Well-posedness for a class of non-autonomous differential inclusions.

Sascha Trostorff (joint work with Maria Wehowski)

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An example: the non-autonomous heat equation

The setting

Well-posedness of non-autonomous problems

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We consider

$$egin{aligned} \partial_0 heta(t) + \operatorname{div} q(t) &= f(t), \ q(t) &= -k(t) \operatorname{grad} heta(t), \end{aligned}$$

for $t \in \mathbb{R}$ in a domain $\Omega \subseteq \mathbb{R}^n$, where ∂_0 denotes the temporal derivative, $k : \mathbb{R} \to L_{\infty}(\Omega)$ suitable function and f is a given source term.

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Classically, one proves that -A(t), subject to suitable boundary conditions, is a generator of an evolution family $(U(t,s))_{t \ge s \ge 0}$ and applies Duhamel's formula.

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We consider the system

$$\begin{pmatrix} \partial_0 \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 0 & k(t)^{-1} \end{pmatrix} + \begin{pmatrix} 0 & \operatorname{div} \\ \operatorname{grad} & 0 \end{pmatrix} \end{pmatrix} \begin{pmatrix} \theta(t) \\ q(t) \end{pmatrix} = \begin{pmatrix} f(t) \\ 0 \end{pmatrix}$$

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$$\left(\partial_0\underbrace{\begin{pmatrix}1&0\\0&0\end{pmatrix}}_{=:M_0(t)}+\underbrace{\begin{pmatrix}0&0\\0&k(t)^{-1}\end{pmatrix}}_{=:M_1(t)}+\underbrace{\begin{pmatrix}0&\mathrm{div}\\\mathrm{grad}&0\end{pmatrix}}_{=:A}\right)\begin{pmatrix}\theta(t)\\q(t)\end{pmatrix}=\begin{pmatrix}f(t)\\0\end{pmatrix}$$

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Thus, we end up with an equation of the form

$$(\partial_0 M_0(\mathbf{m}) + M_1(\mathbf{m}) + A) u = f,$$

where A is skew-selfadjoint (b.c.),

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Thus, we end up with an equation of the form

$$(\partial_0 M_0(\mathbf{m}) + M_1(\mathbf{m}) + A) u = f,$$

where A is skew-selfadjoint (b.c.), or more generally

$$(u, f) \in \partial_0 M_0(\mathbf{m}) + M_1(\mathbf{m}) + A,$$

where A is a maximal monotone relation.

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Well-posedness of non-autonomous problems

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Define the derivative $\partial_{0,\rho}$ on $H_{\rho}(\mathbb{R};H)$ as the closure of

$$\partial_{0,\rho}|_{C^{\infty}_{c}(\mathbb{R};H)}: C^{\infty}_{c}(\mathbb{R};H) \subseteq H_{\rho}(\mathbb{R};H) \to H_{\rho}(\mathbb{R};H)$$

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Then, $\partial_{0,\rho}$ is a normal operator with $\Re \partial_{0,\rho} = \rho$ and thus, $\|\partial_{0,\rho}^{-1}\| \leq \frac{1}{\rho}$.

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In particular, $\partial_{0,\rho}^{-1}$ is causal.

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Consider two strongly measurable, bounded functions $M_i : \mathbb{R} \to L(H)$ and denote by $M_i(\mathbf{m})$ the associated multiplication operator on $L_{2,\text{loc}}(\mathbb{R}; H)$. Throughout, the following assumptions should hold:

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Hypotheses

(a) M_0 is Lipschitz-continuous and there exists a set $N \subseteq \mathbb{R}$ of measure zero, such that for all $x \in H$

 $\mathbb{R}\setminus N\ni t\mapsto M_0(t)x$

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- (c) There exist $\rho_0 > 0$, c > 0 such that

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ho \mathsf{M}_0(t) + rac{1}{2} \dot{\mathsf{M}}_0(t) + \Re \mathsf{M}_1(t) \geq c.$$

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Monotone relations

Let $A \subseteq H \oplus H$ be a binary relation. A is called *monotone* if for all pairs $(u, v), (x, y) \in A$ we have

$$\Re\langle u-x|v-y\rangle\geq 0.$$

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Remark

Let A, B be two monotone relations. Then

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Lemma

Assume that M_0 , M_1 satisfy the hypotheses above. Then, there exist ρ_0 , c > 0 such that for all $\rho \ge \rho_0$ the operator $\partial_{0,\rho}M_0(m) + M_1(m) - c$

is monotone.

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Uniqueness and Continuous dependence Let $A \subseteq H \oplus H$ be monotone and define

$$A_
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Corollary

Assume that M_0 , M_1 satisfy the hypotheses. Then there exists ρ_0 , c > 0 such that $\partial_{0,\rho}M_0(m) + M_1(m) + A_{\rho} - c$ is monotone,

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Corollary

Assume that M_0 , M_1 satisfy the hypotheses. Then there exists ρ_0 , c > 0 such that $\partial_{0,\rho}M_0(m) + M_1(m) + A_{\rho} - c$ is monotone, i.e. for $(u, f), (v, g) \in \partial_{0,\rho}M_0(m) + M_1(m) + A_{\rho}$ we estimate

$$\Re \langle u - v | f - g \rangle_{H_{\rho}(\mathbb{R};H)} \geq c | u - v |^2_{H_{\rho}(\mathbb{R};H)},$$

yielding

$$|u-v|_{H_{\rho}(\mathbb{R};H)}\leq rac{1}{c}|f-g|_{H_{\rho}(\mathbb{R};H)}.$$

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Assume that $A : D(A) \subseteq H \rightarrow H$ is skew-selfadjoint (in particular, A is monotone) and set

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GOAL: Find a dense subset $\mathcal{G} \subseteq H_{\rho}(\mathbb{R}; H)$, where we can show existence, i.e. for $f \in \mathcal{G}$ there exists $u \in D(\mathcal{B}_{\rho})$ with $\mathcal{B}_{\rho}(u) = f$.

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$$H_{\rho}(\mathbb{R}; H) = \overline{R(\mathcal{B}_{\rho})} \oplus N(\mathcal{B}_{\rho}^*).$$

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Theorem (Picard, Waurick, Wehowski, T)

There exists $\rho_0 > 0$ such that for all $\rho \ge \rho_0$ the operator \mathcal{B}_{ρ}^* is injective.

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GOAL: Find a dense subset $\mathcal{G} \subseteq H_{\rho}(\mathbb{R}; H)$, where we can show existence, i.e. for $f \in \mathcal{G}$ there exists $u \in D(\mathcal{B}_{\rho})$ with $(u, f) \in \mathcal{B}_{\rho}$. Problem: The projection theorem does not help! Way out: Perturbation theory for maximal monotone relations.

Well-posedness for a class of non-autonomous differential inclusions.
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Corollary

Assume that M_0, M_1 satisfy the hypotheses. Then there exists $\rho_0 > 0, c > 0$ such that $\partial_{0,\rho}M_0(m) + M_1(m) - c$ is maximal monotone for all $\rho \ge \rho_0$.

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Proof.

This follows from the solution theory above with A = 0.

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For A maximal monotone, $\lambda > 0$ we define

$$A_{\lambda}: H \to H \quad x \mapsto \lambda^{-1}(x - (1 + \lambda A)^{-1}(x))$$

the Yosida approximation.

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Proposition

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Theorem

Let $A, B \subseteq H \oplus H$ be maximal monotone and $y \in H$. Then there exists $x \in H$ such that $(x, y) \in 1 + A + B$ if and only if

$$\sup_{\lambda>0}|B_{\lambda}(x_{\lambda})|<\infty,$$

where $(x_{\lambda}, y) \in 1 + A + B_{\lambda}$.

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We replace the hypothesis

(c) $\exists \rho_0, c > 0 \forall \rho \geq \rho_0, t \in \mathbb{R} \setminus N : \rho M_0(t) + \frac{1}{2} \dot{M}_0(t) + \Re M_1(t) \geq c.$

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- (c') The null-space of $M_0(t)$ is *t*-independent.
- (d') There exists c > 0 such that for all $t \in \mathbb{R}$ we have $M_0(t) \ge c$ on $N(M(0))^{\perp} = R(M_0(0))$ and $\Re M_1(t) \ge c$ on $N(M_0(0))$.

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For $\delta > 0$ we consider the following auxiliary problem:

$$(u, f) \in \partial_{0,\rho} M_0(\mathbf{m}) + \delta - \dot{M}_0(\mathbf{m}) + A_{\rho}.$$

Note that $M_1(m) := \delta - \dot{M}_0(m)$ satisfies (d').

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A regularity result

Proposition

Let $\rho > 0$ be large enough and $f \in D(\partial_{0,\rho}), \lambda > 0$. Moreover let $u_{\lambda} \in H_{\rho}(\mathbb{R}; H)$ such that

$$\partial_{0,\rho} M_0(\mathbf{m}) u_{\lambda} + \delta u_{\lambda} - \dot{M}_0(\mathbf{m}) u_{\lambda} + A_{\rho,\lambda}(u_{\lambda}) = f.$$

Then $u_{\lambda} \in D(\partial_{0,\rho})$.

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Then $u_{\lambda} \in D(\partial_{0,\rho})$.

Proof

Decompose $u_{\lambda} = P_0 u_{\lambda} + P_1 u_{\lambda} \in N(M_0(0)) + R(M_0(0))$. Then $P_1 u_{\lambda} \in D(\partial_{0,\rho})$, since $M_0(m)u_{\lambda} \in D(\partial_{0,\rho})$. Moreover,

$$\delta P_0 u_{\lambda} + P_0 A_{\rho,\lambda} (P_0 u_{\lambda} + P_1 u_{\lambda}) = P_0 f.$$

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$$\delta P_0 u_{\lambda} + P_0 A_{\rho,\lambda} (P_0 u_{\lambda} + P_1 u_{\lambda}) = P_0 f$$

$$B: H_{\rho}(\mathbb{R}; N(M_0(0))) \to H_{\rho}(\mathbb{R}; N(M_0(0))): \quad v \mapsto P_0 A_{\rho,\lambda}(v + P_1 u_{\lambda}).$$

An easy computation shows that B is monotone.

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The monotonicity of B yields

$$\Re \langle \underbrace{\delta \tau_h P_0 u_{\lambda} + B(\tau_h P_0 u_{\lambda})}_{=g} - (\underbrace{\delta P_0 u_{\lambda} + B(P_0 u_{\lambda})}_{=f}) | (\tau_h - 1) P_0 u_{\lambda} \rangle \geq \delta | (\tau_h - 1) P_0 u_{\lambda} |^2.$$

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$\tau_h P_0 f + P_0 (A_{\rho,\lambda} (\tau_h P_0 u_{\lambda} + P_1 u_{\lambda}) - A_{\rho,\lambda} (\tau_h (P_0 u_{\lambda} + P_1 u_{\lambda}))) =: g$

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$$|(\tau_h-1)P_0u_{\lambda}| \leq \frac{1}{\delta}|f-g|$$

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Thus, $(\frac{1}{h}(\tau_h - 1)P_0u_\lambda)_{h>0}$ is bounded, yielding the differentiability of P_0u_λ .

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Proposition

Let $\rho > 0$ be large enough and $f \in D(\partial_{0,\rho})$. Then there exists $u \in H_{\rho}(\mathbb{R}; H)$ such that

$$(u, f) \in \partial_{0,\rho} M_0(\mathbf{m}) + \delta - \dot{M}_0(\mathbf{m}) + A_{\rho}.$$

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Let u_{λ} solve the problem for A_{ρ} replaced by $A_{\rho,\lambda}$. By the perturbation we have to show that $\sup_{\lambda>0} |A_{\rho,\lambda}(u_{\lambda})| < \infty$.

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$$\langle B_\lambda(v)|v
angle \geq 0 \quad (v\in D(B_\lambda)).$$

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$$(\partial_{0,\rho}M_0(\mathbf{m}) + \delta + B_\lambda)(\partial_{0,\rho}u_\lambda) = \partial_{0,\rho}f,$$

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Since the right-hand side is uniformly bounded in λ we get the assertion.

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Corollary (Solution Theory for auxiliary problem) $(\overline{\partial_{0,\rho}}M_0(m) + \delta - \dot{M}_0(m) + A_{\rho})^{-1}$ is a Lipschitz-continuous mapping on $H_{\rho}(\mathbb{R}; H)$ for sufficiently large $\rho > 0$.

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Solution Theory

Theorem (Wehowski, T)

Let M_0 , M_1 satisfy the hypotheses (a), (b), (c'), (d') and let $A \subseteq H \oplus H$ be maximal monotone with $(0,0) \in A$. Then, $(\overline{\partial_{0,\rho}M_0(m) + M_1(m) + A_\rho})^{-1}$ is a Lipschitz-continuous mapping on $H_\rho(\mathbb{R}; H)$ for sufficiently large $\rho > 0$.

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Proof.

The proof follows from the solution theory for the auxiliary problem and easy perturbation arguments.

Well-posedness for a class of non-autonomous differential inclusions.
Thank you for your attention!

- R. Picard, S. Trostorff, M. Waurick and M. Wehowski. On Non-autonomous Evolutionary Problems. J. Evol. Equ., to appear, arxiv 1302.1304.
- S. Trostorff and M. Wehowski.

Well-posedness of Non-autonomous Evolutionary Inclusions. submitted, arxiv 1307.2074.