

$$1) \begin{cases} u_t + c_1 \partial_1 u + c_2 \partial_2 u + f(t, x_1, x_2) u = 0 & u \in \mathbb{R}^+ \times \mathbb{R}^2 \\ u(0, \cdot, \cdot) = g \end{cases}$$

P:

1. NACIN: Konsteci supstitucijin

Cilj je uverti nove varijable ξ_i

$$\xi_i = a_{i1}t + a_{i2}x_1 + a_{i3}x_2, \quad i=1,2,3$$

tako da

① gonge prelikavanje bude regulano, odnosno da metrica bude $\Rightarrow [a_{ij}]_{ij}$ bude regulana.

② funkcija $v(\xi_1, \xi_2, \xi_3) := u(t, x_1, x_2)$ zadovoljava ODS (odnosno da jasnjajih derivacija rame po jednoj varijabli).

Jedan moguci izbor je

$$\begin{aligned} \xi_1 &= c_1 c_2 t + c_2 x_1 + c_1 x_2 \\ \xi_2 &= x_1 - c_1 t \\ \xi_3 &= x_2 - c_2 t \end{aligned} \Rightarrow \begin{aligned} t &= \frac{1}{3c_1 c_2} \xi_1 - \frac{1}{3c_1} \xi_2 - \frac{1}{3c_2} \xi_3 \\ x_1 &= \frac{1}{3c_2} \xi_1 + \frac{2}{3} \xi_2 - \frac{c_1}{3c_2} \xi_3 \\ x_2 &= \frac{1}{3c_1} \xi_1 - \frac{c_2}{3c_1} \xi_2 + \frac{2}{3} \xi_3 \end{aligned}$$

Naravno, gonge uvjeti uz pretpostavku $c_1, c_2 \neq 0$, metodicim, konacno rjesenje kognje dobijeno uvjetit se i u tom slucaju.

Definirajmo

$$\begin{aligned} v(\xi_1, \xi_2, \xi_3) &:= u(t, x_1, x_2) && \text{ordje su } t, x_1 \text{ i } x_2 \text{ dan:} \\ \tilde{f}(\xi_1, \xi_2, \xi_3) &:= f(t, x_1, x_2) && \text{preko } \xi_1, \xi_2 \text{ i } \xi_3 \text{ kao gore} \end{aligned}$$

Tinamo:

$$\begin{aligned} u_t &= v_{\xi_1} \frac{d\xi_1}{dt} + v_{\xi_2} \frac{d\xi_2}{dt} + v_{\xi_3} \frac{d\xi_3}{dt} \\ &= c_1 c_2 v_{\xi_1} - c_1 v_{\xi_2} - c_2 v_{\xi_3} \\ \partial_1 u &= c_2 v_{\xi_1} + v_{\xi_2} \\ \partial_2 u &= c_1 v_{\xi_1} + v_{\xi_3} \end{aligned}$$

$$\begin{aligned} \Rightarrow 0 &= u_t + c_1 \partial_1 u + c_2 \partial_2 u + f(t, x_1, x_2) u \\ &= c_1 c_2 v_{\xi_1} - c_1 v_{\xi_2} - c_2 v_{\xi_3} + c_1 c_2 v_{\xi_1} + c_1 v_{\xi_2} + c_1 c_2 v_{\xi_1} + c_2 v_{\xi_3} + \tilde{f}(\xi_1, \xi_2, \xi_3) v \end{aligned}$$

Dobili smo da funkcija v zadovoljava ODS

$$\boxed{v_{\xi_1} + \frac{1}{3c_1 c_2} \tilde{f} v = 0}$$

Odatle slijedi:

$$v(\xi_1, \xi_2, \xi_3) = v(\bar{\xi}_1, \xi_2, \xi_3) e^{\frac{-1}{3c_1 c_2} \int_{\bar{\xi}_1}^{\xi_1} \tilde{f}(\gamma, \xi_2, \xi_3) d\gamma}$$

- $v(\xi_1, \xi_2, \xi_3) = u(t, x_1, x_2)$

- $v(\bar{\xi}_1, \xi_2, \xi_3) = u\left(\frac{1}{3c_1 c_2} \bar{\xi}_1 - \frac{1}{3c_1} \xi_2 - \frac{1}{3c_2} \xi_3, \frac{1}{3c_2} \bar{\xi}_1 + \frac{2}{3} \xi_2 - \frac{c_1}{3c_2} \xi_3, \frac{1}{3c_1} \bar{\xi}_1 - \frac{c_2}{3c_1} \xi_2 + \frac{2}{3} \xi_3\right)$

Želimo odrediti takav $\bar{\xi}_1$,
t.d. ovde bude 0 pa
da možemo iskoristiti
početni uvjet

$$\Rightarrow \boxed{\bar{\xi}_1 = c_2 \xi_2 + c_1 \xi_3}, \text{ a od prethodno}$$

$$\begin{cases} \bar{\xi}_2 = x_1 - c_1 t \\ \bar{\xi}_3 = x_2 - c_2 t \end{cases}$$

- $\frac{1}{3c_2} \bar{\xi}_1 + \frac{2}{3} \xi_2 - \frac{c_1}{3c_2} \xi_3 = \frac{1}{3} \xi_2 + \frac{c_1}{3c_2} \xi_3 + \frac{2}{3} \xi_2 - \frac{c_1}{3c_2} \xi_3 = \bar{\xi}_2 = x_1 - c_1 t$
- $\frac{1}{3c_2} \bar{\xi}_1 - \frac{c_2}{3c_1} \xi_2 + \frac{2}{3} \xi_3 = \dots = \bar{\xi}_3 = x_2 - c_2 t$

$$\Rightarrow v(\bar{\xi}_1, \xi_2, \xi_3) = u(0, x_1 - c_1 t, x_2 - c_2 t)$$

- $\int_{\bar{\xi}_1}^{\xi_1} \tilde{f}(\gamma, \xi_2, \xi_3) d\gamma = \int_{\bar{\xi}_1}^{\xi_1} \tilde{f}\left(\frac{1}{3c_1 c_2} \gamma - \frac{1}{3c_1} \xi_2 - \frac{1}{3c_2} \xi_3, \frac{1}{3c_2} \gamma + \frac{2}{3} \xi_2 - \frac{c_1}{3c_2} \xi_3, \frac{1}{3c_1} \gamma - \frac{c_2}{3c_1} \xi_2 + \frac{2}{3} \xi_3\right) d\gamma$

$$\begin{cases} \Delta = \frac{1}{3c_1 c_2} \gamma - \frac{1}{3c_1} \xi_2 - \frac{1}{3c_2} \xi_3 \Rightarrow d\Delta = \frac{1}{3c_1 c_2} d\gamma \\ \gamma = \bar{\xi}_1 \Rightarrow \Delta = \frac{1}{3c_1 c_2} \bar{\xi}_1 - \frac{1}{3c_1} \xi_2 - \frac{1}{3c_2} \xi_3 = 0 \\ \gamma = \xi_1 \Rightarrow \Delta = \frac{1}{3c_1 c_2} \xi_1 - \frac{1}{3c_1} \xi_2 - \frac{1}{3c_2} \xi_3 = t \\ \gamma = 3c_1 c_2 \Delta + c_2 \xi_2 + c_1 \xi_3 \\ \Rightarrow \frac{1}{3c_2} \gamma + \frac{2}{3} \xi_2 - \frac{c_1}{3c_2} \xi_3 = c_1 \Delta + \xi_2 = x_1 + c_1 (\Delta - t) \\ \frac{1}{3c_1} \gamma - \frac{c_2}{3c_1} \xi_2 + \frac{2}{3} \xi_3 = c_2 \Delta + \xi_3 = x_2 + c_2 (\Delta - t) \end{cases}$$

$$= 3c_1 c_2 \int_0^t f(\Delta, x_1 + c_1 (\Delta - t), x_2 + c_2 (\Delta - t)) d\Delta$$

$$\Rightarrow \boxed{u(t, x_1, x_2) = g(x_1 - c_1 t, x_2 - c_2 t) e^{-\int_0^t f(\Delta, x_1 + c_1 (\Delta - t), x_2 + c_2 (\Delta - t)) d\Delta}}$$

→ može teško provjeriti da je ovo rješenje i u slučaju kad je $c_1 = 0$ ili $c_2 = 0$

2. NACÍN : metoda funkčnosti

$$S = \{ (0, x_1, x_2) \in \mathbb{R}^3 \}$$

$$\frac{dt}{d\tau} = 1 \quad \Rightarrow \quad t(\tau) = \tau + C_1$$

$$\frac{dx_1}{d\tau} = c_1 \quad \Rightarrow \quad x_1(\tau) = c_1 \tau + C_2$$

$$\frac{dx_2}{d\tau} = c_2 \quad \Rightarrow \quad x_2(\tau) = c_2 \tau + C_3$$

$$\frac{dz}{d\tau} = -f(t, x_1, x_2) \quad \Rightarrow \quad \frac{dz}{z} = -f(\tau + C_1, c_1 \tau + C_2, c_2 \tau + C_3) d\tau \quad / \int_0^\tau$$

$$\Rightarrow z(\tau) = z(0) e^{-\int_0^\tau f(s + C_1, c_1 s + C_2, c_2 s + C_3) ds}$$

$$(0, x_1^0, x_2^0) \in S$$

$$\left. \begin{array}{l} t(0) = 0 \Rightarrow C_1 = 0 \\ x_1(0) = x_1^0 \Rightarrow C_2 = x_1^0 \\ x_2(0) = x_2^0 \Rightarrow C_3 = x_2^0 \\ z(0) = g(x_1^0, x_2^0) \end{array} \right\} \Rightarrow \begin{array}{l} t(\tau) = \tau \\ x_1(\tau) = c_1 \tau + x_1^0 \\ x_2(\tau) = c_2 \tau + x_2^0 \\ z(\tau) = g(x_1^0, x_2^0) e^{-\int_0^\tau f(s + C_1, c_1 s + x_1^0, c_2 s + x_2^0) ds} \end{array}$$

$$\tau = t$$

$$x_1^0 = x_1 - c_1 t$$

$$x_2^0 = x_2 - c_2 t$$

$$\left. \begin{array}{l} \\ \\ \\ \end{array} \right\} \Rightarrow u(t, x_1, x_2) = z(\tau; x_1^0, x_2^0)$$

$$= g(x_1 - c_1 t, x_2 - c_2 t) e^{-\int_0^t f(s, x_1 + c_1(s-t), x_2 + c_2(s-t)) ds}$$

2)

a)

$$\begin{cases} x u_x - 2y u_y - u_z = u^2 & \text{in } \mathbb{R}^3 \\ u(x, y, 0) = x^2 + xy + y^2 \end{cases}$$

S... $\{(x, y, 0) : x, y \in \mathbb{R}\}$

$$\text{monome je } \omega = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ -2y \\ -1 \end{bmatrix} = -1 \neq 0 \Rightarrow \text{nenka}$$

karakterističnih
tocala

B) METODA KARAKTERISTIKA

$$\frac{dx}{d\tau} = x \Rightarrow \frac{dx}{x} = d\tau \Rightarrow \ln|x| = \tau + C \Rightarrow x(\tau) = C_1 e^\tau$$

$$\frac{dy}{d\tau} = -2y \Rightarrow \dots \Rightarrow y(\tau) = C_2 e^{-2\tau}$$

$$\frac{dz}{d\tau} = -1 \Rightarrow z(\tau) = -\tau + C_3$$

$$\text{tjednoje} \rightarrow \frac{dv}{d\tau} = u^2 \Rightarrow \frac{dv}{u^2} = d\tau \Rightarrow -\frac{1}{u} = \tau + C_4 \Rightarrow v = \frac{-1}{\tau + C_4}$$

Ta rubnog ujetia dobivamo: $(x_0, y_0, 0) \in S \dots$ plohe na kojoj je zadano:

$$x_0 = x(0) = C_1$$

$$y_0 = y(0) = C_2$$

$$0 = z(0) = C_3$$

$$x_0^2 + x_0 y_0 + y_0^2 = v(0) = -\frac{1}{C_4} \Rightarrow C_4 = -\frac{1}{x_0^2 + x_0 y_0 + y_0^2}$$

$$\left. \begin{array}{l} x(\tau) = x_0 e^\tau \\ y(\tau) = y_0 e^{-2\tau} \\ z(\tau) = -\tau \\ v(\tau) = \frac{-x_0^2 - x_0 y_0 - y_0^2}{(x_0^2 + x_0 y_0 + y_0^2)\tau - 1} \end{array} \right\} \Rightarrow$$

Izrazimo $\tau, x_0 \text{ i } y_0$ preko $x, y \text{ i } z$:

$$\boxed{\tau = -z}$$

$$\boxed{\begin{aligned} y_0 &= y e^{2\tau} = y e^{-2z} \\ x_0 &= x e^{-\tau} = x e^z \end{aligned}}$$

$$u(x, y, z) = v(\tau; x_0, y_0)$$

$$= \frac{-x^2 e^{2z} - xy e^{-z} - y^2 e^{-4z}}{-(+x^2 e^{2z} + xy e^{-z} + y^2 e^{-4z})z - 1}$$

$$= \frac{x^2 e^{2z} + xy e^{-z} + y^2 e^{-4z}}{1 + (x^2 e^{2z} + xy e^{-z} + y^2 e^{-4z})z}$$

2)

b)

$$\begin{cases} ux u_x - y u u_y = y^2 - x^2 \\ u(x, x) = f(x) \end{cases} \quad u \in \mathbb{R}^2$$

P:

$$S \dots \{(x, x) : x \in \mathbb{R}\} \Rightarrow v = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ -1 \end{bmatrix} \cdot \begin{bmatrix} ux \\ -yu \end{bmatrix} = ux + yu - 2ux \rightarrow \text{charakteristična točka je samo ishodiste}$$

* na S gledamo da je $y = x$ ~~prava~~ $y = -x$.

Nakon što podvijelimo jednačinu s u dobivamo:

$$\frac{dx}{dt} = x \Rightarrow x(t) = C_1 e^t$$

$$\frac{dy}{dt} = -y \Rightarrow y(t) = C_2 e^{-t}$$

$$\frac{dv}{dt} = \frac{y^2 - x^2}{v} \Rightarrow v dv = (C_2^2 e^{-2t} - C_1^2 e^{2t}) dt$$

$$\frac{v^2}{2} = -\frac{C_2^2}{2} e^{-2t} - \frac{C_1^2}{2} e^{2t} + C_3$$

$$v^2(t) = -C_2^2 e^{-2t} - C_1^2 e^{2t} + C_3 \quad \text{ocito neće imati smisla za negativne t}$$

$$(x_0, y_0) \in S \Rightarrow$$

$$x_0 = x(0) = C_1$$

$$y_0 = y(0) = C_2$$

$$f(x_0) = v(0) \Rightarrow f^2(x_0) = v^2(0) = -C_2^2 - C_1^2 + C_3$$

$$f^2(x_0) = -2x_0^2 + C_3 \Rightarrow C_3 = f^2(x_0) + 2x_0^2$$

$$\Rightarrow \begin{aligned} x(t) &= x_0 e^t \\ y(t) &= y_0 e^{-t} \\ v^2(t) &= -x_0^2 (e^{-2t} + e^{2t}) + f^2(x_0) + 2x_0^2 \end{aligned} \quad \left. \begin{array}{l} \text{brojući da je } xy \text{ nužno} \\ \text{njegove vrijednosti definirati samo} \\ \text{na I i III kvadrantu} \end{array} \right\} \Rightarrow \begin{aligned} x_0^2 &= xy \\ e^t &= \frac{x}{x_0} \Rightarrow e^{2t} = \frac{x^2}{x_0^2} = \frac{x^2}{xy} = \frac{x}{y} \Rightarrow e^{-2t} = \frac{y}{x} \end{aligned}$$

$$x_0^2 = xy \Rightarrow x_0 = \boxed{\operatorname{sign}(x) \sqrt{xy}} \quad \rightarrow x_0, x, y su istog predznaka$$

$$\begin{aligned} \Rightarrow u^2(x, y) &= v^2(t; x_0) = -xy \left(y + \frac{x}{y} \right) + f^2(\operatorname{sign}(x) \sqrt{xy}) + 2xy \\ &= -\cancel{xy} \cancel{\left(y + \frac{x}{y} \right)} + f^2(\operatorname{sign}(x) \sqrt{xy}) \end{aligned} \quad \text{ovo mora biti } \geq 0$$

pa skup mojih vrijednosti definirati njegove ovisnosti o f

NAP. Alternativno se može uvesti na početku supstitucija

tad:

$$\begin{cases} v_x = u u_x \\ v_y = u u_y \end{cases}$$

$$\boxed{xv_x - yv_y = y^2 - x^2}$$

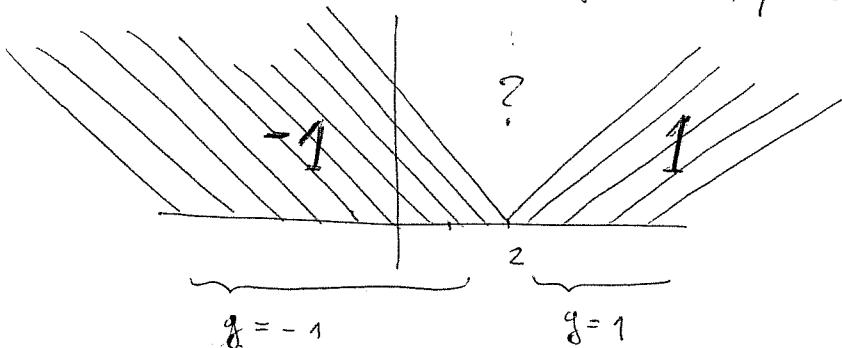
$$v(x, x) = \frac{u^2(x, x)}{2} = \frac{f^2(x)}{2}$$

$v = \frac{u^2}{2}$ jer je
njegovo po v i samo
ne karovi metimo
supstituciju

3)

$$\begin{cases} u_t + uu_x = 0 \\ u(0, \cdot) = g \end{cases}, \quad g(x) = \begin{cases} -1, & x < 2 \\ 1, & x \geq 2 \end{cases}$$

Piš: Karakteristike su oblika $x(t) = g(x_0)t + x_0$, pri čemu $x_0 \in \mathbb{R}$.



Otredimo rješenje u podmjeni gdje nemamo karakteristike.

① R-H ujet u točki $t=0, x=2$

$$\left. \begin{array}{l} u_t = -1 \\ u_x = 1 \\ F_t = 1 \\ F_x = 1 \end{array} \right\} -2 \stackrel{\circ}{\wedge} = 0 \Rightarrow \Delta(t) = C$$

$$\Delta(0) = 2 \Rightarrow C = 2$$

$$\Rightarrow x(t) = \Delta(t) = 2 \text{ je kružnica } \tilde{x}$$

Time smo dobili:

Međutim, ovo nije

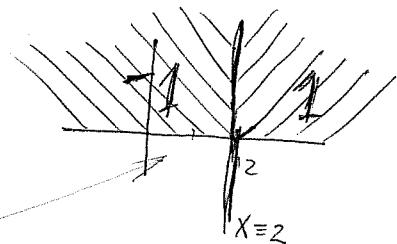
$$u(t, x) = \begin{cases} -1, & x < 2 \\ 1, & x \geq 2 \end{cases}, \quad t \in \mathbb{R}^+$$

entropijsko rješenje jer je $u_t < u_x$
(tehoder, notavamo da karakteristike izlaze iz kružnje solje što nije dobro)

② ENTROPIJSKO RJEŠENJE

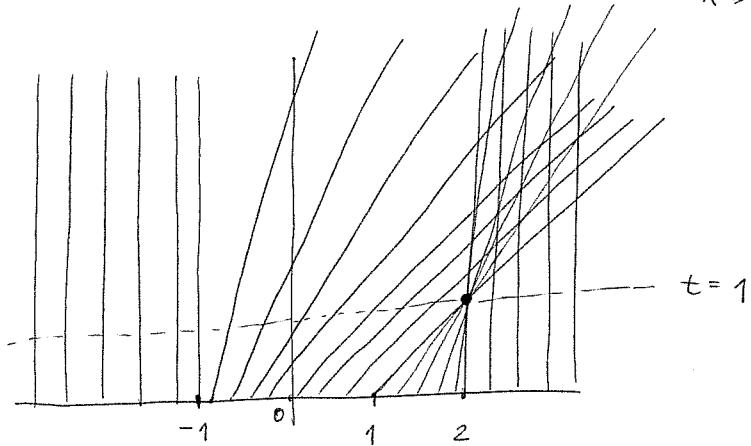
Postavimo neprekidno rješenje. Želimo da na pravcu $t = -x + 2$ bude vrijednost -1 , dok na pravcu $t = x - 2$ bude vrijednost 1 . To postizemo f.d. definiramo

$$u(t, x) = \begin{cases} -1, & t < -x + 2 \\ \frac{x-2}{t}, & -x+2 \leq t \leq x-2 \\ 1, & t > x-2 \end{cases}$$



4) a) $\begin{cases} u_t + uu_x = 0 \\ u(0, \cdot) = g \end{cases}$, $g(x) = \begin{cases} 0 & , x < -1 \\ x+1 & , -1 \leq x < 0 \\ 1 & , 0 \leq x < 1 \\ 2-x & , 1 \leq x < 2 \\ 0 & , x \geq 2 \end{cases}$

Bi.



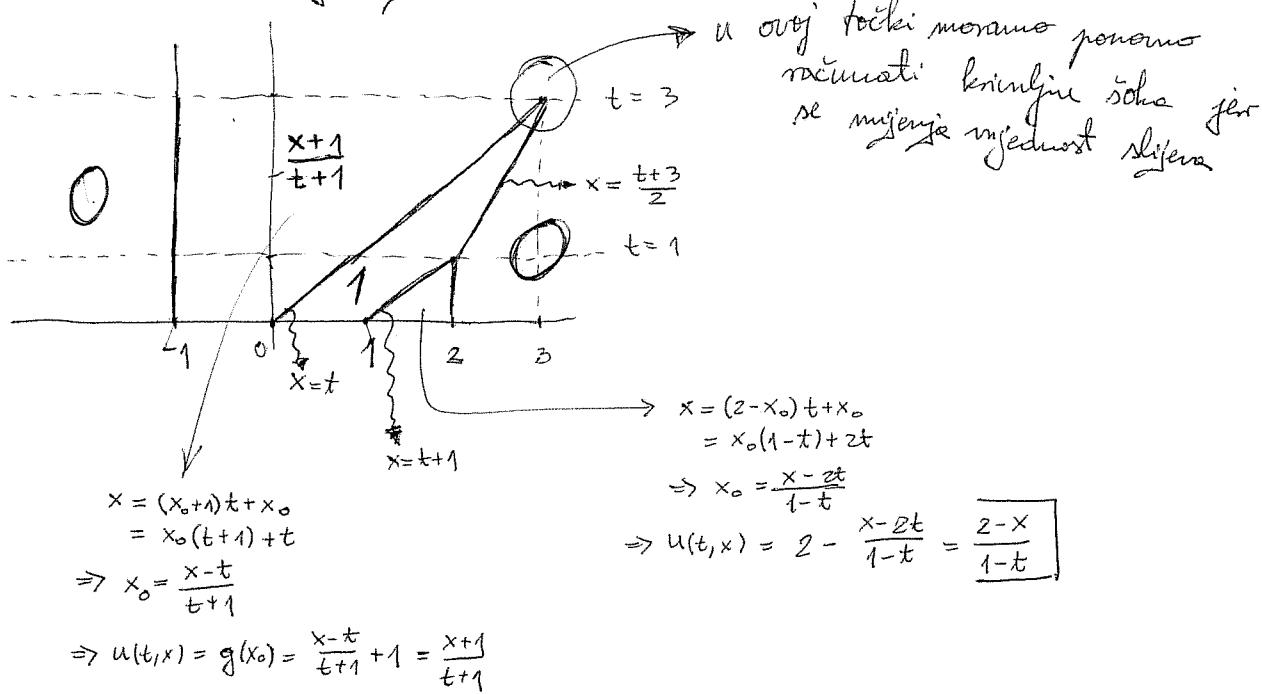
Trebamo izračunati kružnu řešku u točki $t=1, x=2$.

$$\left. \begin{array}{l} u_\ell = 1 \\ u_r = 0 \\ F_\ell = \frac{1}{2} \\ F_r = 0 \end{array} \right\} \Rightarrow \dot{s} = \frac{1}{2} \Rightarrow s(t) = \frac{1}{2}t + C$$

$$s(1) = 2 \Rightarrow \frac{1}{2} + C = 2 \Rightarrow C = \frac{3}{2}$$

Kružna řeška je $x(t) = s(t) = \frac{t+3}{2}$.

Skicirajmo nadejno rješenje:



Našim je řešení už známo $t=3, x=3$.

$$\left. \begin{array}{l} u_t = \frac{\Delta(t)+1}{t+1} \\ u_{tt} = 0 \\ F_t = \frac{1}{2} \left(\frac{\Delta(t)+1}{t+1} \right)^2 \\ F_{tt} = 0 \end{array} \right\} \Rightarrow \Delta = \frac{\Delta+1}{2t+2}$$

$$\frac{ds}{\Delta+1} = \frac{dt}{2t+2} \quad | \int \Rightarrow \ln(\Delta+1) = \ln(2t+2) + C$$

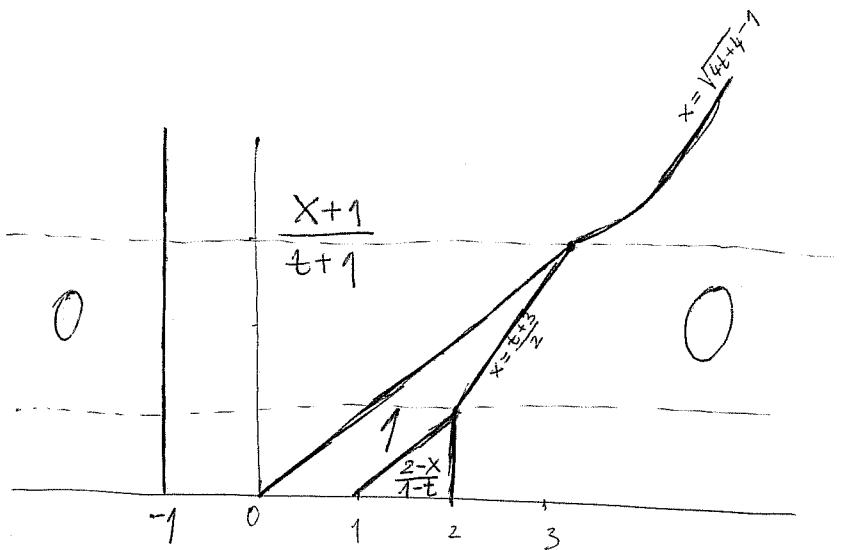
$$\Rightarrow \Delta+1 = C\sqrt{2t+2}$$

$$\Delta(t) = C\sqrt{2t+2} - 1$$

$$\Delta(3) = 3 \Rightarrow \sqrt{8}C - 1 = 3 \Rightarrow C = \frac{4\sqrt{2}}{2\sqrt{2}} = \sqrt{2}$$

$$\Rightarrow \boxed{\Delta(t) = \sqrt{4t+4} - 1} =: x(t)$$

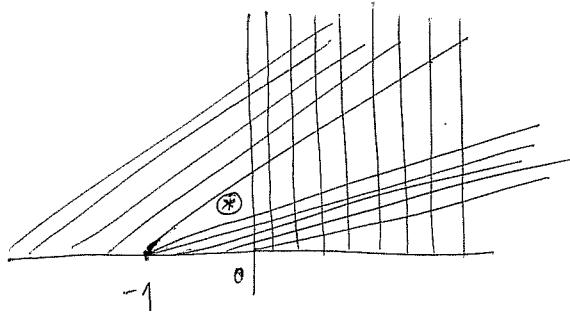
Žd možeme zavést
nějaký význam:



4) b)

$$\begin{cases} u_t + uu_x = 0 \\ u(0, \cdot) = g \end{cases}, \quad g(x) = \begin{cases} 1 & ; x < -1 \\ 2 & ; -1 \leq x < 0 \\ 0 & ; x \geq 0 \end{cases}$$

R:



① Odredimo kružnicu řešení v bodě u t=0, x=0.

$$\left. \begin{array}{l} u_t = 2 \\ u_r = 0 \\ F_t = 2 \\ F_r = 0 \end{array} \right\} \Rightarrow 2s = 2 \Rightarrow s(t) = t + C$$

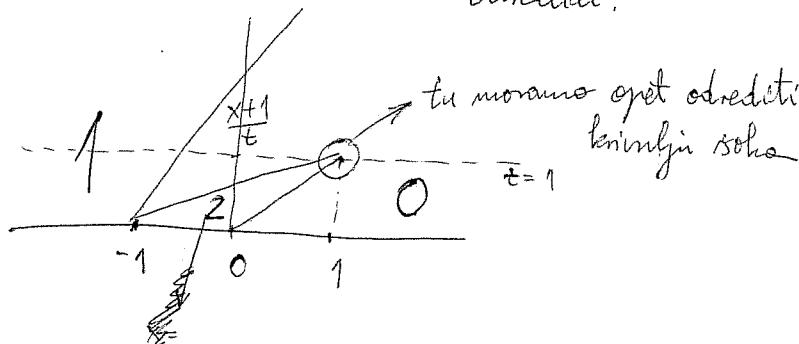
$$s(0) = 0 \Rightarrow C = 0$$

$$\boxed{s(t) = t} \quad \dots \text{první kružnice řešení}$$

② Odredimo druhou kružnici řešení \circledast .

Staráme $\frac{x+1}{t}$. Jde je me pravou $x = +t - 1$ mřednost jednačka $\frac{+t - 1 + 1}{t} = +1$, dok je me pravou $x = +2t - 1$ jednačka $\frac{+2t - 1 + 1}{t} = +2$, to jsou i hřeben.

Skicirováno stále do sedadla odrediti.

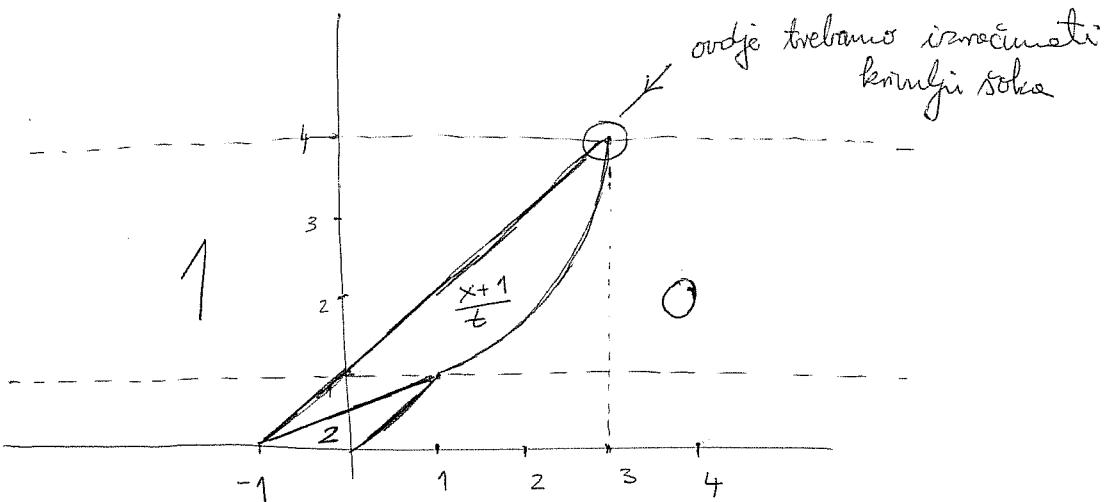


$$\left. \begin{array}{l} u_t = \frac{s+1}{t} \\ u_r = 0 \\ F_t = \frac{1}{2} \left(\frac{s+1}{t} \right)^2 \\ F_r = 0 \end{array} \right\} \Rightarrow s = \frac{s+1}{zt} \Rightarrow \frac{ds}{s+1} = \frac{dt}{zt} \int \Rightarrow \ln|s+1| = \ln\sqrt{zt} + C \Rightarrow s+1 = C\sqrt{zt} \Rightarrow s(t) = C\sqrt{zt} - 1$$

$$s(1) = 1 \Rightarrow \sqrt{z}C - 1 = 1 \Rightarrow C = \sqrt{z}$$

$$\Rightarrow \boxed{s_2(t) = \sqrt{4t} - 1} \quad \dots \text{druhá kružnice řešení}$$

Tada imamo:



- ④ Izračunajte slike u točki $t=4, x=3$.

$$\left. \begin{array}{l} u_e = 1 \\ u_r = 0 \\ F_e = \frac{1}{2} \\ F_r = 0 \end{array} \right\} \Rightarrow \Delta = \frac{1}{2} \Rightarrow \Delta(t) = \frac{1}{2}t + C \quad \left. \begin{array}{l} 3 = \Delta(4) = 2 + C \Rightarrow C = 1 \end{array} \right\} \Rightarrow \boxed{\Delta(t) = \frac{1}{2}t + 1} \quad \text{... treća kružna slika}$$

Konacno je resenje dano sa:

