

## PERIODIC SOLUTIONS OF A FIRST ORDER DIFFERENTIAL EQUATION

LAVOSLAV ČAKLOVIĆ

University of Zagreb, Croatia

ABSTRACT. The first order dynamical system  $\dot{z} = F(t, z)$  is considered, where  $F$  is  $T$ -periodic in time and sub-linear at infinity. Existence of  $T$ -periodic solution is proved, using degree theory, and applications to non-convex Hamiltonian systems is given as well.

### 1. INTRODUCTION AND MAIN RESULTS

*General type equation.* We consider the following first order differential equation

$$(F) \quad \dot{z} = F(t, z)$$

where  $F \in C^1(\mathbb{R} \times \mathbb{R}^N, \mathbb{R}^N)$ ,  $N \in \mathbb{N}$ , is  $T$ -periodic in time. Our goal is to find a  $T$ -periodic solution of (F) under the following **sub-linearity** condition at infinity

$$(SL) \quad \limsup_{|z| \rightarrow +\infty} \frac{|F(t, z)|}{|z|} = 0, \text{ uniformly in } t,$$

in Sobolev space  $H_T^1 := \{z \in H^1(0, T; \mathbb{R}^N) \mid z(0) = z(T)\}$  of  $T$ -periodic functions. A standard technique is to decompose the space in orthogonal sum

$$H_T^1 = E^1 \oplus \mathbb{R}^N, \quad z = u + m,$$

where  $E^1 = \{u \in H^1 \mid \int u = 0\}$ , and  $\int z = \frac{1}{T} \int_0^T z(t) dt$  is the mean value of function  $z(t)$ . According to the above decomposition we split equation

---

2000 *Mathematics Subject Classification.* 34C25, 46N20, 47H15, 55M25, 58C30, 58F22.

*Key words and phrases.* Differential equations, periodic solution, degree, Hamiltonian system.

(F) to obtain  $E^1$ -component of (F), an infinite dimensional equation, and  $\mathbb{R}^N$ -component of (F), finite dimensional one:

$$(F_1) \quad \begin{aligned} \dot{u} &= F(t, u + m) - \mathbf{f}F(t, u + m) \\ 0 &= \mathbf{f}F(t, u + m). \end{aligned}$$

We would like to introduce a deformation parameter  $\tau$ ,  $0 \leq \tau \leq 1$  to obtain a homotopically equivalent uncoupled system which has a solution. Following this idea we introduce

$$(F_\tau) \quad \begin{aligned} \dot{u} &= \tau[F(t, \tau u + m) - \mathbf{f}F(t, \tau u + m)] \\ 0 &= \mathbf{f}F(t, \tau u + m), \end{aligned}$$

for  $\tau = 1$  ( $F_\tau$ ) reduces to ( $F_1$ ) and for  $\tau = 0$  we obtain an uncoupled system

$$(F_0) \quad \begin{aligned} \dot{u} &= 0 \\ 0 &= \mathbf{f}F(t, m). \end{aligned}$$

Solving ( $F_\tau$ ) is equivalent to finding a zero of the function

$$(m, u) \mapsto \left( \mathbf{f}F(t, m + \tau u), u - \left( \frac{d}{dt} \right)^{-1} \left( \tau[F(t, m + \tau u) - \mathbf{f}F(t, m + \tau u)] \right) \right)$$

defined on  $\mathbb{R}^N \times E^1$ . Some a priori bounds are needed and invertibility of  $\frac{d}{dt}$  should be justified.

As it was kindly pointed out by the referee, it seems that instead the homotopy defined in formula ( $F_\tau$ ) the homotopy in the proof of Theorem IV.3 in the Mawhin's book [9] can be used.

*A priori bound.* To obtain an a priori bound on the solution let us rewrite the sub-linearity condition (SL) in equivalent form:

$$(\varepsilon SL) \quad \begin{aligned} &\forall \varepsilon > 0, \exists C_\varepsilon > 0, \text{ such that} \\ &|F(t, z)| \leq \varepsilon|z| + C_\varepsilon, \quad z \in \mathbb{R}^N, \quad t \in \mathbb{R}. \end{aligned}$$

As shown in the next proposition some restrictions on  $\varepsilon$  are essential for obtaining a priori bound on solution. See also an example in the proof of Theorem 1.3.

**PROPOSITION 1.1.** *Assume that  $F$  is sub-linear at infinity,  $m \in \mathbb{R}^n$  and  $u \in E^1$  is a solution of the first equation in ( $F_\tau$ ). If  $\varepsilon$ , in inequality ( $\varepsilon SL$ ), is such that  $\varepsilon T < \sqrt{3}/2$  in then*

$$(1.1) \quad \|u\|_{L^\infty} \leq \delta|m| + \gamma$$

where

$$\delta := \frac{\varepsilon T}{\sqrt{T} - \varepsilon T} \quad \text{and} \quad \gamma := \frac{C_\varepsilon T}{\sqrt{T} - \varepsilon T}.$$

We prove the proposition in section 3 on page 291. Moreover, for any  $r > 0$  we introduce

$$R_\varepsilon(r) := \frac{r + \gamma}{1 - \delta}$$

As we shall see in Lemma 3.1, inequality (1.1) implies that  $z = m + u(t)$  is localized in the ball  $B(|m|, R_\varepsilon(r) - r)$  whenever  $|m| \geq R_\varepsilon(r)$ .

There are two additional properties, we call them 'guiding function' and 'half space localization'. Each of them assures a priori bound on the solution.

**Guiding function.**

- There exist a guiding function  $W(z)$ ,
- (1.2)  $W \in C^1(\mathbb{R}^N, \mathbb{R})$ , and positive  $r > 0$  such that
- $|z| \geq r \Rightarrow F(t, z) \cdot W'(z) > 0$  uniformly on  $t$ .

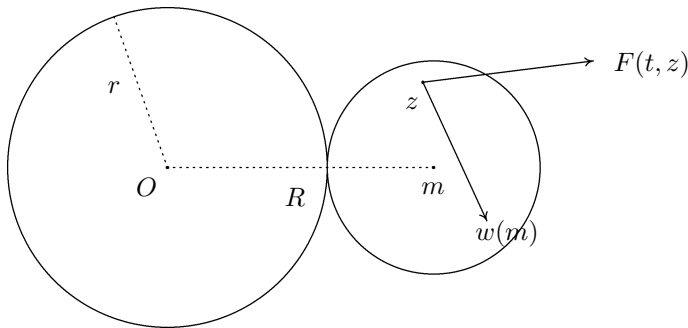
As shown in Lemma 3.2, if  $F$  has a guiding function then  $|m| \geq R_\varepsilon(r)$  implies that the second equation  $(F_\tau)$  has no solution.

**Half space localization.**

- There exists  $r > 0$  and a continuous function  $w : \mathbb{R}^N \setminus B(0, R_\varepsilon(r)) \rightarrow \mathbb{R}^N$ , such that
- (1.3)  $|m| \geq R_\varepsilon(r) \Rightarrow (w(m) \cdot m \geq 0 \text{ and } F(t, z) \cdot w(m) > 0)$
- for all  $z \in B(m, R_\varepsilon(r) - r)$  uniformly on  $t$ .

If  $z \in B(m, R_\varepsilon(r) - r)$  and  $F$  satisfies half space localization property then  $F(t, z)$  belongs to the half space  $\{z \in \mathbb{R}^N \mid w(m) \cdot z > 0\}$ . Specially, this implies that the second equation  $(F_\tau)$  has no solution.

In both cases, i.e. if  $F$  has guiding function or satisfies half space localization property, then, if there exists a solution  $z = u + m$  of  $(F_\tau)$  it should satisfy  $|m| \leq R_\varepsilon(r)$ . Evidently, some additional property of  $F$  is needed to prove the existence of solution. This is the non-triviality of degree as stated in next theorem.



A priori bound

**THEOREM 1.2** (Krasnoselski). *Assume that  $F(t, z)$  satisfies (SL) (or ( $\varepsilon$ SL)). If  $F$  has guiding function and  $d := \deg(W', B(0, r), 0) \neq 0$  then (F) has a  $T$ -periodic solution.*

A simple argument for introducing condition  $\deg(W', B(0, r), 0) \neq 0$  is the situation when  $F : \mathbb{R} \rightarrow \mathbb{R}$  is strictly positive. Then, equation  $\dot{z} = F(z)$  has no periodic solutions,  $\deg(W', B, 0) = 0$  for any interval  $B = (-r, r)$ ,  $r > 0$  and condition (1.2) is fulfilled with  $W' = F$ . Evidently, the degree  $d$  has the same value for greater  $r$  because of the non-vanishing derivative  $W'$  in (1.2).

Applications to some types of Hamiltonian systems are given in section 5. The theorem is a particular case of [6, Lema 6.5, Ch. 2] and we are not going to prove it here. Its proof is inspirative for more general statement in the next theorem.

**THEOREM 1.3.** *Assume that  $F(t, z)$  satisfies (SL) (or ( $\varepsilon$ SL)). If  $F$  satisfies half space localization property and  $\deg(w, 0, R) \neq 0$  then (F) has a  $T$ -periodic solution.*

An application to radial-like Hamiltonian is given in Theorem 1.4, with  $w(m) = Jm$ .

*Radial-like Hamiltonians.* We consider the first order Hamiltonian system

$$(H) \quad \dot{z} = JH'(t, z)$$

where  $H(t, z) : \mathbb{R} \times \mathbb{R}^N \rightarrow \mathbb{R}$  is  $C^1$  function and  $T$ -periodic in time (prime denotes partial derivative with respect to  $z$ ).

We say that Hamiltonian  $H$  is **strongly sub-quadratic** at infinity if there exists  $r > 0$  and  $1 < p < 2$  such that

$$(SS) \quad |H'(t, z)| \leq \Theta_2 |z|^{p-1} \text{ whenever } |z| \geq r.$$

We say that Hamiltonian  $H$  is **radial-like** if there exists  $\mu > 0$  such that

$$(Rad) \quad \frac{H'(t, z) \cdot z}{|H'(t, z)||z|} \geq \mu > 0 \text{ for } |z| \geq r > 0 \text{ uniformly in } t.$$

The following theorem is a consequence of Theorem 1.3.

**THEOREM 1.4.** *Suppose that the Hamiltonian  $H$  is radial-like an strongly sub-quadratic at infinity. Then:*

- i)  $F = JH'$  is sub-linear at infinity and satisfies (1.3) with  $w(m) = Jm$ .
- ii) Hamiltonian system (H) has a  $T$ -periodic solution.

The same conclusion as in Theorem 1.4 can be proved using variational methods under additional hypothesis on Hamiltonian

$$|H'(t, z)| \cdot |z| \geq \beta \geq 0, \quad |z| \geq r \geq 0 \text{ uniformly in } t.$$

The proof can be found in [5].

A simple test for radial-like Hamiltonian is given in the following theorem.

**THEOREM 1.5.** *Assume that Hamiltonian  $H$  is strongly sub-quadratic at infinity and satisfies*

$$(1.4) \quad \Theta_1 |z|^p \leq H'(t, z)z$$

where  $0 < \Theta_1 \leq \Theta_2$  and  $1 < p < 2$ . Then  $H(t, z)$  is radial-like Hamiltonian.

**OPEN PROBLEM.** Is it possible to prove Theorem 1.4 under weaker condition

$$H'(t, z) \cdot z > 0, \quad |z| \geq r \geq 0 \text{ (uniformly in } t)$$

instead of (Rad)?

*Almost convex Hamiltonians.* We also consider Hamiltonians that are **weakly sub-quadratic** in the sense

$$(WS) \quad \limsup_{|z| \rightarrow +\infty} \frac{|H(t, z)|}{|z|^2} = 0, \quad \text{uniformly on } t.$$

It seems that weak subquadraticity is not sufficient for existence of  $T$ -periodic solutions for (H) even for radial-like Hamiltonians. We need an additional assumption

$$(AC) \quad H(t, z) = \hat{H}(t, z) - \frac{k}{2}|z|^2$$

where  $\hat{H}$  is strictly convex for some positive number  $k$ . Hamiltonian which satisfies (AC) we call **almost convex**. In other words,  $H$  is almost convex if adding a quadratic term makes it strictly convex.

The following theorem is then easy to prove.

**THEOREM 1.6.** *Assume that the Hamiltonian  $H(t, z)$  is radial-like, weakly sub-quadratic, and almost convex for  $0 < k < \frac{2}{T\sqrt{3}}$ . Then, the Hamiltonian system (H) has a  $T$ -periodic solution.*

Evidently, without proof, we have the following corollary.

**COROLLARY 1.7.** *Assume that Hamiltonian  $H$  is radial-like, weakly sub-quadratic and convex. Then (H) has a  $T$ -periodic solution.*

## 2. SOME TECHNICAL RESULTS

The framework for our problem is the space  $H_T^1 := H^1(S_T, \mathbb{R}^N)$  of  $T$ -periodic functions from  $\mathbb{R}$  to  $\mathbb{R}^N$ , here  $S_T$  denotes the sphere  $\mathbb{R}/[0, T]$ , with a standard Hilbert space structure and norm

$$\|z\|_{H^1} = \left( \int_0^T |z(t)|^2 dt + \int_0^T |\dot{z}(t)|^2 dt \right)^{1/2}.$$

From now on we shall use shorthand notation  $\int_0^T f$  for the integral  $\int_0^T f(t)dt$ .

LEMMA 2.1. For all  $u \in E^1$  we have

$$(2.1) \quad \|u\|_{L^\infty} \leq \sqrt{\frac{T}{12}} \|\dot{u}\|_{L^2}.$$

Moreover, the constant  $\sqrt{T/12}$  is the best Sobolev constant in (2.1).

PROOF. Let  $u = \sum_{\substack{k \in \mathbb{Z} \\ k \neq 0}} u_k e^{i k \frac{2\pi}{T} t}$  be Fourier expansion for  $u$ , where  $u_k \in \mathbb{R}^N$ . Then

$$\begin{aligned} \dot{u}(t) &= \sum_{\substack{k \in \mathbb{Z} \\ k \neq 0}} i k \frac{2\pi}{T} u_k e^{i k \frac{2\pi}{T} t} \\ \|\dot{u}\|_{L^2} &= \frac{2\pi}{T} \left( \sum_{\substack{k \in \mathbb{Z} \\ k \neq 0}} T k^2 |u_k|^2 \right)^{1/2}. \end{aligned}$$

On the other hand

$$\begin{aligned} |u(t)| &\leq \sum_{\substack{k \in \mathbb{Z} \\ k \neq 0}} |u_k| k \frac{1}{k} \leq \left( \sum_{\substack{k \in \mathbb{Z} \\ k \neq 0}} |u_k|^2 k^2 \right)^{1/2} \left( \sum_{\substack{k \in \mathbb{Z} \\ k \neq 0}} \frac{1}{k^2} \right)^{1/2} \\ &= \frac{\pi}{\sqrt{3}} \frac{\sqrt{T}}{2\pi} \|\dot{u}\|_{L^2} = \sqrt{\frac{T}{12}} \|\dot{u}\|_{L^2}. \end{aligned}$$

This proves inequality. To see that  $\sqrt{T/12}$  is the best Sobolev constant in inequality (2.1) we take

$$u = \sum_{k \neq 0} \frac{1}{k^2} e^{i k \frac{2\pi}{T} t},$$

with  $\|u\|_{L^\infty} = u(0) = \sum_{k \neq 0} \frac{1}{k^2} = \frac{\pi^2}{3}$ . On the other side,

$$\|\dot{u}\|_{L^2} = \frac{2\pi}{T} \left( \sum_{k \neq 0} T \frac{1}{k^2} \right)^{1/2} = \frac{2\pi}{\sqrt{T}} \frac{\pi}{\sqrt{3}},$$

which proves the claim.  $\square$

The following lemma speaks about invertibility of  $\frac{d}{dt}$ .

LEMMA 2.2.

- i)  $L := \frac{d}{dt}$  is a bounded linear operator from  $H^1$  to  $L^2 := L^2(S_T; \mathbb{R}^N)$
- ii)  $L$  is bijective from  $E^1$  onto  $E = \{u \in L^2 \mid \int u = 0\}$  and  $L^{-1} : E \rightarrow E^1$  is an isomorphism of Banach spaces.

iii)  $L^{-1} : E \rightarrow E$  and  $L^{-1} : E \rightarrow L^\infty := L^\infty(0, T; \mathbb{R}^N)$  are compact operators, and

$$\|L^{-1}\|_{\mathcal{L}(E, L^\infty)} \leq \sqrt{\frac{T}{12}}.$$

PROOF. i) follows from the definition of the norm on  $H^1$ . ii) Injectivity is clear:  $N(L) = \{u \in E^1 | \dot{u} = 0\} = \{0\}$ . To prove surjectivity let us take  $v \in E$ , i.e.  $f v = 0$ . Then  $z(t) = \int_0^t v(\tau) d\tau$  belongs to  $H^1$ ,  $\dot{z} = v$  and  $z(t)$  is  $T$ -periodic. Put  $z_0 = z - fz$ . Then  $z_0 \in E^1$  and  $\dot{z}_0 = v$ .

That  $L^{-1} : E \rightarrow E^1$  is an isomorphism follows from open mapping theorem.

iii) is a consequence of the well-known theorem of Rellich and Kondrachov (see H. Brezis [3]). The inequality follows from Lemma 2.1.  $\square$

### 3. A PRIORI BOUNDS

PROOF OF PROPOSITION 1.1. Because  $0 \leq \tau \leq 1$  it is sufficient to prove the proposition for  $\tau = 1$ . Using inequality  $\|u + m\|_{L^\infty} \leq \|u\|_{L^\infty} + |m|$  and inequality  $(\varepsilon SL)$ , one gets from  $(F_\tau)$ , that

$$\|\dot{u}\|_{L^2} \leq 2\varepsilon T^{1/2}(\|u\|_{L^\infty} + |m|) + 2C_\varepsilon T^{1/2}.$$

Using Lemma 2.1 we obtain

$$2\sqrt{3}T^{-1/2}\|u\|_{L^\infty} \leq 2\varepsilon T^{1/2}(\|u\|_{L^\infty} + |m|) + 2C_\varepsilon T^{1/2}$$

and finally

$$\|u\|_{L^\infty} \leq \frac{\varepsilon T}{\sqrt{3} - \varepsilon T}|m| + \frac{C_\varepsilon T}{\sqrt{3} - \varepsilon T} =: \delta|m| + \gamma.$$

which proves the inequality.  $\square$

LEMMA 3.1. Assume that  $F$  is sub-linear at infinity. For a given  $m \in \mathbb{R}^N$  let  $u(t)$  is a solution of the first equation in  $(F_\tau)$  and  $r > 0$ . Then, for  $|m| \geq R_\varepsilon(r)$  the following inequalities take place:

$$|u(t)| \leq |m| - r \quad \text{and} \quad |u(t) + m| \geq r.$$

PROOF. i) Let us prove first that  $|m| = R_\varepsilon$ . Then, because of Proposition 1.1,

$$\begin{aligned} |u(t)| &\leq \delta \frac{r + \gamma}{1 - \delta} + \gamma = \frac{\delta r + \gamma}{1 - \delta} = \frac{r + \gamma}{1 - \delta} - r \\ &= R_\varepsilon(r) - r = |m| - r \end{aligned}$$

ii) If  $|m| = R > R_\varepsilon$ , let us denote  $r(R) = R(1 - \delta) - \gamma$ . Obviously  $r(R) > r$  and, as above,

$$|u(t)| \leq R - r(R) \leq |m| - r.$$

To prove the second inequality in lemma let us calculate

$$\begin{aligned} |u(t) + m| &\geq |m| - |u(t)| \geq |m| - \delta|m| - \gamma \\ &= (1 - \delta)|m| - \gamma \geq r. \end{aligned}$$

□

The following lemma is already proved in the book of Krasnoselski [6]. Because of its importance and simplicity we are giving a sketch of the proof.

LEMMA 3.2 (Krasnoselski). *Assume that function  $F$  is sub-linear at infinity and has a guiding function for  $|z| \geq r$ . Then, equation  $(F_\tau)$  has no solution with mean  $m$  such that  $|m| \geq R_\varepsilon(r)$ .*

SKETCH OF THE PROOF. Let  $u \in E^1$  is a solution of the first equation  $(F_\tau)$ . Then,

$$0 \neq \int F(t, \tau u(t) + m).$$

Otherwise,

$$\dot{u} = \tau F(t, \tau u + m)$$

and for  $z(t) = \tau u(t) + m$  we have

$$\dot{z} = \dot{u} = F(t, z).$$

Using Lemma 3.1 and (1.2) and we finally have

$$\frac{d}{dt} W(z(t)) = \tau^2 F(t, z(t)) \cdot W'(z(t)) > 0$$

which is impossible since  $z$  is  $T$ -periodic. □

#### 4. PROOF OF THEOREM 1.3

Let us consider a model Hamiltonian of the form

$$H(z) = \frac{1}{p}|z|^p, \quad 1 < p < 2, \quad z \in \mathbb{R}^2.$$

Using the fact that the corresponding energy is constant we can solve it explicitly using a substitution  $z = r e^{i\phi(t)}$ . But Theorem 1.2 cannot be applied. If we look carefully why this method fails, we see that the choice of function  $W(z)$  is the cause of difficulties. The equation is

$$\dot{z} = |z|^{p-2} Jz.$$

If we take  $w(z) = Jz$  and multiply both sides of the equation, we get

$$\dot{z} \cdot Jz = |z|^{p-2} Jz \cdot Jz = |z|^p.$$

The right-hand side is positive, but the left-hand side cannot be written in the form  $\frac{d}{dt} U(z)$  and we cannot prove an à priori bound on the solution. To overcome this difficulty we introduced half space localization property (1.3).



PROOF OF THEOREM 1.3. Let us denote by  $\varphi_\tau(u, m)$  a function from  $E \times \mathbb{R}^N$  to  $E$  defined by

$$\varphi_\tau(u, m) = L^{-1} \left\{ \tau \left[ F(t, \tau u + m) - \int F(t, \tau u + m) \right] \right\}.$$

The function  $\varphi_\tau$  is continuous in  $(\tau, u, m)$  and compact. Solving  $(F_\tau)$  is equivalent to finding a zero of the function  $\chi_\tau : E \times \mathbb{R}^N \rightarrow E \times \mathbb{R}^N$  defined by

$$\chi_\tau(u, m) = (u - \varphi_\tau(u, m), \int F(t, \tau u(t) + m) dt).$$

Because of inequality

$$\|u\|_{L^2} \leq T^{1/2} \|u\|_{L^\infty} \leq T^{1/2} (\delta |m| + \gamma)$$

it is more convenient to study solvability of equation  $\chi_\tau(u, m) = 0$  in the subset  $\Omega = B_1 \times B_2$  in  $E \times \mathbb{R}^n$  where  $B_1 = B\left(0, \frac{\delta R + \gamma}{1 - \delta} T^{1/2}\right) \subset E$  and  $B_2 = B(0, R) \subset \mathbb{R}^N$ , with  $R = \frac{r + \gamma}{1 - \delta}$ . To prove the existence of solution, it suffices to show that the degree

$$d_\tau := \deg(\chi_\tau, B_1 \times B_2, (0, 0)), \quad \tau \in [0, 1]$$

is different from zero. Because of the half space localization property (1.3) and Lemma 3.1 the degree is well defined, because  $\int F(t, \tau u + m) \neq 0$  for  $|m| = R$ , and does not depend on  $\tau$ . We calculate it for  $\tau = 0$ :

$$\begin{aligned} d_0 &= \deg(u \times \int F(t, m), B_1 \times B_2, (0, 0)) \\ &= \deg(id_E, B_1, 0) \cdot \deg(\int F(t, m), B_2, 0) \\ &= \deg(\int F(t, m), B_2, 0) \end{aligned}$$

where we have used  $\deg(id_E, B_1, 0) = 1$ . Let us define  $\bar{F}(m) = \int F(t, m)$ . Then  $|m| = R$  implies that

$$\bar{F}(m) \cdot w(m) = \int F(t, m) \cdot w(m) dt > 0.$$

We conclude that  $\bar{F}/\partial B_2$  and  $w/\partial B_2$  are homotopic and

$$\deg(w, B_2, 0) = 1 \neq 0.$$

This proves the theorem. □

### 5. SOME CONSEQUENCES OF THEOREMS 1.2 AND 1.3

Here are some examples of the first order Hamiltonian systems for which Theorem 1.2 is applicable.

COROLLARY 5.1. *Suppose  $F(t, z) = JH'(t, z)$  sub-linear at infinity and*

$$H'_x x - H'_y y > 0 \quad (\text{or } < 0).$$

*Then, the equation (F) has a T-periodic solution.*

Here  $W(z) = \frac{1}{2}(x^2 - y^2) = \frac{1}{2}\operatorname{Re}|z|^2$ ,  $w(z) = (x, -y)$  and  $\deg(w, B_R, 0) \neq 0$  for  $R > 0$ . In fact,  $\deg(w, B_R, 0) = -1$  which is a consequence of excision and multiplicative properties of the degree.

COROLLARY 5.2. *A special case of the previous corollary is the following one:*

$$H(t, z) = f(t) \left( \frac{1}{p}|x|^p - \frac{1}{p}|y|^p \right), \quad 1 < p < 2$$

where  $f(t) > 0$  and is  $T$ -periodic. Then

$$H'_x x - H'_y y = \left( |x|^p + |y|^p \right) f(t) > 0$$

and Corollary 5.1 can be applied.

COROLLARY 5.3. *Let  $H(t, z) = \frac{1}{p}f(t)|z|^p + g(t)|z|$  where  $1 < p < 2$  and  $f, g$  are real  $T$ -periodic continuous functions and  $0 < \alpha \leq \min f(t)$ . Then the Hamiltonian system  $\dot{z} = JH'(t, z)$  has a  $T$ -periodic solution.*

PROOF. Indeed,  $F(t, z) := JH'(t, z)$  is sub-linear at infinity. It is sufficient to prove that  $F$  satisfies the half space localization property. Let us define  $w(m) := Jm$  and choose  $r > 0$  such that

$$\alpha r^{p-1} > \rho := \max_{t \in [0, T]} |g(t)|.$$

Then,

$$w \cdot m = Jm \cdot m = 0$$

and if  $|m| = R_\varepsilon(r) =: R$  and  $z \in B(m, R - r)$  then  $|z| > r$  by Lemma 3.1 and

$$\begin{aligned} F(t, z) \cdot Jm &= JH'(t, z) \cdot Jm = H'(t, z) \cdot m \\ &= f(t)|z|^{p-2}z \cdot m + g(t)\frac{z}{|z|} \cdot m \\ &\geq \alpha r^{p-1}R - \rho R \geq (\alpha r^{p-1} - \rho)R > 0 \end{aligned}$$

which implies (1.3).  $\square$

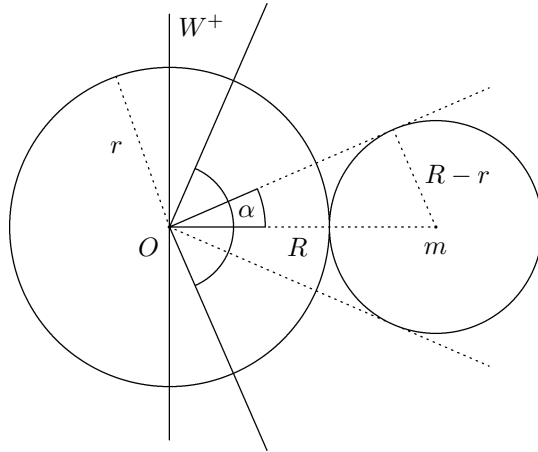
COROLLARY 5.4. *Same conclusion as in Corollary 5.3 with hypothesis  $H(t, z) = \frac{1}{p}f(t)|z|^p + g(t)z$  where  $g : [0, T] \rightarrow \mathbb{R}^N$ .*

## 6. RADIAL-LIKE HAMILTONIANS

*Proof of Theorem 1.4.* It is sufficient to prove that for  $|m|$  large enough, there exists  $\varepsilon > 0$  in  $(\varepsilon\text{SL})$ , such that

$$(6.1) \quad \sin \alpha := \frac{R_\varepsilon(r) - r}{R_\varepsilon(r)} < \mu.$$

In this case  $H'(t, z)$  is an element of the positive dual cone generated by the ball  $B(m, R_\varepsilon(r) - r)$ , hence an element of the half space  $\{x \in \mathbb{R}^{2N} \mid x \cdot m > 0\}$



and obviously  $\int JH'(t, z) \cdot Jm = \int H'(t, z) \cdot m \neq 0$  which proves half space localization property. To prove (6.1) we have

$$\frac{R_\varepsilon(r) - r}{R_\varepsilon(r)} = \frac{\frac{r+\gamma}{1-\delta} - r}{\frac{r+\gamma}{1-\delta}} = \frac{r\delta + \gamma}{r + \gamma}.$$

Then (6.1) is equivalent to

$$r(\mu - \delta) > \gamma(1 - \mu).$$

Now,  $\varepsilon$  can be chosen such that  $\mu - \delta > 0$  and  $r$  can be taken such that

$$r > \frac{\gamma(1 - \mu)}{\mu - \delta}$$

which proves the theorem. □

*Proof of Theorem 1.5.* Let  $F(t, z) = JH'(t, z)$ . Evidently  $F$  is sub-linear at infinity. To prove that  $H$  is radial-like Hamiltonian let us consider  $z$  such that  $|z| \geq r$ . Then

$$\frac{H'(t, z) \cdot z}{|H'(t, z)||z|} \geq \frac{\Theta_1|z|^p}{\Theta_2|z|^p} = \frac{\Theta_1}{\Theta_2} =: \mu > 0$$

which proves the theorem. □

### 7. ALMOST CONVEX HAMILTONIANS

*Proof of Theorem 1.6.* The idea is to prove inequality (1.1) and to get a priori bound on the solution from this inequality. We shall write (H) in the form

$$L_k z := \dot{z} + kJz = J\hat{H}'(t, z)$$

or, to simplify the notation

$$(7.1) \quad L_k z = \hat{F}(t, z)$$

with  $\hat{F}(t, z) = J\hat{H}'(t, z)$ .

Let us perform decomposition of the equation (7.1) like in  $(F_1)$ , i.e.

$$(7.2) \quad \begin{aligned} L_k u &= \hat{F}(t, u+m) - \mathfrak{f}\hat{F}(t, u+m) \\ 0 &= \mathfrak{f}F(t, u+m). \end{aligned}$$

The proof will be divided into several steps:

$$1^{\text{st}} \text{ step: } \limsup_{|z| \rightarrow +\infty} \frac{|\hat{F}(t, z)|}{|z|} \leq 2k, \text{ uniformly on } t.$$

2<sup>nd</sup> step: For any  $u \in E$  such that  $\mathfrak{f}u = 0$  we have

$$\|u\|_{L^\infty} \leq \frac{\sqrt{T}}{2\sqrt{3} - kT} \|L_k u\|_{L^2}.$$

3<sup>rd</sup> step: If  $u \in E, \mathfrak{f}u = 0$ , is a solution of the first equation (7.2) for given  $m \in \mathbb{R}^{2N}$ , then

$$\|u\|_{L^\infty} \leq \delta|m| + \gamma, \quad 0 < \delta < 1$$

where  $\delta = \frac{2(2k + \varepsilon)T}{\sqrt{3} - 5kT - \varepsilon T}, \gamma = \frac{2C_\varepsilon T}{\sqrt{3} - 5kT - \varepsilon T}$ .

4<sup>th</sup> step: (Conclusion) Using (Rad) and the 3<sup>rd</sup> step we obtain a priori bound on the solution, because (1.3) is satisfied with  $w(m) = Jm$ .

Proof of the 1<sup>st</sup> step. Let us denote by  $\hat{G}$  the Legendre transform of  $\hat{H}$ , i.e.

$$\hat{G}(t, v) = -\hat{H}(t, z) + vz$$

where  $v = \hat{H}'(t, z)$  and  $z = \hat{G}'(t, v)$ . Because of (WS) and the properties of the Legendre transform for each  $\varepsilon, 0 < \varepsilon < k$ , there exists  $C_\varepsilon \in \mathbb{R}$  such that

$$\begin{aligned} \frac{k - \varepsilon}{2}|z|^2 - C_\varepsilon &\leq \hat{H}(t, z) \leq \frac{k + \varepsilon}{2}|z|^2 + C_\varepsilon \\ \frac{1}{2(k + \varepsilon)}|v|^2 - C_\varepsilon &\leq \hat{G}(t, v) \leq \frac{1}{2(k - \varepsilon)}|v|^2 + C_\varepsilon. \end{aligned}$$

Functions  $\hat{H}$  and  $\hat{G}$  are bounded from below by a constant  $-C_\varepsilon$  and consequently

$$(7.3) \quad \frac{1}{2(k + \varepsilon)}|v|^2 - C_\varepsilon \leq \hat{G}(t, v) \leq vz - \hat{H}(t, z) \leq vz + C_\varepsilon,$$

$$(7.4) \quad \frac{k - \varepsilon}{2}|z|^2 - C_\varepsilon \leq \hat{H}(t, z) \leq vz - \hat{G}(t, v) \leq vz + C_\varepsilon.$$

Dividing (7.3) by  $|v||z|$  we have

$$\frac{1}{2(k + \varepsilon)} \frac{|v|}{|z|} \leq 1 + \frac{2C_\varepsilon}{|v||z|}, \quad \forall \varepsilon > 0$$

which proves the 1<sup>st</sup> step.

Proof of the 2<sup>nd</sup> step.

$$\begin{aligned} \|L_k u\|_{L^2} &= \|\dot{u} + kJu\|_{L^2} \geq \|\dot{u}\|_{L^2} - k\|u\|_{L^2} \\ &\geq \frac{2\sqrt{3}}{\sqrt{T}}\|u\|_{L^\infty} - k\sqrt{T}\|u\|_{L^\infty} \\ &= \frac{2\sqrt{3} - kT}{\sqrt{T}}\|u\|_{L^\infty} \end{aligned}$$

where we have used inequality (2.1) from Lemma 2.1 and inequality  $\|u\|_{L^2} \leq \sqrt{T}\|u\|_{L^\infty}$ .

Proof of the 3<sup>rd</sup> step. Using the 1<sup>st</sup> and 2<sup>nd</sup> step in the first equation of (7.2) we obtain

$$\begin{aligned} \frac{2\sqrt{3} - kT}{\sqrt{T}}\|u\|_{L^\infty} &\leq \|L_k u\|_{L^2} \\ &\leq 2(2k + \varepsilon)T^{1/2}(\|u\|_{L^\infty} + |m|) + 2C_\varepsilon T^{1/2} \end{aligned}$$

which proves the claim.  $\square$

**COROLLARY 7.1.** *Suppose that  $H(t, z) = h(z) + g(t)z$ , where  $h(z)$  is a convex, radial-like and weakly sub-quadratic. If  $g : \mathbb{R} \rightarrow \mathbb{R}^N$  is  $T$ -periodic and non-constant. Then, Hamiltonian system  $H$  has a non-constant  $T$ -periodic solution.*

## 8. APPENDIX

The following inequalities are useful in the theory of convex Hamiltonian systems. Let  $G(z) = \gamma|z|^q + \alpha$  where  $\gamma > 0$ ,  $q > 1$  and  $\alpha \in \mathbb{R}$ . Then if  $\frac{1}{p} + \frac{1}{q} = 1$ ,

$$G^*(v) = \left(\frac{1}{\gamma q}\right)^{p/q} \frac{|v|^p}{p} - \alpha.$$

If  $H$  is a Legendre function, then:

$$(8.1) \quad H(z) \leq \gamma|z|^q + \alpha \iff H^*(v) \geq \left(\frac{1}{\gamma q}\right)^{p/q} \frac{|v|^p}{p} - \alpha,$$

$$(8.2) \quad H(z) \geq \gamma|z|^q + \alpha \iff H^*(v) \leq \left(\frac{1}{\gamma q}\right)^{p/q} \frac{|v|^p}{p} - \alpha.$$

**PROPOSITION 8.1.** *Let  $H$  be a Legendre function such that for some  $\gamma > 0$ ,  $q > 1$ ,  $\alpha, \eta \in \mathbb{R}$ ,*

$$(8.3) \quad \eta \leq H(z) \leq \gamma|z|^q + \alpha.$$

If  $\frac{1}{p} + \frac{1}{q} = 1$  then

$$\left(\frac{1}{\gamma q}\right)^{p/q} \frac{|H'(z)|^p}{p} \leq H'(z)z + \alpha - \eta$$

PROOF. Let  $v = H'(z)$ . From (8.1) and (8.3) we obtain

$$\left(\frac{1}{\gamma q}\right)^{p/q} \frac{|v|^p}{p} - \alpha \leq H^*(v) = vz - H(z) \leq vz - \eta.$$

□

## REFERENCES

- [1] A. Bahri, H. Berestycki, *Existence of forced oscillations for some nonlinear differential equations*, Comm. Pure Appl. Math. **37** (1983), 403–442.
- [2] H. Berestycki, *Solutions périodiques de systèmes hamiltoniens*, Séminaire Bourbaki, Soc. Math. France, Paris, 1983, 105–128.
- [3] H. Brezis, *Analyse fonctionnelle, théorie et applications*, Masson, Paris, 1983.
- [4] F. Clarke, I. Ekeland, *Hamiltonian trajectories having prescribed minimal period*, Comm. Pure, Appl. Math. **33** (1980), 103–116.
- [5] L. Čaklović, *Periodic solutions of a first order nonconvex Hamiltonian system*, Glas. Mat. **37** (2002), 101–118.
- [6] M. A. Krasnosel'ski, *The operator of translation along trajectories of ordinary differential equations*, Mir, Moskow, 1966.
- [7] M. A. Krasnosel'ski, *Topological methods in the theory of nonlinear integral equations*, Macmillan, New York, 1964.
- [8] I. Ekeland, J. M. Lasry, *On the number of Periodic trajectories for a Hamiltonian flow on a convex energy surface*, Ann. Math. **112**(1980), 283–319
- [9] J. Mawhin, *Topological degree methods in nonlinear boundary value problems*, CBMS **40**, Amer. Math. Soc., Providence, R.I., 1979.
- [10] L. Nirenberg, *Topics in nonlinear functional analysis*, Lecture notes, Courant Institute of Math. Sc., New York Univ., 1974.
- [11] P. H. Rabinowitz, *Subharmonic solutions of Hamiltonian systems*, Comm. Pure Appl. Math. **33** (1980), 609–633.
- [12] P. H. Rabinowitz, *Méthodes topologiques et problèmes aux limites non linéaires*, Lecture notes Univ. Paris VI, (1975), Redigées par H. Berestycki.
- [13] M. Willem, *Subharmonic oscillations of convex Hamiltonian systems*, Nonlinear Anal. **9** (1985), 1303–1311.

L. Čaklović  
 Department of Mathematics  
 University of Zagreb  
 P.O.Box 335, 10002 Zagreb  
 Croatia  
 E-mail: caklovic@math.hr

Received: 20.06.2000.

Revised: 29.01.2003.