & & & 1 & & & \\ & & \sin \phi & & & & & \cos \phi & & \\ & & & & & & & & 1 & \\ & & & & & & & & & \ddots \\ & & & & & & & & & & 1 \end{bmatrix},$$

where  $(i, j) = (i(k), j(k))$  is called the  $k$ -th pivot pair.

## JACOBI METHOD - Algorithm

$$\|\mathcal{A} \times_1 \mathbf{U}^T \times_2 \mathbf{U}^T \times_3 \cdots \times_d \mathbf{U}^T\|^2 \rightarrow \max.$$

For the sake of simplicity, assume  $d = 3$ ,  $\mathcal{A} \in \mathbb{R}^{n \times n \times n}$ .

For  $\mathbf{Q}$  orthogonal and  $M = \begin{bmatrix} I_r & 0 \\ 0 & 0 \end{bmatrix}$ , let

$$f(\mathbf{Q}) = \|\mathcal{A} \times_1 \mathbf{M}\mathbf{Q}^T \times_2 \mathbf{M}\mathbf{Q}^T \times_3 \mathbf{M}\mathbf{Q}^T\|^2$$

**Maximization problem:**  $f(\mathbf{Q}) \rightarrow \max.$



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REPEAT

Choose  $(i(k), j(k))$ .

Find  $\phi$ .

$$R_k = R(i(k), j(k), \phi(k))$$

$$Q_{k+1} = Q_k R_k$$

$$\mathcal{A}_{k+1} = \mathcal{A}_k \times_1 R_k^T \times_2 R_k^T \times_3 R_k^T$$

UNTIL convergence

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# JACOBI METHOD - Convergence

- **Pivot pairs**  $(i, j)$  are taken from the set

$$(1, r + 1), (1, r + 2), \dots, (1, n), (2, r + 1), \dots, (r, n).$$

- **Rotation angle**  $\phi$  maximizes

$$\psi(\phi) = \sum_{p,q=1}^r (\mathcal{A}(i, p, q) \cos \phi + \mathcal{A}(j, p, q) \sin \phi)^2.$$

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## Theorem (B., Kressner)

Let  $(\mathbf{Q}_k)_k$  be a sequence of orthogonal matrices obtained by the Jacobi algorithm with  $\mathcal{A} \in \mathbb{R}^{n \times n \times \dots \times n}$  antisymmetric. Every accumulation point of  $(\mathbf{Q}_k)_k$  is a stationary point of function  $f(\mathbf{Q}) = \|\mathcal{A} \times_1 \mathbf{M}\mathbf{Q}^T \times_2 \mathbf{M}\mathbf{Q}^T \times_3 \mathbf{M}\mathbf{Q}^T\|^2$ .

## Numerical examples - Approximation error

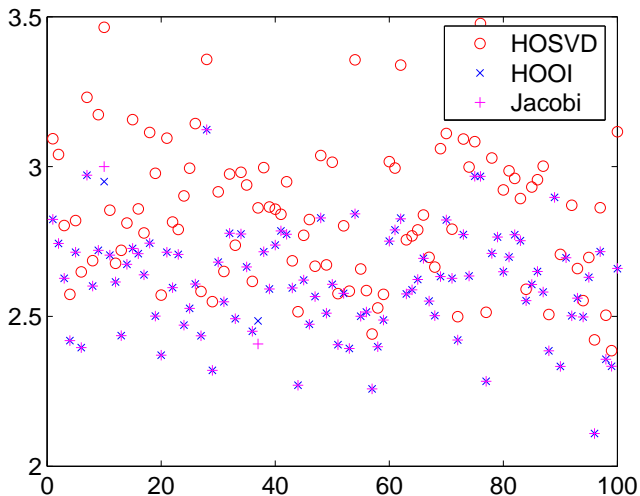


Figure: Multilinear rank 3 approximation of 100 random antisymmetric  $10 \times 10 \times 10$  tensors.

## Numerical examples - Approximation error

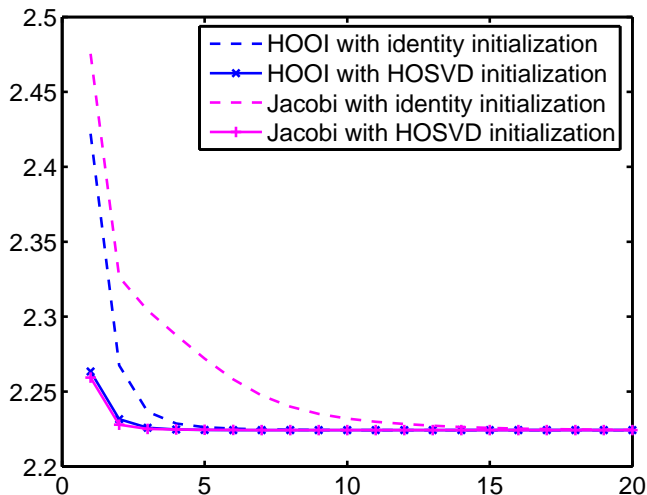


Figure: Multilinear rank 6 approximation of a random  $10 \times 10 \times 10$  tensor.

# MULTILINEAR RANK $d$ APPROXIMATION

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- $\mathcal{A}$  antisymmetric  
 $\mathcal{A} \dashrightarrow \mathcal{B} = x_1 \circ x_2 \circ \cdots \circ x_d$  rank 1, unstructured  
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### Theorem (B., Kressner)

Let  $\mathcal{A} \in \mathbb{R}^{n \times \cdots \times n}$  be an antisymmetric tensor of order  $d$ . It holds

$$\begin{aligned} & \max \{ \|\mathcal{A} \times_1 U^T \cdots \times_d U^T\| \mid U \in \mathbb{R}^{n \times d}, U^T U = I_d \} \\ & = d! \max \{ |\mathcal{A} \times_1 v_1^T \cdots \times_d v_d^T| \mid \|v_1\|_2 = \cdots = \|v_d\|_2 = 1 \}. \end{aligned}$$

- If  $\mathcal{B} = \alpha u_1 \circ u_2 \circ \cdots \circ u_d$ , is the best rank-1 approximation and  $u_k$  are mutually orthonormal,  $1 \leq k \leq d$ , then

$$\hat{\mathcal{A}} = d! \text{anti}(\mathcal{B})$$

is the best multilinear rank  $d$  approximation.



# HOPM AND NEW INITIALIZATION

- **Minimization problem:**  $\|\mathcal{A} - u_1 \circ u_2 \circ \dots \circ u_d\|^2 \rightarrow \min$
- **Higher order power method** ( $\sim$  2002)
- ALS algorithm,  
in each microiteration one vector  $u_k$ ,  $1 \leq k \leq d$ , is updated
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- Converges to local minima
  
- Standard initialization by HOSVD:  $u_k = \mathbf{U}_k(:, 1)$ ,  $1 \leq k \leq d$ .
- New initialization for  $d = 4$

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Form square matricization  $\mathbf{A}_{(1,2)}$ .

Compute eigenvector  $v \in \mathbb{R}^{n^2}$  belonging to largest eigenvalue of  $\mathbf{A}_{(1,2)}$ .

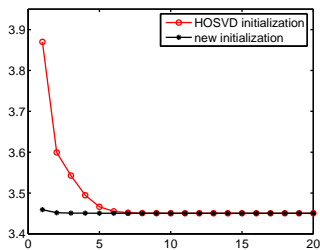
Form  $\tilde{\mathbf{V}} \in \mathbb{R}^{n \times n}$ .

Compute  $\tilde{\mathbf{V}} = \mathbf{U}\Sigma\mathbf{V}^T$ .

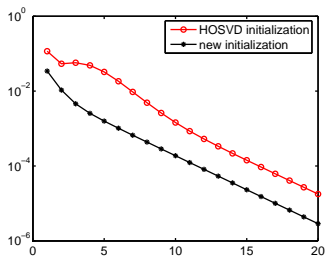
$u_i = \mathbf{U}(:, i)$ ,  $1 \leq i \leq 4$ .

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## $d = 4$ : New initialization - Convergence



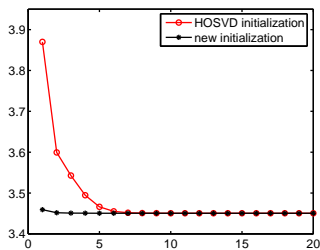
(a) Approximation error



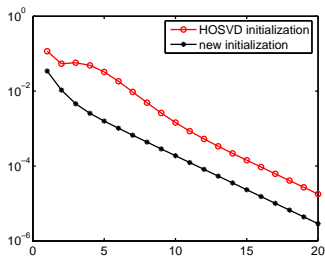
(b) Norm of gradient

Figure: Multilinear rank 4 approximation of a random  $10 \times 10 \times 10 \times 10$  tensor.

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(a) Approximation error



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**THANK YOU!**