Low-rank tensor methods for high-dimensional eigenvalue problems

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Low-rank tensor techniques

- Emerged during last five years in numerical analysis.
- Successfully applied to:
 - parameter-dependent / multi-dimensional integrals;
 - electronic structure calculations: Hartree-Fock / DFT;
 - stochastic and parametric PDEs;
 - high-dimensional Boltzmann / chemical master / Fokker-Planck / Schrödinger equations;
 - micromagnetism;
 - rational approximation problems;
 - computational homogenization;
 - computational finance;
 - stochastic automata networks;
 - multivariate regression and machine learning;
 - ▶ ...
- For references on these applications, see
 - L. Grasedyck, DK, Ch. Tobler (2013). A literature survey of lowrank tensor approximation techniques. GAMM-Mitteilungen, 36(1).
 - W. Hackbusch (2012). Tensor Spaces and Numerical Tensor Calculus, Springer.

High dimensionality

Continuous problem on *d*-dimensional domain with $d \gg 1$

 \Downarrow Straightforward discretization \Downarrow

Discretized problem of order $O(n^d)$

Other causes of high dimensionality:

- parameter dependencies
 - parametrized coefficients
 - parametrized topology
- stochastic coefficients
- systems describing joint probability distributions

▶ ...

Dealing with high dimensionality

Established techniques:

- Sparse grid collocation/Galerkin methods.
- Adaptive (wavelet) methods.
- Monte Carlo method.
- Reduced basis method.

...

Common trait:

Smart discretization \rightsquigarrow system *hopefully* of order $\ll O(N^D)$ but not in this talk!

This talk:

Straightforward discretization \sim system of order $O(N^D)$.

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Smart discretization \rightsquigarrow system *hopefully* of order $\ll O(N^D)$ but not in this talk!

This talk:

Straightforward discretization \rightsquigarrow system of order $O(N^D)$.



Example: PDE-eigenvalue problem

Goal: Compute smallest eigenvalue for

$$\Delta u(\xi) + V(\xi)u(\xi) = \lambda u(\xi) \quad \text{in } \Omega = [0, 1]^d,$$

$$u(\xi) = 0 \quad \text{on } \partial \Omega.$$

Assumption: Potential represented as

$$V(\xi) = \sum_{j=1}^{s} V_{j}^{(1)}(\xi_{1}) V_{j}^{(2)}(\xi_{2}) \cdots V_{j}^{(d)}(\xi_{d}).$$

→ finite difference discretization

$$\mathcal{A}\mathbf{u}=(\mathcal{A}_L+\mathcal{A}_V)\mathbf{u}=\lambda\mathbf{u},$$

with

$$\mathcal{A}_{L} = \sum_{j=1}^{d} \underbrace{I \otimes \cdots \otimes I}_{d-j \text{ times}} \otimes \mathcal{A}_{L} \otimes \underbrace{I \otimes \cdots \otimes I}_{j-1 \text{ times}},$$
$$\mathcal{A}_{V} = \sum_{j=1}^{s} \mathcal{A}_{V,j}^{(d)} \otimes \cdots \otimes \mathcal{A}_{V,j}^{(2)} \otimes \mathcal{A}_{V,j}^{(1)}.$$

Example: Henon-Heiles potential

Consider $\Omega = [-10, 2]^d$ and potential ([Meyer et al. 1990; Raab et al. 2000; Faou et al. 2009])

$$V(\xi) = \frac{1}{2} \sum_{j=1}^{d} \sigma_j \xi_j^2 + \sum_{j=1}^{d-1} \left(\sigma_*(\xi_j \xi_{j+1}^2 - \frac{1}{3} \xi_j^3) + \frac{\sigma_*^2}{16} (\xi_j^2 + \xi_{j+1}^2)^2 \right).$$

with $\sigma_j \equiv 1$, $\sigma_* = 0.2$.

Discretization with n = 128 dof/dimension for d = 20 dimensions.

- Eigenvector has $n^d \approx 10^{42}$ entries.
- Explicit storage of eigenvector would require 10²⁵ exabyte!¹

¹Global data storage in 2011 calculated at 295 exabyte, see http://www.bbc.co.uk/news/technology-12419672.

Example: Henon-Heiles potential

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Discretization with n = 128 dof/dimension for d = 20 dimensions.

- Eigenvector has $n^d \approx 10^{42}$ entries.
- Explicit storage of eigenvector would require 10²⁵ exabyte!¹

Solved with accuracy 10^{-12} in less than 1 hour on laptop.

¹Global data storage in 2011 calculated at 295 exabyte, see http://www.bbc.co.uk/news/technology-12419672.

Contents

- 1. Low-rank matrices
- 2. Low-rank tensor formats
- 3. Low-rank methods for 2D
- 4. Low-rank methods for arbitrary dimensions
- 5. Outlook

Low-rank matrices

Discretization of bivariate function

- ▶ Bivariate function: f(x, y) : $[x_{\min}, x_{\max}] \times [y_{\min}, y_{\max}] \rightarrow \mathbb{R}$.
- Function values on tensor grid $[x_1, \ldots, x_n] \times [y_1, \ldots, y_m]$.
- Normally collected in looong vector:

$$= \begin{bmatrix} f(x_1, y_1) \\ f(x_2, y_1) \\ \vdots \\ f(x_m, y_1) \\ f(x_1, y_2) \\ f(x_2, y_2) \\ \vdots \\ f(x_m, y_2) \\ \vdots \\ f(x_m, y_2) \\ \vdots \\ f(x_1, y_n) \\ f(x_2, y_n) \\ \vdots \\ f(x_m, y_n) \end{bmatrix}$$

f



Discretization of bivariate function

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- Function values on tensor grid $[x_1, \ldots, x_n] \times [y_1, \ldots, y_m]$.
- Collected in a matrix:

$$F = \begin{bmatrix} f(x_1, y_1) & f(x_1, y_2) & \cdots & f(x_1, y_n) \\ f(x_2, y_1) & f(x_2, y_2) & \cdots & f(x_2, y_n) \\ \vdots & \vdots & & \vdots \\ f(x_m, y_1) & f(x_m, y_2) & \cdots & f(x_m, y_n) \end{bmatrix}$$



Low-rank approximation

Setting: Matrix $X \in \mathbb{R}^{n \times m}$, *m* and *n* too large to compute/store *X* explicitly.

Idea: Replace X by RS^T with $R \in \mathbb{R}^{n \times r}$, $S \in \mathbb{R}^{m \times r}$ and $r \ll m, n$.



 $\min \{ \|X - RS^T\|_2 : R \in \mathbb{R}^{n \times r}, S \in \mathbb{R}^{m \times r} \} = \sigma_{r+1}.$ with singular values $\sigma_1 \ge \sigma_2 \ge \cdots \ge \sigma_{\min\{m,n\}}$ of X.

Singular values of random matrices



No reasonable low-rank approximation possible

Singular values of ground state

- Computed ground state for Henon-Heiles potential for d = 2.
- Reshaped ground state into matrix.



Excellent rank-10 approximation possible

When to expect good low-rank approximations

Rule of thumb: Smoothness helps.

When to expect good low-rank approximations

Rule of thumb: Smoothness helps, but is not always needed.



Discretization of bivariate function

- ▶ Bivariate function: f(x, y) : $[x_{\min}, x_{\max}] \times [y_{\min}, y_{\max}] \rightarrow \mathbb{R}$.
- Function values on tensor grid $[x_1, \ldots, x_n] \times [y_1, \ldots, y_m]$:

 $F = \begin{bmatrix} f(x_1, y_1) & f(x_1, y_2) & \cdots & f(x_1, y_n) \\ f(x_2, y_1) & f(x_2, y_2) & \cdots & f(x_2, y_n) \\ \vdots & \vdots & & \vdots \\ f(x_m, y_1) & f(x_m, y_2) & \cdots & f(x_m, y_n) \end{bmatrix}$



Basic but crucial observation: $f(x, y) = g(x)h(y) \rightsquigarrow$

$$F = \begin{bmatrix} g(x_1)h(y_1) & \cdots & g(x_1)h(y_n) \\ \vdots & & \vdots \\ g(x_m)h(y_1) & \cdots & g(x_m)h(y_n) \end{bmatrix} = \begin{bmatrix} g(x_1) \\ \vdots \\ g(x_m) \end{bmatrix} \begin{bmatrix} h(y_1) & \cdots & h(y_n) \end{bmatrix}$$

Separability implies rank 1.

Separability and low rank

Approximation by sum of separable functions

$$f(x,y) = \underbrace{g_1(x)h_1(y) + \dots + g_r(x)h_r(y)}_{=:f_r(x,y)} + \text{error.}$$

Define

$$F_r = \begin{bmatrix} f_r(x_1, y_1) & \cdots & f_r(x_1, y_n) \\ \vdots & & \vdots \\ f_r(x_m, y_1) & \cdots & f_r(x_m, y_n) \end{bmatrix}.$$

Then F_r has rank $\leq r$ and $||F - F_r||_F \leq \sqrt{mn} \times \text{error.}$

$$\sigma_{r+1}(F) \leq ||F - F_r||_2 \leq ||F - F_r||_F \leq \sqrt{mn} \times \text{error}$$

Semi-separable approximation implies low-rank approximation.

Semi-separable approximation by polynomials

Solution of approximation problem

 $f(x,y) = g_1(x)h_1(y) + \cdots + g_r(x)h_r(y) + \text{error.}$

not trivial; g_j , h_j can be chosen arbitrarily!

General construction by polynomial interpolation:

1. Lagrange interpolation of f(x, y) in y-coordinate:

$$I_{y}[f](x,y) = \sum_{j=1}^{r} f(x,\theta_{j})L_{j}(y)$$

with Lagrange polynomials L_j of degree r - 1 on $[x_{\min}, x_{\max}]$.

2. Interpolation of $I_{y}[f]$ in *x*-coordinate:

$$I_{x}[I_{y}[f]](x,y) = \sum_{i,j=1}^{r} f(\xi_{i},\theta_{j})L_{i}(x)L_{j}(y) \triangleq \sum_{i=1}^{r} L_{i,x}(x)L_{j,y}(y),$$

where $f[f(\xi_i, \theta_j)]_{i,j}$ is "diagonalized" by SVD.

Semi-separable approximation by polynomials

error
$$\leq \|f - I_x[I_y[f]]\|_{\infty}$$

 $= \|f - I_x[f] + I_x[f] - I_x[I_y[f]]\|_{\infty}$
 $\leq \|f - I_x[f]\|_{\infty} + \|I_x\|_{\infty}\|f - I_y[f]\|_{\infty}$

with Lebesgue constant $||I_x||_{\infty} \sim \log r$ when using Chebyshev interpolation nodes.

[Temlyakov'1992, Uschmajew/Schneider'2013]:

$$\sup_{f\in B^s} \inf \left\| f(x,y) - \sum_{k=1}^r g_k(x) h_k(y) \right\|_{L^2} \sim r^{-s},$$

with Sobolev space B^s of periodic functions with partial derivatives up to order s.

Semi-separable approximation by polynomials

error
$$\leq \|f - I_X[I_Y[f]]\|_{\infty}$$

 $= \|f - I_X[f] + I_X[f] - I_X[I_Y[f]]\|_{\infty}$
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Low-rank tensors

Vectors, matrices, and tensors



- scalar = tensor of order 0
- (column) vector = tensor of order 1
- matrix = tensor of order 2
- ► tensor of order 3 = $n_1 n_2 n_3$ numbers arranged in $n_1 \times n_2 \times n_3$ array

Tensors of arbitrary order

A *d*-th order tensor \mathcal{X} of size $n_1 \times n_2 \times \cdots \times n_d$ is a *d*-dimensional array with entries

$$\mathcal{X}_{i_1,i_2,\ldots,i_d}, \qquad i_\mu \in \{1,\ldots,n_\mu\} ext{ for } \mu = 1,\ldots,d.$$

In the following, entries of $\mathcal X$ are real (for simplicity) \rightsquigarrow

 $\mathcal{X} \in \mathbb{R}^{n_1 \times n_2 \times \cdots \times n_d}.$

Multi-index notation:

$$\mathfrak{I} = \{1, \ldots, n_1\} \times \{1, \ldots, n_2\} \times \cdots \times \{1, \ldots, n_d\}.$$

Then $i \in \mathfrak{I}$ is a tuple of *d* indices:

$$i=(i_1,i_2,\ldots,i_d).$$

Allows to write entries of \mathcal{X} as \mathcal{X}_i for $i \in \mathfrak{I}$.

Functions and tensors

Consider a function $f(x_1, ..., x_d) \in \mathbb{R}$ in *d* variables $x_1, ..., x_d$. Tensor $\mathcal{X} \in \mathbb{R}^{n_1 \times \cdots \times n_d}$ represents discretization of *u*:

- > \mathcal{X} contains function values of *f* evaluated on a grid; or
- X contains coefficients of truncated expansion in tensorized basis functions:

$$f(\mathbf{x}_1,\ldots,\mathbf{x}_d) \approx \sum_{i\in\mathfrak{I}} \mathcal{X}_i \phi_{i_1}(\mathbf{x}_1) \phi_{i_2}(\mathbf{x}_2) \cdots \phi_{i_d}(\mathbf{x}_d).$$

Functions and tensors

One of many ways to separate variables of *f*:

$$f(x_1, x_2, \ldots, x_d) \approx \sum_{k=1}^r g_k(x_1) h_k(x_2, \ldots, x_d)$$

Corresponding matrix/tensor decomposition?

Matricization

Stack 1-fibers into an $n_1 \times (n_2 \cdots n_d)$ matrix:



Separation wrt $\{x_1\}$ corresponds to low-rank matrix approximation

 $X^{(1)} \approx U_1 V_1^T$.

Tucker decomposition

Consider low-rank decompositions corresponding to {x₁}, {x₂}, {x₃}:

$$\begin{array}{rcl} X^{(1)} &\approx & U_1 V_1^T \\ X^{(2)} &\approx & U_2 V_2^T \\ X^{(3)} &\approx & U_3 V_3^T \end{array}$$

Form $r_1 \times r_2 \times r_3$ core tensor C:

$$\mathsf{vec}(\mathcal{C}) := \left(U_3^{\mathsf{T}} \otimes U_2^{\mathsf{T}} \otimes U_1^{\mathsf{T}} \right) \cdot \mathsf{vec}(\mathcal{X}).$$

Yields Tucker decomposition:

$$\mathsf{vec}(\mathcal{X}) \approx (U_3 \otimes U_2 \otimes U_1) \cdot \mathsf{vec}(\mathcal{C}).$$

Approximation error governed by truncated singular values of $X^{(1)}, X^{(2)}, X^{(3)}$.

Tucker decomposition

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Approximation error governed by truncated singular values of $X^{(1)}, X^{(2)}, X^{(3)}$.

Need for storing $r_1 \times r_2 \times \cdots \times r_d$ core tensor hurts in high dimensions.

Functions and tensors

Another one of many ways to separate variables of *f*:

$$f(x_1, x_2, x_3, \ldots, x_d) \approx \sum_{k=1}^r g_k(x_1, x_2) h_k(x_2, \ldots, x_d)$$

Corresponding matrix/tensor decomposition?

More general matricizations

Separation wrt $\{x_1, x_2\}$ corresponds to low-rank matrix approximation

 $X^{(1,2)} \approx U_{12}V_{12}^T$

for (1,2) matricization of \mathcal{X} .

General matricization for mode decomposition $\{1, \ldots, d\} = t \cup s$:

 $\boldsymbol{X}^{(t)} \in \mathbb{R}^{(n_{t_1} \cdots n_{t_k}) \times (n_{s_1} \cdots n_{s_{d-k}})}$

with

$$(X^{(t)})_{(i_{t_1},...,i_{t_k}),(i_{s_1},...,i_{s_{d-k}})} := X_{i_1,...,i_d}$$



Tensor network diagrams

Examples:



- (i) vector;
- (ii) matrix;
- (iii) matrix-matrix multiplication;
- (iv) Tucker decomposition;
- (v) hierarchical Tucker decomposition.

Hierarchical construction

Singular value decomposition: $X^{(t)} = U_t \Sigma_t U_s^T$. Column spaces are nested \rightsquigarrow

$$\begin{aligned} t &= t_1 \cup t_2 \quad \Rightarrow \quad \text{span}(U_t) \subset \text{span}(U_{t_2} \otimes U_{t_1}) \\ &\Rightarrow \quad \exists B_t : \ U_t = (U_{t_2} \otimes U_{t_1})B_t. \end{aligned}$$

Size of *U*_t:

$$U_t \in \mathbb{R}^{n_{t_1} \cdots n_{t_k} \times r_t}$$
 with $r_t = \operatorname{rank}(X^{(t)})$

For *d* = 4:

$$\begin{array}{rcl} U_{12} &=& (U_2 \otimes U_1)B_{12} \\ U_{34} &=& (U_4 \otimes U_3)B_{34} \\ \text{vec}(\mathcal{X}) = X^{(1234)} &=& (U_{34} \otimes U_{12})B_{1234} \\ \Rightarrow & \text{vec}(\mathcal{X}) &=& (U_4 \otimes U_3 \otimes U_2 \otimes U_1)(B_{34} \otimes B_{12})B_{1234}. \end{array}$$

Dimension tree

Tree structure for d = 4:



Reshape:

 $\begin{array}{rcl} B_{12} \in \mathbb{R}^{r_1 r_2 \times r_{12}} & \Rightarrow & \mathcal{B}_{12} \in \mathbb{R}^{r_1 \times r_2 \times r_{12}} \\ B_{34} \in \mathbb{R}^{r_3 r_4 \times r_{34}} & \Rightarrow & \mathcal{B}_{34} \in \mathbb{R}^{r_3 \times r_4 \times r_{34}} \\ B_{1234} \in \mathbb{R}^{r_{12} r_{34} \times 1} & \Rightarrow & \mathcal{B}_{1234} \in \mathbb{R}^{r_{12} \times r_{34}} \end{array}$

Dimension tree



- Often, U₁, U₂, U₃, U₄ are orthonormal. This is advantageous but not required.
- Storage requirements for general *d*:

 $\mathcal{O}(dnr) + \mathcal{O}(dr^3),$

where $r = max\{r_t\}$, $n = max\{n_\mu\}$.

Singular value tree

Example: Singular value tree of solution to elliptic PDE with 4 parameters.











Computation of inner products - contraction step



$$(U_t^x)^T U_t^y = (B_t^x)^T ((U_{t_2}^x)^T U_{t_2}^y \otimes (U_{t_1}^x)^T U_{t_1}^y) B_t^y.$$

- htucker command: innerprod(x,y)
- Overall cost: $\mathcal{O}(dnr^2) + \mathcal{O}(dr^4)$.

Hierarchical Tucker decomposition

- Simulation of quantum many-body systems: tree tensor networks [Shi/Duan/Vidal'2006].
- Numerical analysis: [Hackbusch/Kühn'2009], [Grasedyck'2010].
- MATLAB toolbox from http://anchp.epfl.ch/htucker
- ▶ For fixed *r*: Storage linear in *d*!
- When to expect good low-rank approximations?

Hierarchical Tucker decomposition

- When to expect good low-rank approximations?
- Approximation error from separation wrt to $\{x_1, \ldots, x_a\}$:

$$f(x_1,\ldots,x_a,x_{a+1},\ldots,x_d)\approx\sum_{k=1}^r g_k(x_1,\ldots,x_a)h_k(x_{a+1},\ldots,x_d)$$

for a = 1, ..., d - 1.

[DK/Tobler'2011]: For analytic functions

error
$$\leq \exp(-r^{\max\{1/a,1/(d-a)\}})$$
.

► [Temlyakov'1992, Uschmajew/Schneider'2013]: For f ∈ B^{s,mix}

error
$$\leq r^{-2s} (\log r)^{2s(\max\{a,d-a\}-1)}$$

Smoothness is neither sufficient nor necessary for high dimensions

Hierarchical Tucker decomposition

- When to expect good low-rank approximations?
- Approximation error from separation wrt to $\{x_1, \ldots, x_a\}$:

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error
$$\leq r^{-2s} (\log r)^{2s(\max\{a,d-a\}-1)}$$

Smoothness is neither sufficient nor necessary for high dimensions!

Low-rank methods for 2D

Rayleigh quotients wrt low-rank matrices

Consider symmetric $n^2 \times n^2$ matrix \mathcal{A} . Then

$$\lambda_{\min}(\mathcal{A}) = \min_{x \neq 0} \frac{\langle x, \mathcal{A}x \rangle}{\langle x, x
angle}$$

We now...

- reshape vector x into $n \times n$ matrix X;
- reinterpret Ax as linear operator $A : X \mapsto A(X)$;
- for example if $\mathcal{A} = \sum_{k=1}^{s} B_k \otimes A_k$ then

$$\mathcal{A}(X) = \sum_{k=1}^{s} B_k X A_k^T.$$

Rayleigh quotients wrt low-rank matrices

Consider symmetric $n^2 \times n^2$ matrix \mathcal{A} . Then

$$\lambda_{\min}(\mathcal{A}) = \min_{X
eq 0} rac{\langle X, \mathcal{A}(X)
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with matrix inner product $\langle\cdot,\cdot\rangle.$ We now...

restrict X to low-rank matrices.

Rayleigh quotients wrt low-rank matrices

Consider symmetric $n^2 \times n^2$ matrix \mathcal{A} . Then

$$\lambda_{\min}(\mathcal{A}) \approx \min_{\substack{\boldsymbol{X} = \boldsymbol{U} \boldsymbol{V}^{T} \neq 0}} \frac{\langle \boldsymbol{X}, \mathcal{A}(\boldsymbol{X}) \rangle}{\langle \boldsymbol{X}, \boldsymbol{X} \rangle}.$$

- Approximation error governed by low-rank approximability of X.
- Solved by Riemannian optimization techniques or ALS.

ALS for solving

$$\lambda_{\min}(\mathcal{A}) \approx \min_{\substack{X = \mathcal{U}V^{\top} \neq 0}} \frac{\langle X, \mathcal{A}(X) \rangle}{\langle X, X \rangle}.$$

Initially:

- ▶ fix target rank r
- ▶ $U \in \mathbb{R}^{m \times r}$, $V^{n \times r}$ randomly, such that V is ONB

$$\begin{split} \tilde{\lambda} - \lambda &= \mathbf{6} \times \mathbf{10^3} \\ \text{residual} &= \mathbf{3} \times \mathbf{10^3} \end{split}$$



ALS for solving

$$\lambda_{\min}(\mathcal{A}) \approx \min_{X = UV^{T} \neq 0} \frac{\langle X, \mathcal{A}(X) \rangle}{\langle X, X \rangle}.$$

Fix V, optimize for U.

$$\begin{array}{lll} \langle X, \mathcal{A}(X) \rangle & = & \operatorname{vec}(UV^{\mathsf{T}})^{\mathsf{T}} \mathcal{A} \operatorname{vec}(UV^{\mathsf{T}}) \\ & = & \operatorname{vec}(U)^{\mathsf{T}} (V \otimes I)^{\mathsf{T}} \mathcal{A} (V \otimes I) \operatorname{vec}(U) \end{array}$$

 \rightsquigarrow Compute smallest eigenvalue of reduced matrix (*rn* × *rn*) matrix

 $(V \otimes I)^T \mathcal{A}(V \otimes I).$

Note: Computation of reduced matrix benefits from Kronecker structure of \mathcal{A} .

ALS for solving

$$\lambda_{\min}(\mathcal{A}) \approx \min_{\boldsymbol{X} = \boldsymbol{U} \boldsymbol{V}^{\mathsf{T}} \neq 0} \frac{\langle \boldsymbol{X}, \mathcal{A}(\boldsymbol{X}) \rangle}{\langle \boldsymbol{X}, \boldsymbol{X} \rangle}.$$

Fix V, optimize for U.

 $ilde{\lambda} - \lambda = 2 \times 10^3$ residual = 2×10^3



ALS for solving

$$\lambda_{\min}(\mathcal{A}) \approx \min_{\substack{\boldsymbol{X} = \boldsymbol{U} \boldsymbol{V}^{\top} \neq 0}} \frac{\langle \boldsymbol{X}, \mathcal{A}(\boldsymbol{X}) \rangle}{\langle \boldsymbol{X}, \boldsymbol{X} \rangle}.$$

Orthonormalize U, fix U, optimize for V.

$$\begin{array}{lll} \langle X, \mathcal{A}(X) \rangle &=& \mathsf{vec}(UV^{\mathsf{T}})^{\mathsf{T}} \mathcal{A} \, \mathsf{vec}(UV^{\mathsf{T}}) \\ &=& \mathsf{vec}(V^{\mathsf{T}})(I \otimes U)^{\mathsf{T}} \mathcal{A}(I \otimes U) \mathsf{vec}(V^{\mathsf{T}}) \end{array}$$

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 $(I \otimes U)^T \mathcal{A}(I \otimes U).$

Note: Computation of reduced matrix benefits from Kronecker structure of \mathcal{A} .

ALS for solving

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Orthonormalize U, fix U, optimize for V.

$$\begin{split} \tilde{\lambda} - \lambda &= 1.5 \times 10^{-7} \\ \text{residual} &= 7.7 \times 10^{-3} \end{split}$$



ALS for solving

$$\lambda_{\min}(\mathcal{A}) \approx \min_{\substack{\boldsymbol{X} = \boldsymbol{U} \boldsymbol{V}^{\top} \neq 0}} \frac{\langle \boldsymbol{X}, \mathcal{A}(\boldsymbol{X}) \rangle}{\langle \boldsymbol{X}, \boldsymbol{X} \rangle}.$$

Orthonormalize V, fix V, optimize for U.

$$\begin{split} \tilde{\lambda} - \lambda &= \mathbf{1} \times \mathbf{10^{-12}} \\ \text{residual} &= \mathbf{6} \times \mathbf{10^{-7}} \end{split}$$



ALS for solving

$$\lambda_{\min}(\mathcal{A}) \approx \min_{\substack{\boldsymbol{X} = \boldsymbol{U} \boldsymbol{V}^{\top} \neq 0}} \frac{\langle \boldsymbol{X}, \mathcal{A}(\boldsymbol{X}) \rangle}{\langle \boldsymbol{X}, \boldsymbol{X} \rangle}.$$

Orthonormalize U, fix U, optimize for V.

$$\begin{split} \tilde{\lambda} - \lambda &= 7.6 \times 10^{-13} \\ \text{residual} &= 7.2 \times 10^{-8} \end{split}$$



Low-rank methods for arbitrary dimensions

Originally from computational quantum physics [Schollwöck 2011] for matrix product states.

Goal:

$$\mathsf{min}\left\{\frac{\langle \mathcal{X}, \mathcal{A}(\mathcal{X})\rangle}{\langle \mathcal{X}, \mathcal{X}\rangle}: \, \mathcal{X} \in \mathcal{H}\text{-}\mathsf{Tucker}\big((\mathit{r}_t)_{t \in \mathcal{T}}\big), \, \, \mathcal{X} \neq \mathbf{0}\right\}$$

Method: Choose one node *t*, fix all other nodes, set new tensor at node *t* to minimize Rayleigh quotient $\frac{\langle \mathcal{X}, \mathcal{A}(\mathcal{X}) \rangle}{\langle \mathcal{X}, \mathcal{X} \rangle}$. This is done for all nodes (a sweep), and sweeps are continued until convergence.

Sketch:

$$X^{(t)} = U_t V_t^{\mathsf{T}} = (U_{t_r} \otimes U_{t_l}) B_t V_t^{\mathsf{T}},$$

$$\operatorname{vec}(\mathcal{X}) = (V_t \otimes U_{t_r} \otimes U_{t_l}) \operatorname{vec}(B_t) = \mathcal{U}_t \operatorname{vec}(B_t).$$

$$\Rightarrow \min\left\{\frac{y^{T}(\mathcal{U}_{t}^{T}\mathcal{A}\mathcal{U}_{t})y}{y^{T}(\mathcal{U}_{t}^{T}\mathcal{U}_{t})y}: y \in \mathbb{R}^{r_{t_{l}}r_{t_{r}}r_{t}}, y \neq 0\right\}.$$

ALS - Comments

Ordering of a sweep In principle, nodes of tensor can be traversed in any ordering. Experimentally, makes little difference. Depth-first-search ordering allows data reuse in the computation of the reduced eigenvalue problems.





Numerical Experiments - Sine potential, d = 10

ALS



Hierarchical ranks 40.

Numerical Experiments - Henon-Heiles, d = 20

ALS



Hierarchical rank 40.

Numerical Experiments - $1/||\xi||_2$ potential, d = 20

ALS



Hierarchical rank 30.

Outlook

Outlook: Low-rank tensor completion

Setting:

- Consider tensor X with very few entries known, described by linear projection P_Ω.
- Assume low (multilinear) rank model for \mathcal{X} .

Low-rank reconstruction:

$$\begin{split} & \underset{\mathcal{X}}{\min} \quad \frac{1}{2} \| \mathsf{P}_{\Omega} \mathcal{X} - \text{known entries} \|^2 \\ & \text{subject to} \quad \mathcal{X} \in \mathcal{M}_k := \{ \mathbb{R}^{n_1 \times n_2 \times \cdots \times n_d} : \text{rank}(\mathcal{X}) = \mathbf{k}) \end{split}$$

- \mathcal{M}_k is a smooth manifold.
- Becomes Riemannian with metric induced by standard inner product.
- Allows to apply general Riemannian optimization techniques [Absil, Mahony and Sepulchre'05].
- Adaption of nonlinear conjugate gradient method in [DK/Steinlechner/Vandereycken'12].

Outlook: Reconstruction of CT Scan

$199 \times 199 \times 150$ tensor from MRI/CT data base "INCISIX".

Slice of original tensor



Sampled tensor (6.7%)





Low-rank completion of rank 21





Compares very well with existing results wrt low-rank recovery and speed, e.g., Gandy/Recht/Yamada/'2011: Tensor completion and low-n-rank tensor recovery via convex optimization.

Conclusions

Conclusions and Outlook

- Scientific computing with low-rank tensors rapidly evolving field and highly technical.
- Low-rank tensors capable of solving certain high-dimensional eigenvalue problems.
- Precise scope of applications far from clear; many applications remain to be explored. More analysis needed!

Some current trends:

- Tensorization of vectors + low rank (discrete Chebfun?) by Hackbusch, Khoromskij, Oseledets, Tyrtishnikov, ...
- Computational differential geometry on low-rank tensor manifolds by Koch, Lubich, Schneider, Uschmajew, Vandereycken, ...
- Robust low rank (Candes et al.) for tensors ~> suitable way of dealing with singularities?

▶ ...

Workshop on Matrix Equations and Tensor Techniques EPF Lausanne, October 10th - 11th 2013



Alain Herzog

http://anchp.epfl.ch/MatrixEquations Organizers: P. Benner, H. Faßbender, L. Grasedyck, D. Kressner.